



Symbolic Timing Analysis for Systems

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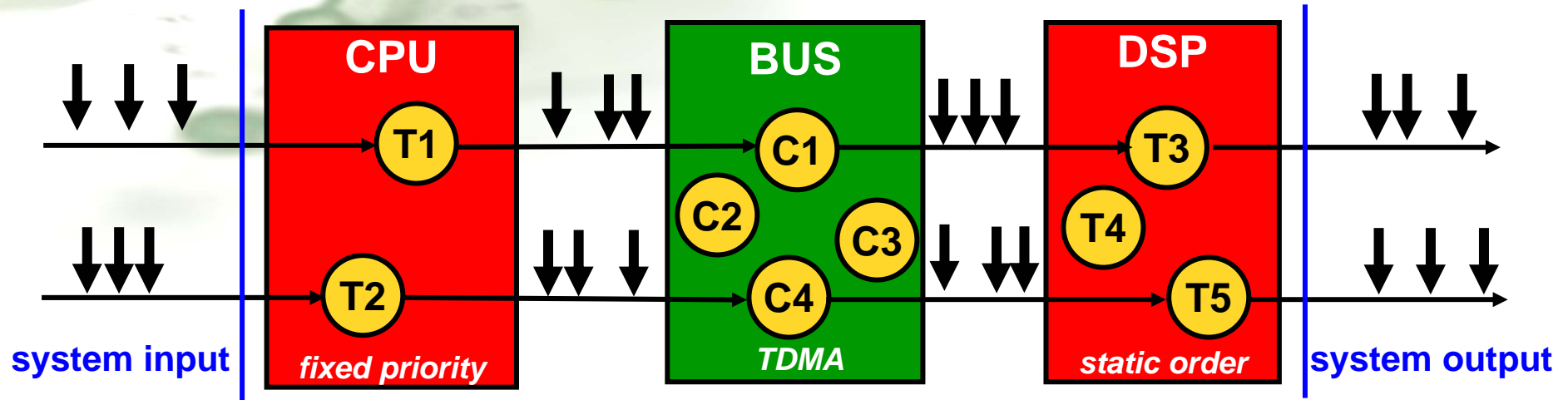
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SymTA/S Approach

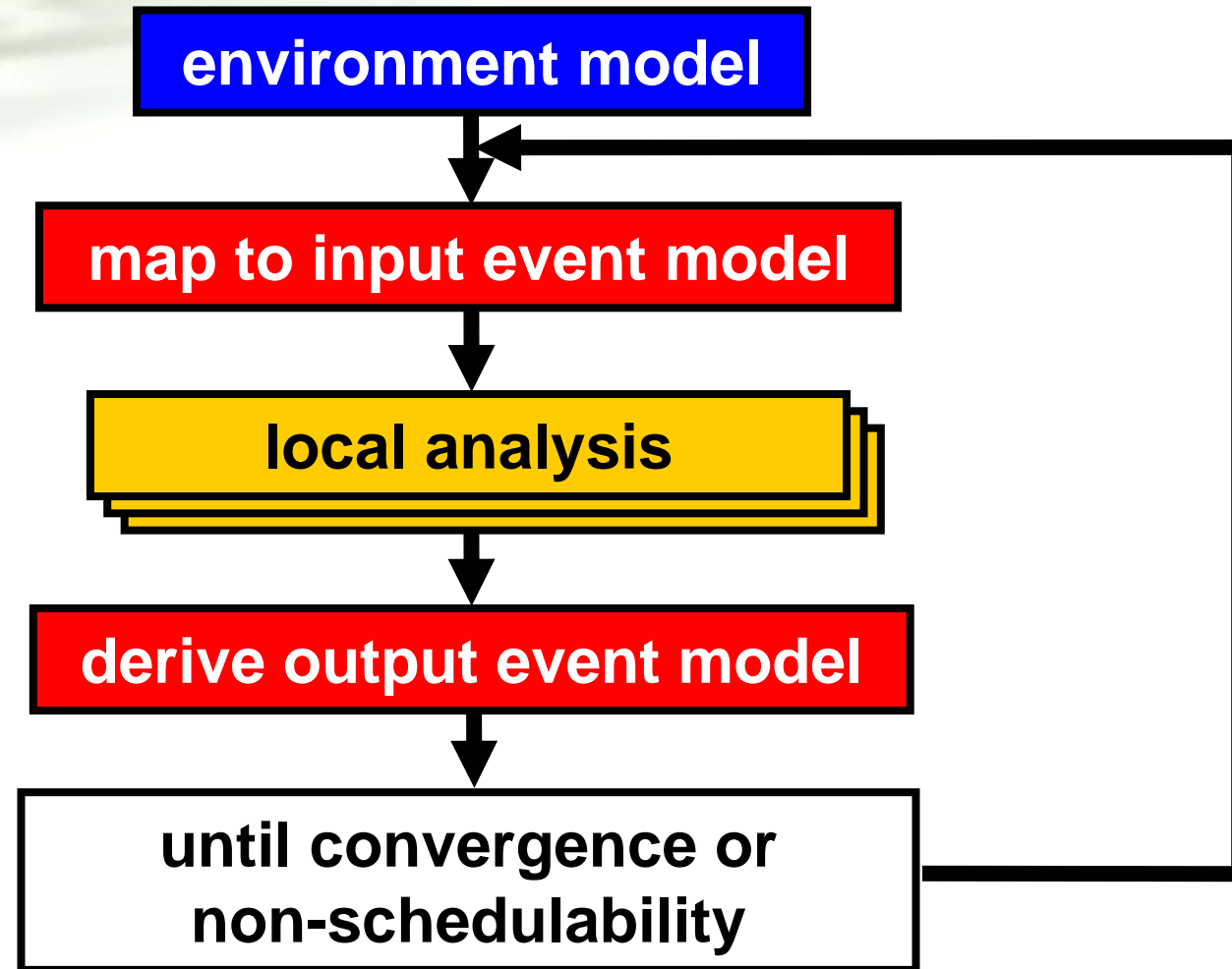
- **Compositional analysis**
- **Relies on local timing analysis methods for components**
- **Component I/O timing described by event models**
- **System-level composition by event stream propagation and event model interfacing between components**
- **Iterative solution of event stream propagation**
- **Considers buffering influences on system timing**
- **Scalable and flexible, including heterogeneous systems**

Compositional Approach



- Tasks are coupled by data flows (task inter-communication)
- Interpreted as activating events (event models)
- Composition by means of event stream propagation
 - Apply local scheduling techniques at resource level
 - Determine the behavior of the output stream
 - Propagate to the next component

System Analysis Loop

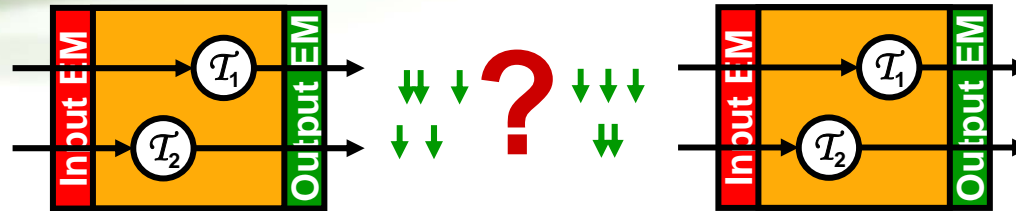


Standard Event Models

- **Six-class event models using the same set of parameters**
 - **strictly periodic** T
 - **periodic with jitter** $T, J < T$
 - **periodic with bursts** $T, J \geq T, d$
 - **sporadic** t
 - **sporadic with jitter** $t, J < t$
 - **sporadic with bursts** $t, J \geq t, d$
- **Automatic Model Transformations**
 - **Event Model Interfaces**
 - **Event Adaptation Functions, incl. Shaping/Buffering**

Event Model Transformations

- components may require different event models



needs interfaces

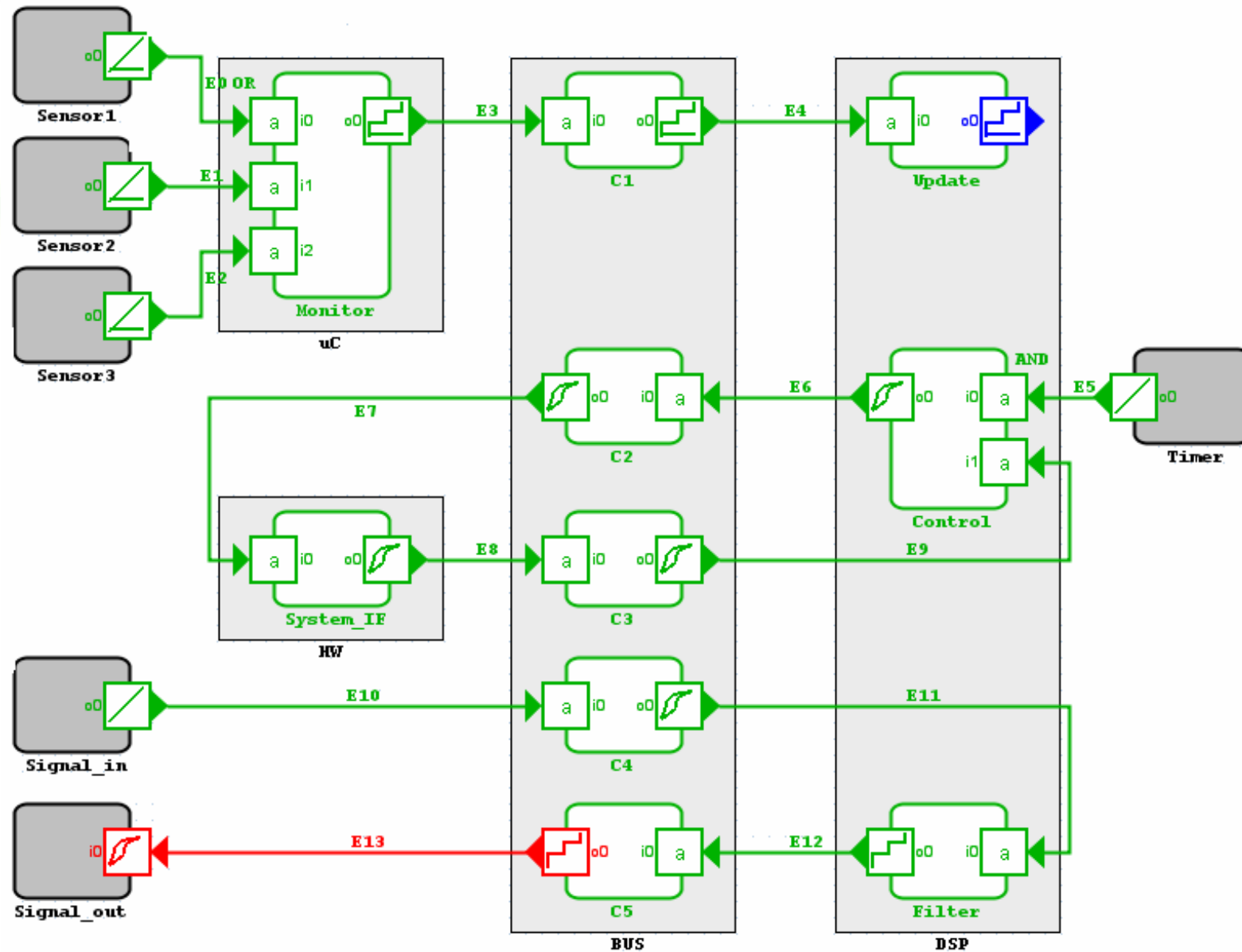
Important because

- Output timing usually more irregular than input timing
- Input models more constrained
 - Re-use of local analysis techniques (RMS)
 - Implementation dependent (e.g. black box)

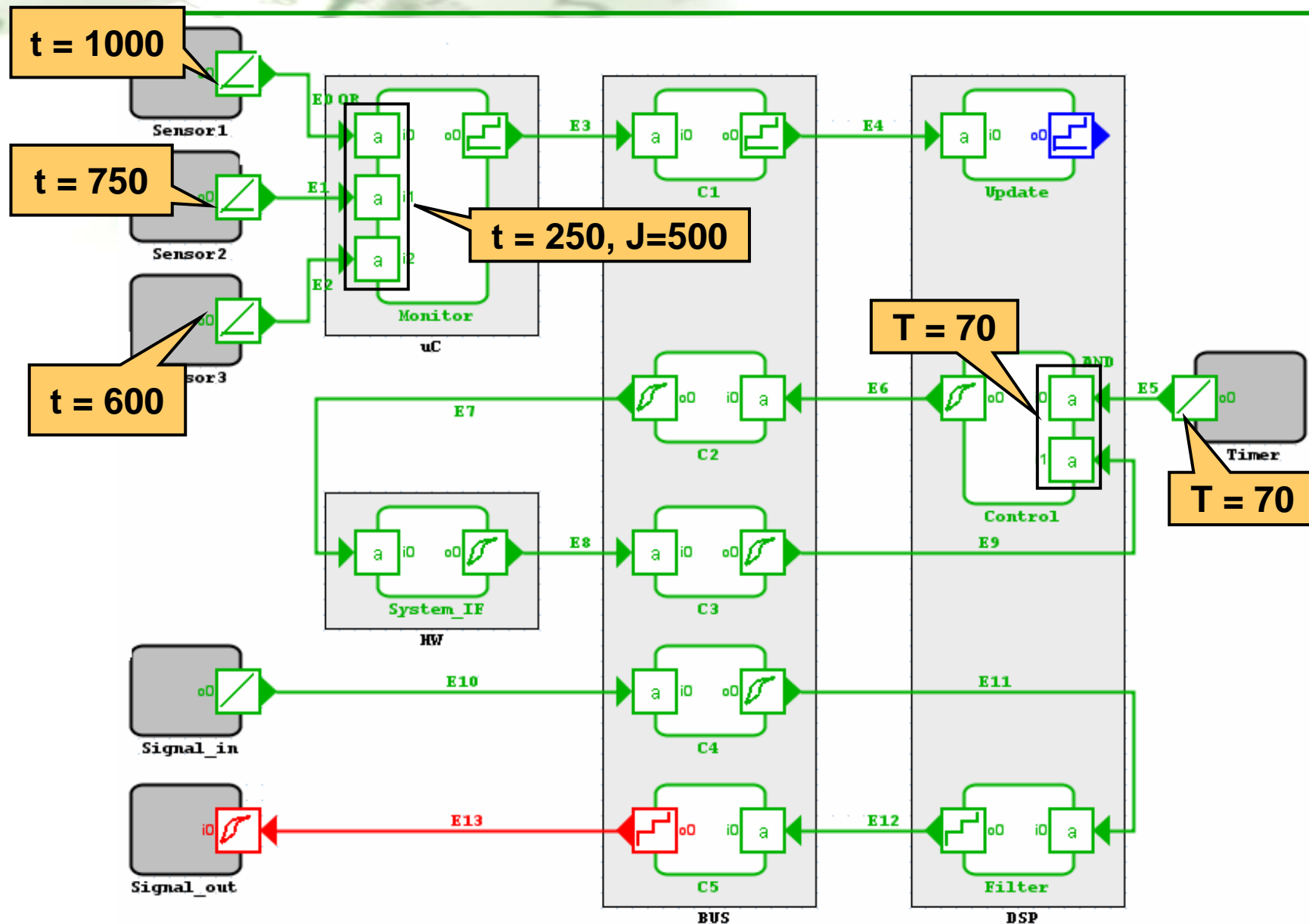
Resource Level Analysis

- **Local scheduling techniques**
 - **Static Priority Preemptive incl. RMS and DMS**
 - **TDMA**
 - **EDF**
 - **Round Robin**
 - **Static Execution Order**
- **Industry related (including non-preemptiveness)**
 - **OSEK flavours**
 - **CAN, including error models**

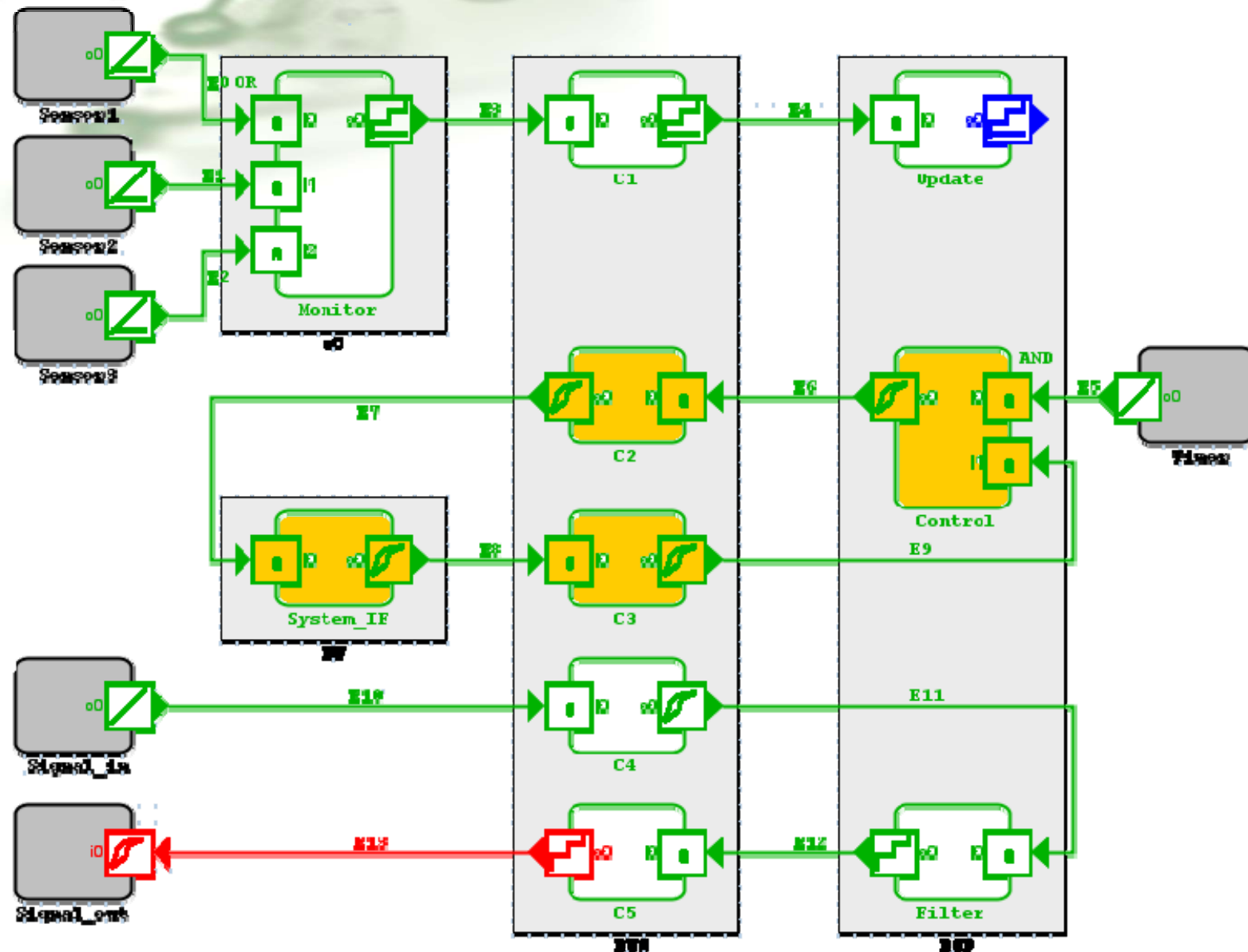
System Example



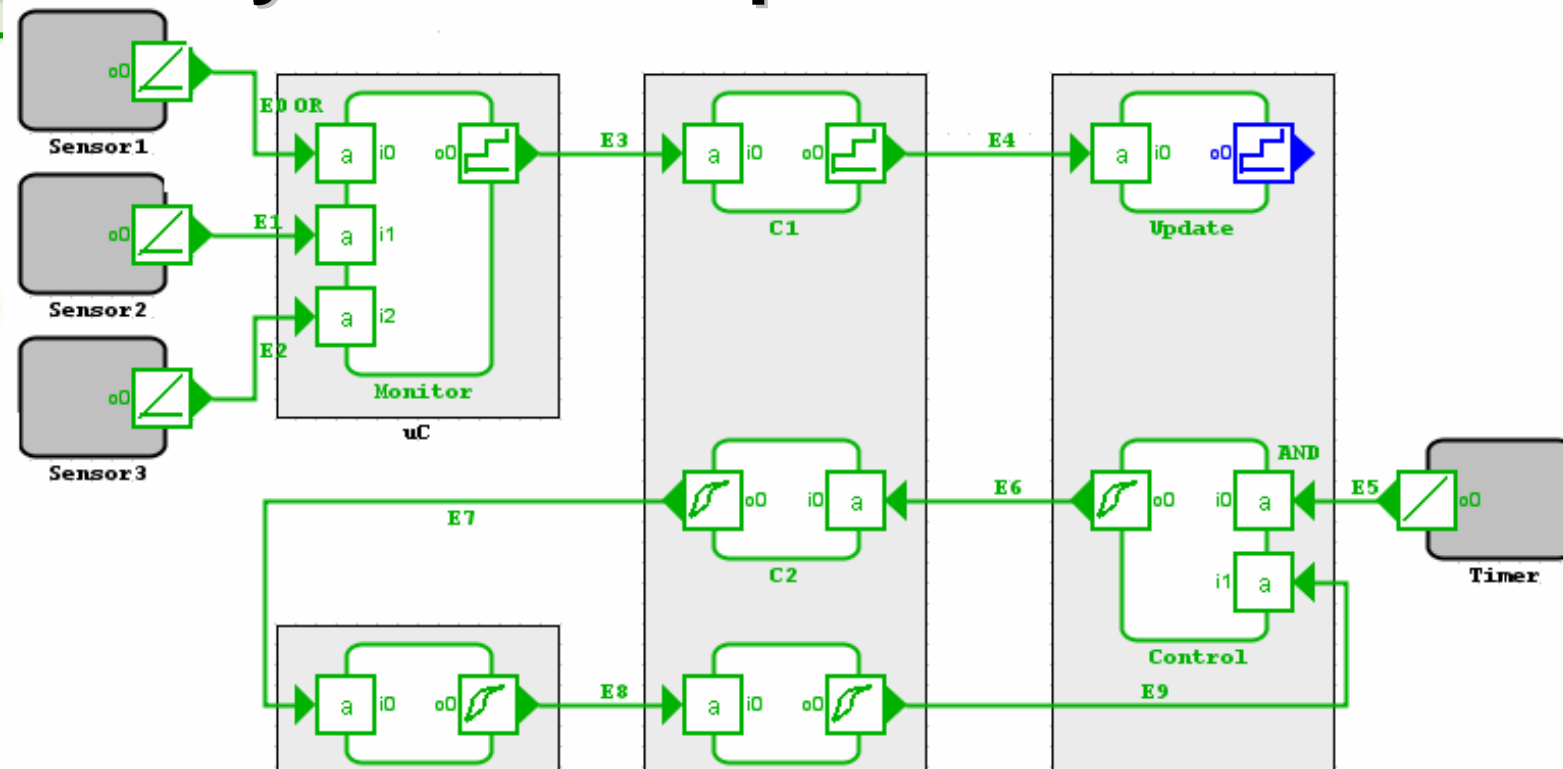
System Example: Multi-input Tasks



System Example: Functional Cycle



System Example: Constraints



Path Observer

Start:

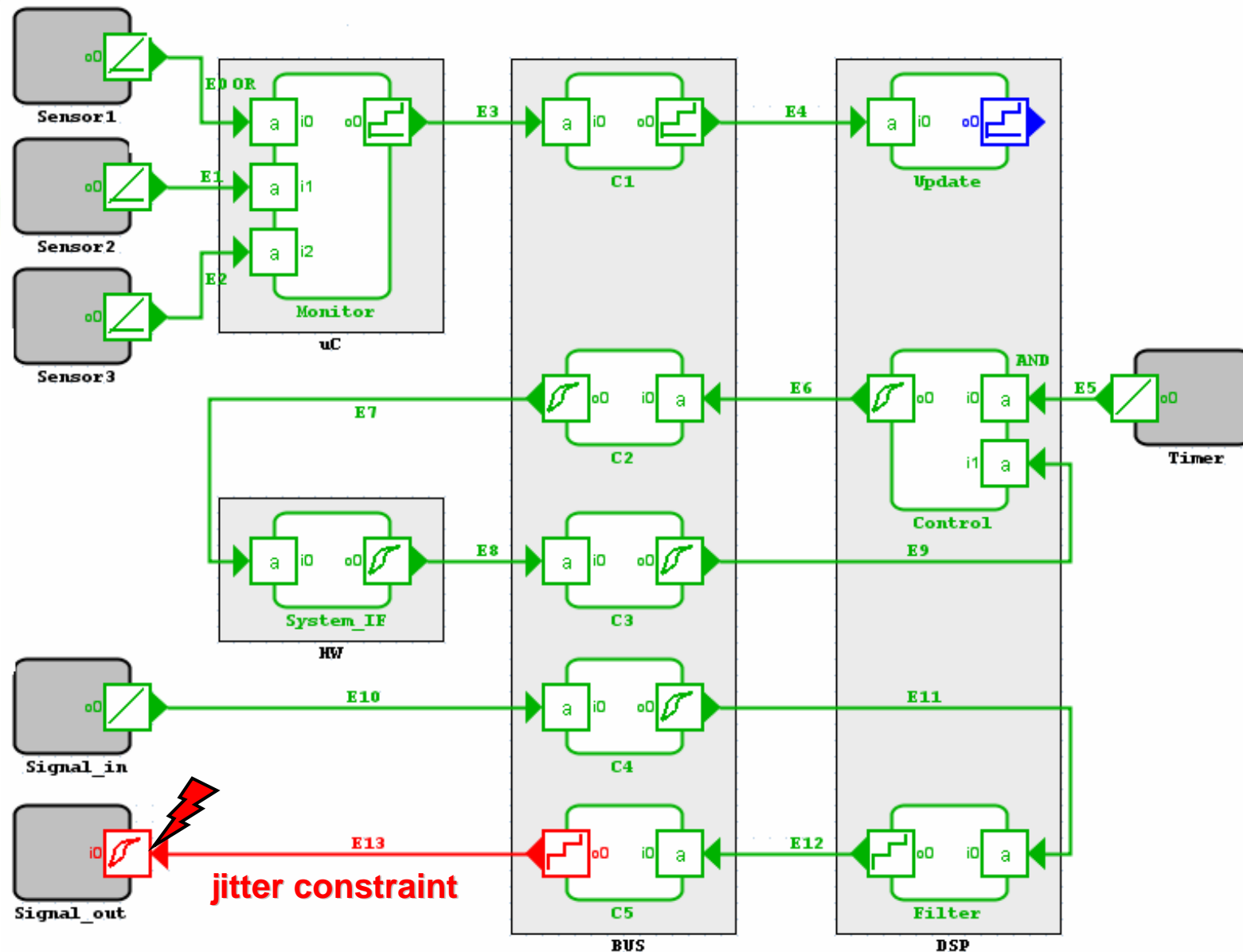
End:

all

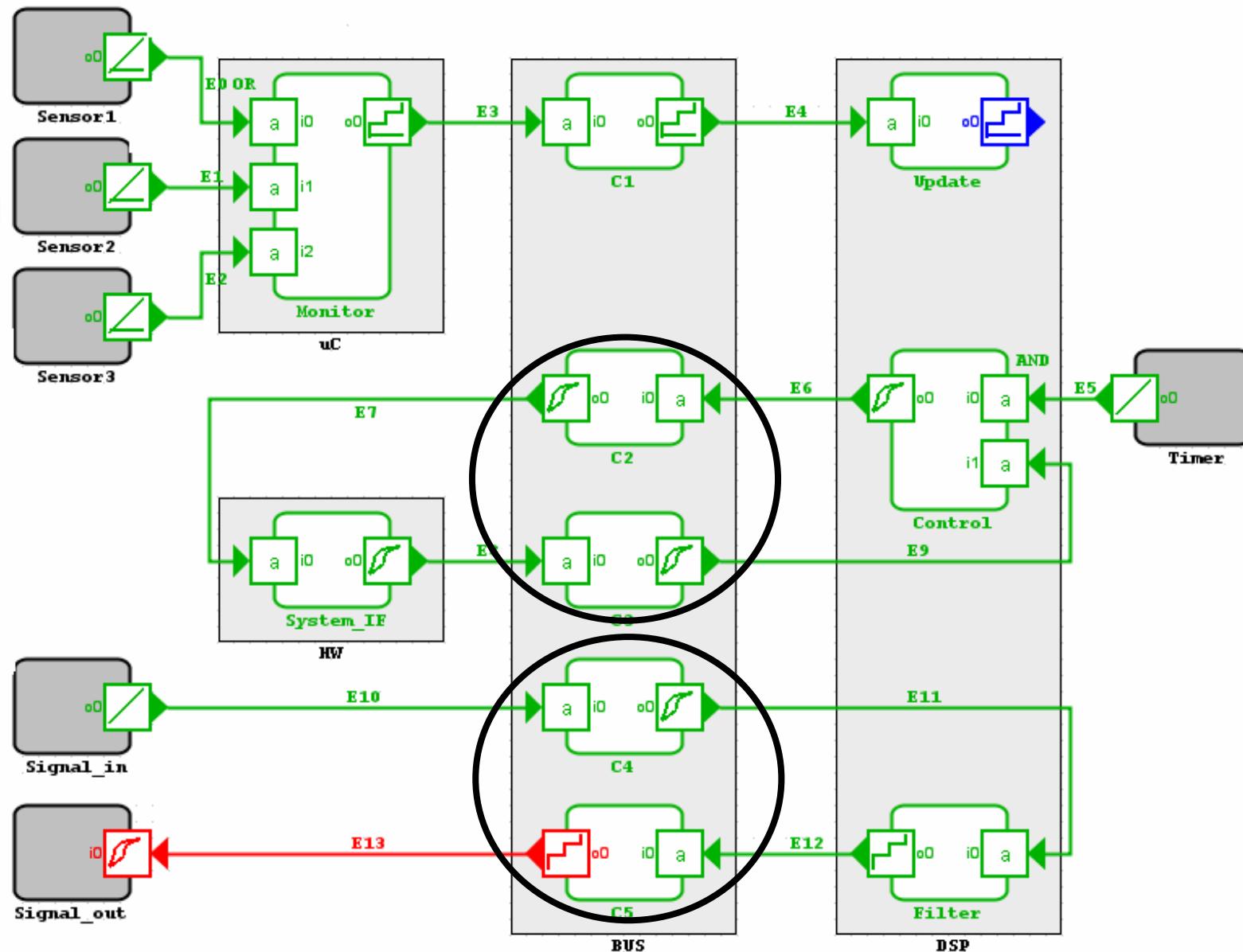
| Name | Latency | Constraint | Buffer | Status |
|--------------------------|---------|------------|--------|--------|
| Paths | | | | |
| • Sensor1 → Update | [19,45] | 70 | 5 | |
| • Sensor2 → Update | [19,45] | 70 | 5 | |
| • Sensor3 → Update | [19,45] | 70 | 5 | |
| • Signal_in → Signal_out | ? | 60 | ? | |

| Name | Latency | Token Con... | Laten... | Req. Tokens | Buffer | Status |
|---|---------|--------------|----------|-------------|--------|--------|
| Cycles | | | | | | |
| ✓ Control→E6→C2→E7→System_IF→E8→C3→E9→Control | [43,76] | 2 | 140 | 2 | 5 | |

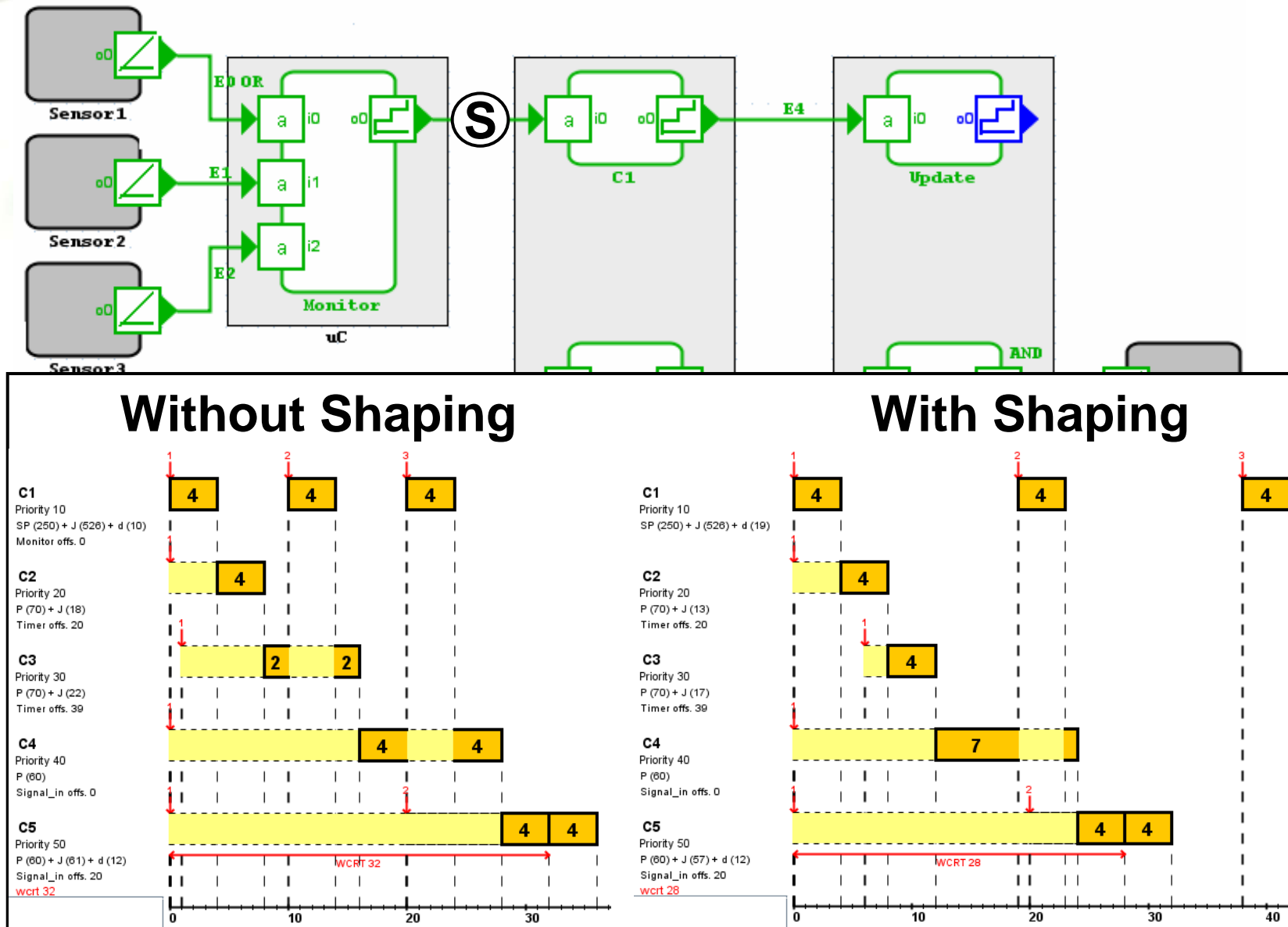
System Example: Constraints



System Example: Precedence Relations



System Example: Traffing Shaping

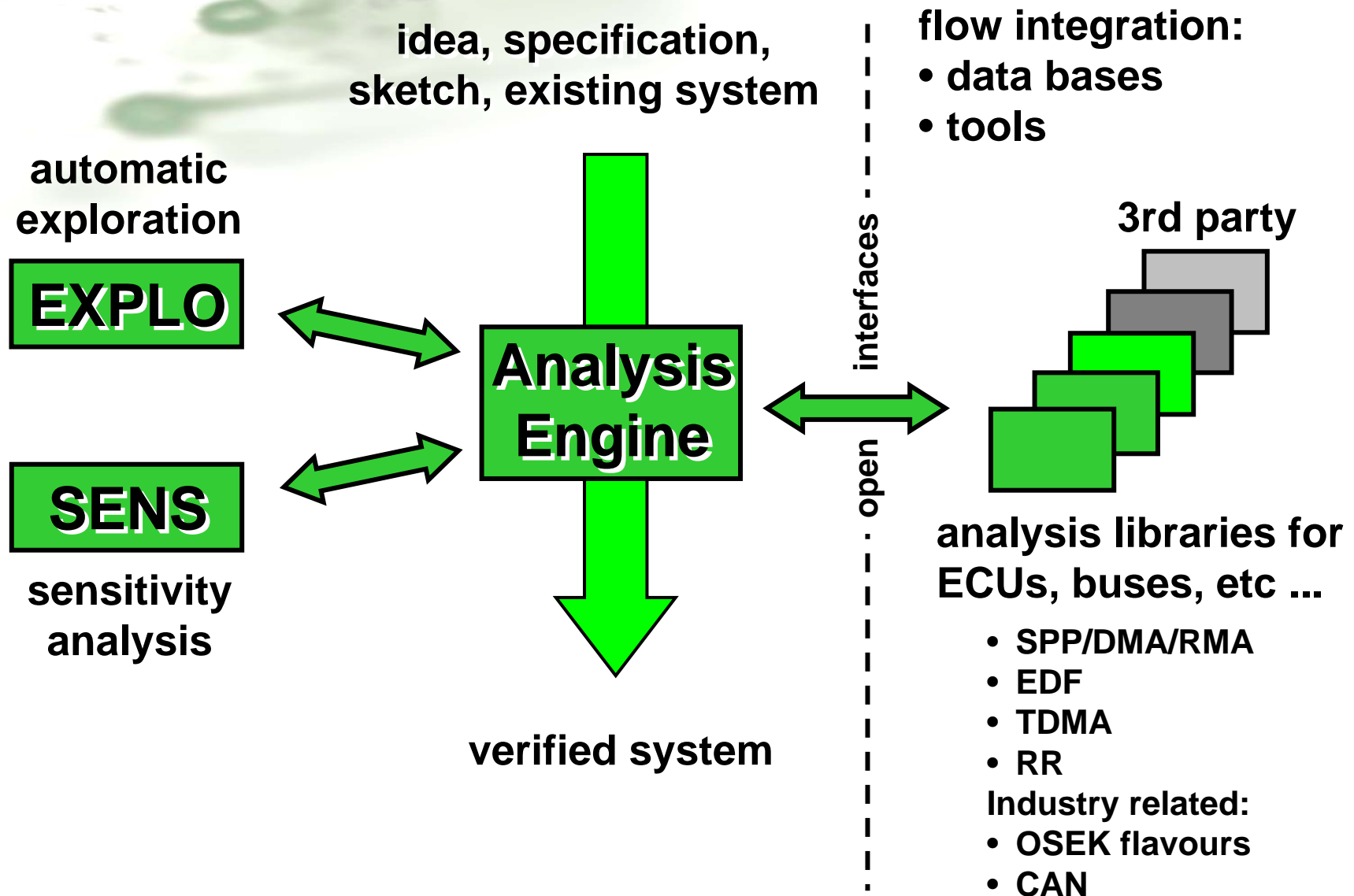




Key features

- **Heterogeneous architectures with local scheduling strategies**
- **Complex applications**
 - **Multi-input tasks with AND and OR-activation**
 - **Tasks with different execution modes & context propagation**
 - **Functional and non-functional cycles**
- **System-level analysis**
 - **Local and global phase (offset) information between events and event streams, task precedence relations**
 - **End-to-end deadlines**
- **Traffic Shaping**
 - **Buffer sizes**
 - **Control interaction of connected components**

SymTA/S Tool Suite



Current Limitations and Possible Extensions

- **FIFO communication and activation**
- **Local analysis focus vs. holistic consideration**
 - **Pay bursts only once**
- **Few "holistic ideas" can be extracted and used in the compositional approach**
 - **Pseudo-holistic algorithm to compute path latencies**
- **Other event models**