



Requirements: Dynamic Memory Management

Alfons Crespo



Memory Management

- There is a significant work done in quality of service of processor scheduling and networks. But memory is a resource that has been included in the list of resources but
.....
- In real-time community there is some myths about dynamic memory management

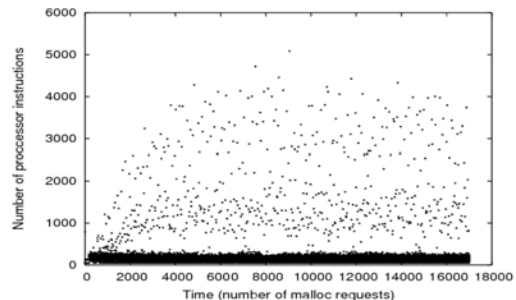
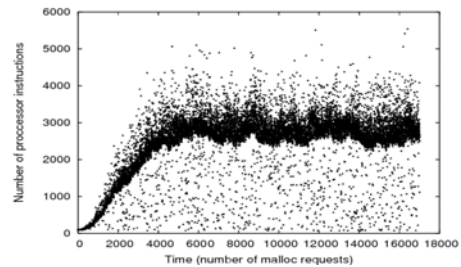
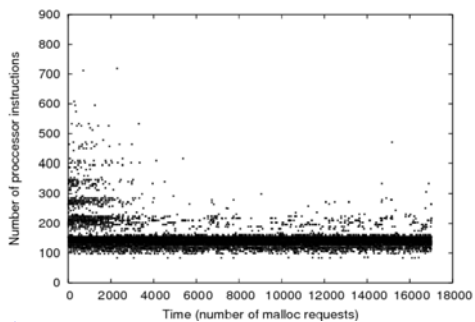


Myths

1. Allocating dynamic memory (**malloc** operation) is **unbounded and slow**
2. Long running programs will fragment the memory pool more and more, consuming unbounded memory.
3. It is better to implement your own allocator for your application needs
4. Real-time applications should not use dynamic memory
5.



Allocators





Memory Management

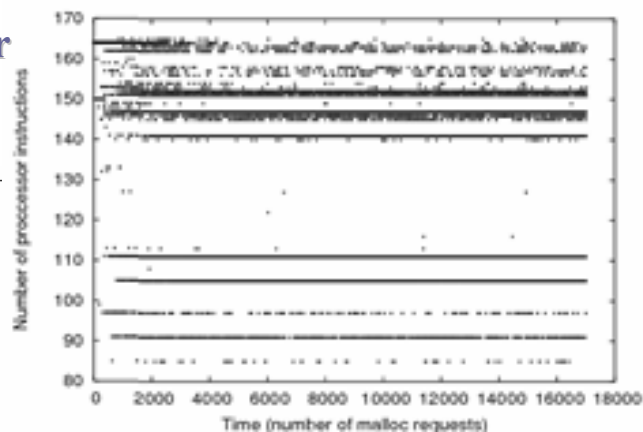
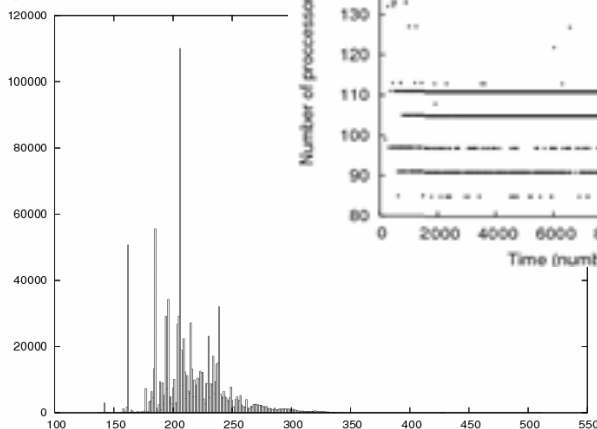
- Current applications (multimedia, mobile, etc.) can require the use of **dynamic memory**.
- Current dynamic storage allocation techniques presents
 - Constant temporal cost ($O(1)$) for allocating and deallocating objects (chunks of memory)
 - Low fragmentation ($< 15\%$) in application running for long periods
- These features permit to include the temporal cost in the schedulability analysis.

..... but the fragmentation require additional features.



Temporal analysis

TLSF allocator (OCERA)



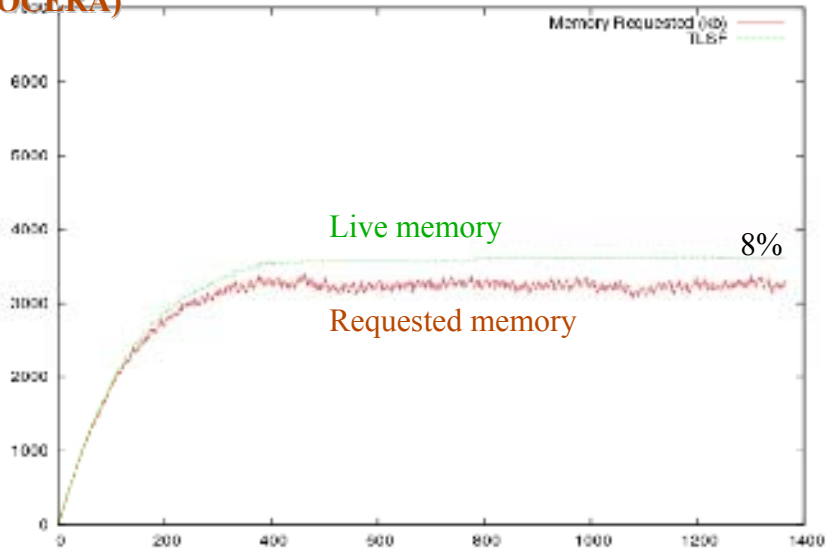
Number of instructions

Number of processor cycles histogram

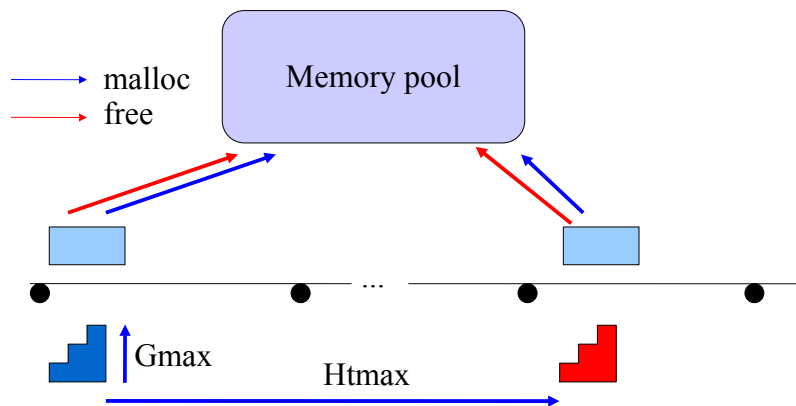


Fragmentation

TLSF allocator (OCERA)



Real-time task using memory



Attributes:

Gmax - maximum amount of memory allocated by period

Htmax - maximum holding time

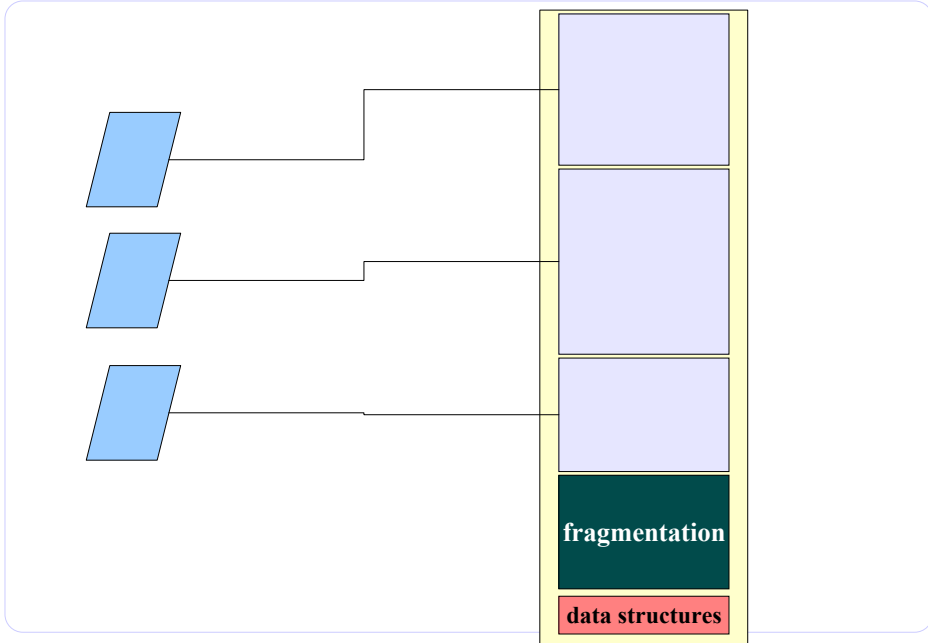
(Ci, Pi, Di, Gi, Hi)

$$\text{Worst Case Memory Space (WCMS)} = G_{\max} * (H_{\text{tmax}} / \text{Period})$$



Real-time task using memory

Grupo de sistemas de tiempo real. <http://www.gii.upv.es>



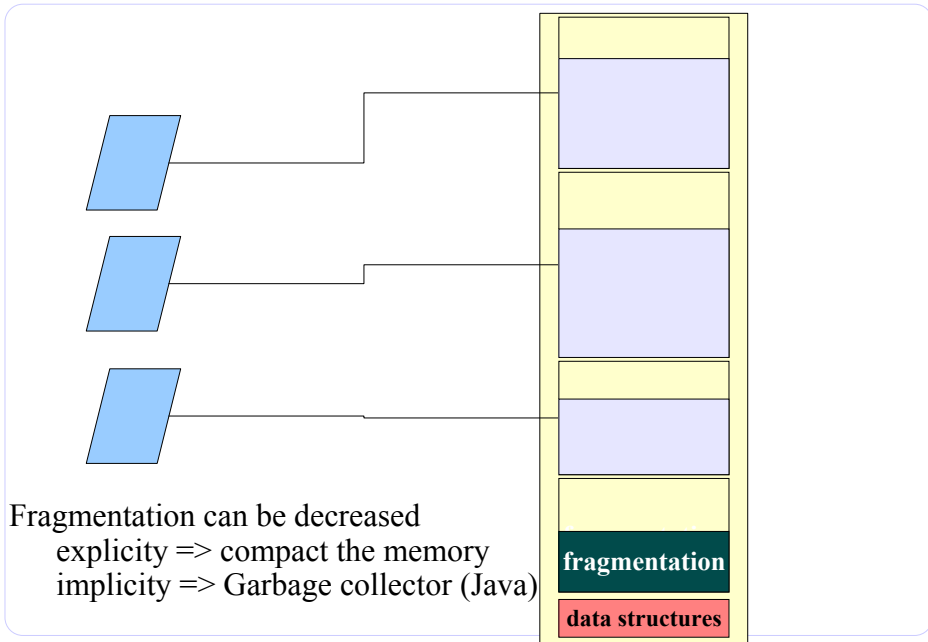
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Real-time task using memory

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Real-time task using memory

Memory can be allocated **permanent** to a task which can it and free at any moment.

Memory can be allocated **temporally** to a task which can it and free under some constraints (spatial or temporal constrains).

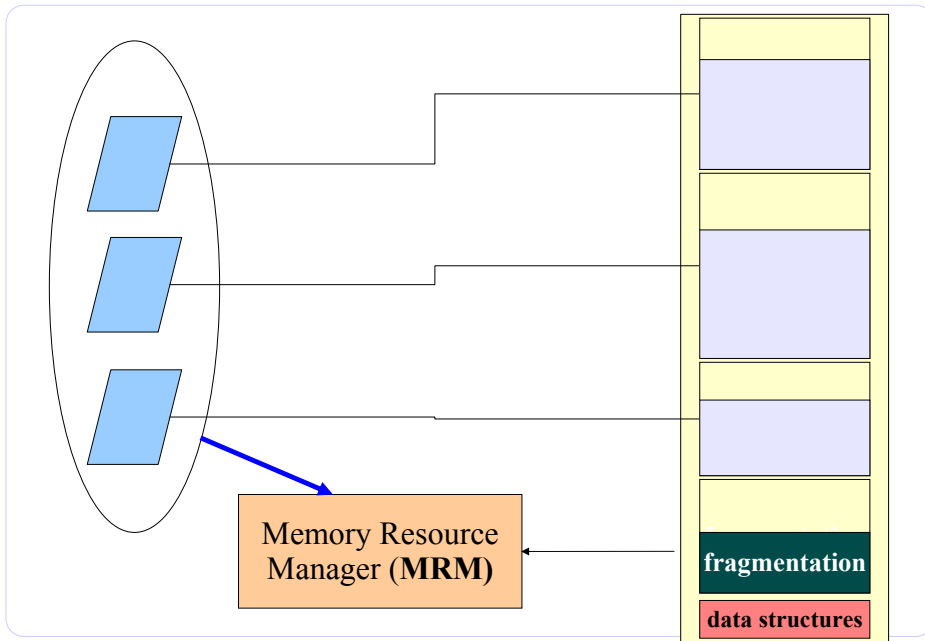
A memory allocation is **permanent** if
 $M_{\text{allocated}} < M_{\text{max}}$

When no more **permanent** memory can be allocated, more memory can be allocated in a **temporal** way.

- Temporal constraints: during an interval
- Storage constraints: while the memory use is within a range



MRM





MRM Interface

Specify the memory requirements:

```
MRM_preallocation_parameters(task_id : in Task_Identification,  
    preallocated_memory_size: in Size,  
    max_request_period: input Time)
```

Allocate objects in a permanent way

```
function malloc(task_id : in Task_Identification, size : in Size)  
    return pointer;
```

Deallocate objects

```
procedure free(task_id : in Task_Identification, ptr : in Pointer);
```



MRM Interface

Negotiate **new** memory requirements:

- based on temporal requirements

```
# A task can ask for more memory (s blocks) for an interval  
# A task can ask for the maximum memory available during k periods
```

- based on storage requirements

```
# A task ask for memory based on storage criteria (not temporal  
guarantee). Task has to release memory by request.
```

Allocate objects in a temporal way

```
tmalloc
```



MRM

Also, other kind of tasks can be considered (Non periodic tasks)

- **run for a number of periods (under server constraints)**

or / and

- **have global memory needs (maximum memory by applications)**