# Some lesser-known contributions of Paul Caspi

Jacques pulou

With some help from E. Closse and D. Weil







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#### Paul 's Doctorate Thesis : identifying unstable deterministic linear systems



### Crucial moment during Paul's defense : (1979 May 25th 1979, IEG-INPG)

One examiner of the Paul Caspi Doctoral Thesis defence :

"Mister Caspi: what good are non stable systems ?"

Paul Caspi :

"Imagine that each cow produces 0,9 calf by year on the average"

## Two exemple of linear deterministic and unstable systems





#### Country beef herd

#### hydroptere

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## 1 : first encounter with safety critical applications

Crouzet Aviation (now subsidiary of Schneider Electric)



- Crouzet (Valence near Grenoble) wants to experiment SC systems
- Crouzet proposes to study a concrete example :
  - Airborne anemometric station (sampling pressure-s and temperature sampling to compute aircraft speed)
  - The goal was to be better than 10<sup>-7</sup> fault / hour
  - On the average 10 hour flight 1 default for 1 Million flights

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### Self checking and reconfigurable systems









### 2: Meeting IC Random Testing



- Given a set of fault F and a level of confidence 1-ε
- Find the **minimal number of inputs** L that decreases the risk to get a "false positive" under ε
- If Pf is the probability that an input detect the "most difficult to detect" fault f within F then :

L = log (
$$\epsilon$$
)/ log (1-pf) pf = min Pr {a random input detect f}  
f \in F

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### Random Testing of RAM

- Fault hypothesis on RAM take into account RAM cell plane geometry or its word structure.
  - Suppose cells i, ,j, k = (0,1,0) when i is set then k is upset too



- Such fault are denoted as finite pattern sensitive fault (PSF)
- Paul give the rather simple demonstration that test length (at a given confidence level) for any PSF behaves linearly with the size of memory: L = α +βn

### 3: Hardware Testability Measure



Consider node c : Minimal Cut from circuit input i to c Commandability of c =3

Minimal cut from c to circuit output o Observability of c =2

Module netlist of an harware system

## Introducing Information theorie based testability measure

- Module Observability and Commandability are based on a "new Entropy " function with respect to the one from C.E Shannon (this is an upper bound of it)
- Defining Module Commandability and Observability as upper bounds of the amount of information that can be brings respectively:
  - to the module inputs from circuit inputs
  - from the module outputs to circuit outputs
- This very basic (precise module function are not taken into account) but seminal work has been further extended to software issue …
  - New testability measure beside classical NPATH and McCabe'cyclomatic number
  - Promising application to testability measurement of .... LUSTRE synchronous data flow programs . (SATAN Tool)



## 4 : Triggering the France Telecom branch of the synchronous evolution

- An existing target for code execution, but without high level specification (GSM MAC layer of ALCATEL one touch mobile)
- Paul Caspi advice: the Esterel formulation is well adapted
- A new kind of Esterel compilation method : the SAXO-RT compiler
  - Efficient
  - For a subset of Esterel in a first step, then a complete compiler
- Transfer to Dassaut Systems (E.Closse and D.Weil)
  - Development of LCM: Esterel semantic + ML features
  - Evolution of LCM:
    - Convergence data flow and state machine
    - back to Lustre branch in the Lucid form (collaboration with M.Pouzet)

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#### TAXYS = Kronos + Esterel Assigning timed behaviour to Esterel

- Kronos : model-checking of timed-automata (VERIMAG)
- TAXYS : annotated ESTEREL as high-level language for writing timed automata.



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#### THANK YOU PAUL...

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### Welcome in a Synchronous World !



Assuming perfect observability of subsystem

Information based Testability

 $\sum p_i \log_2 p_i$ 

i ∈ set of input s of a given (sub)-system "Random" Testability

#### Min (p<sub>i</sub>)

 $i \in set of input s$ of a given (sub)-system

 $p_i$  = Probability that input of (sub) system = i



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