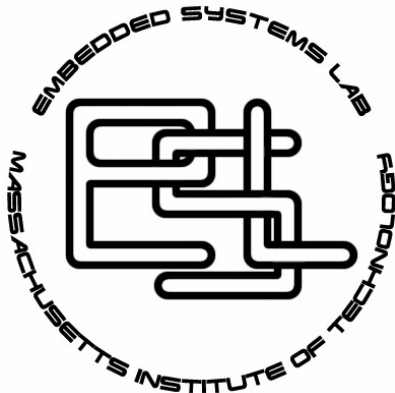


Bi-Directional Traceability: The Hi-Five Framework Approach to Reliable Validation of Early System Designs



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Project Outline

□ Motivations

- High cost of Validation & Verification (**V&V**)
- Benefits of **modeling**
 - Building confidence into the system early on
 - Economics of bug detection and correction
- Reuse of the **state-of-the-art**
 - Verification
 - Test case generation

Overview of Hi-Five



Current State

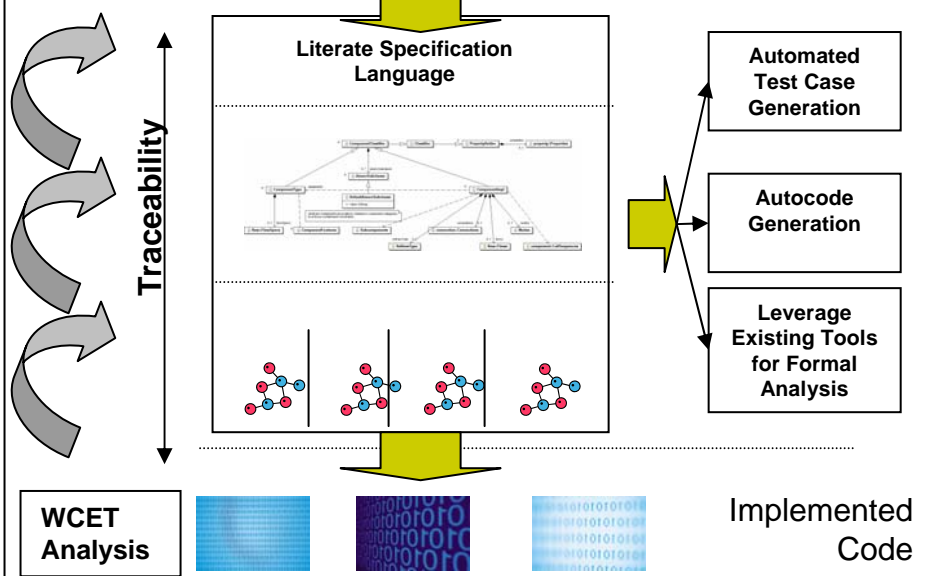
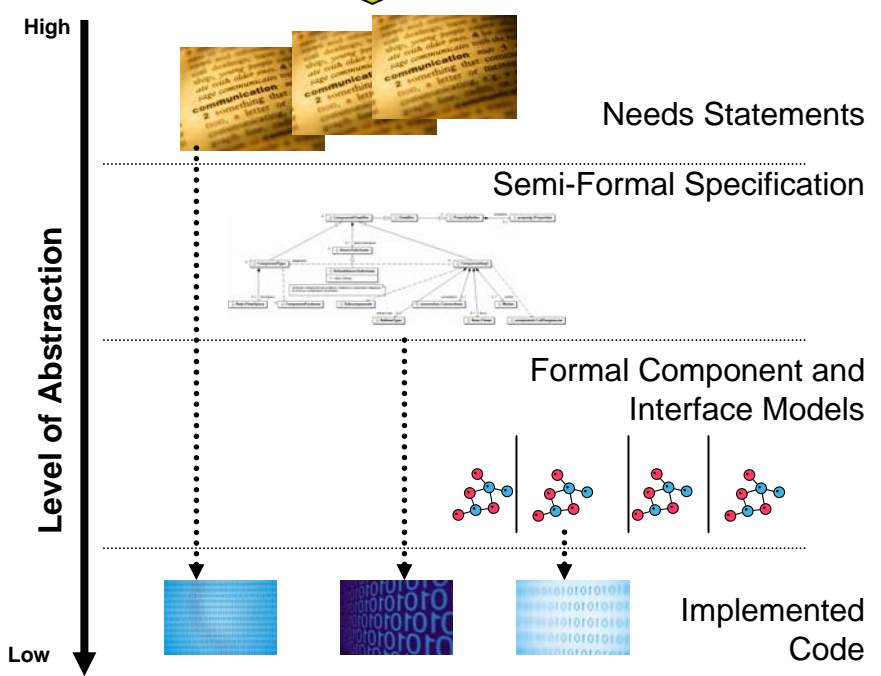


Ongoing Research



Abstracted

Abstracted



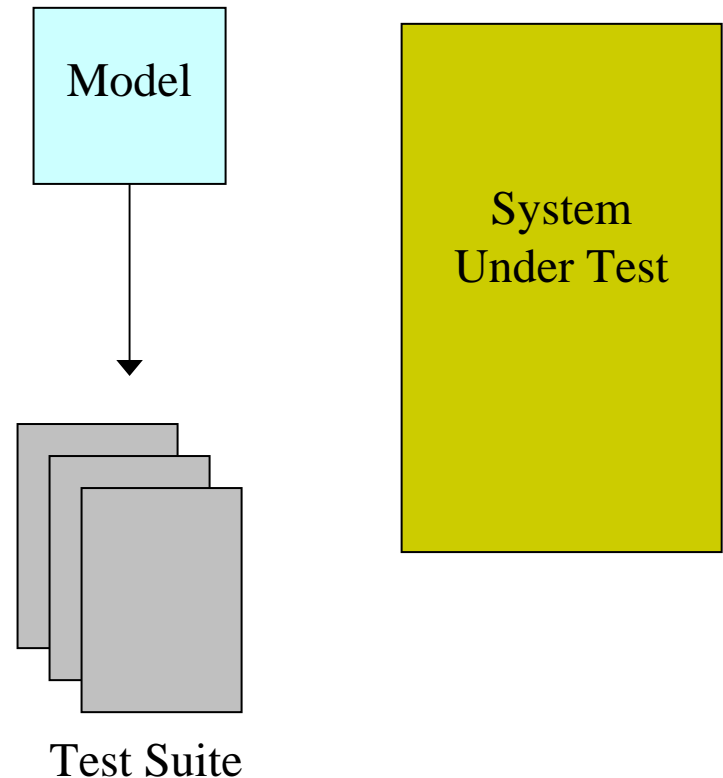
Modeling Time and Non-Functional Properties



- Can time be reliably estimated for software, without an implementation?
 - Maybe you don't care
 - Level of abstraction
 - Speed of software vs. rest of system
 - Nature of system
 - Maybe you care
 - Do the best you can
 - Estimates become constraints on implementation
 - Use feedback from implementation in model
 - Develop around a known platform with a library of components

Test Case Generation

- Model-Based Testing
 - Use model to generate test cases
 - Model acts as an oracle
 - Meaning of model coverage vs. implementation coverage?



The TASM Language

- Literate modeling language based on ASM
- Function + Time + Resources
- Duration is the key paradigm to represent time
- Time specified as interval to capture BCET, WCET, and uncertainty



The TASM Toolset

- Graphical Front-End for Specification, Simulation, and Analysis

- Integrates UPPAAL
 - To verify BCET and WCET paths in the model

- Integrates the SAT4J SAT solver
 - To verify Completeness and Consistency of models



Design

- PROJECT
 - CONFIGURATIONS
 - simple
 - ENVIRONMENT
 - TEMPLATES
 - MAIN MACHINES
 - CONTROLLER
 - FAULT_INJECTOR
 - HUMID
 - SCHEDULER
 - TEMP
 - TIMELINER
 - FUNCTION MACHINES
 - SUB MACHINES
 - EXECUTE_BUNDLES
 - EXECUTE_PLANTSIM_SEQUE
 - PLANTSIM_BUNDLE
 - SEQUENCE_HUMIDITY_MON
 - SEQUENCE_HUMIDITY_MON
 - SEQUENCE_TEMP_MONITOR
 - SEQUENCE_TEMP_MONITOR

ABOUT

name: SEQUENCE_TEMP_MONITOR_WORK

description:

VARIABLES

monitored variables: temp_seq_b; temperature;

controlled variables: temp_seq_b; trying_to_cool_system; temp_seq_s; cooling;

RULES

```

R1: b0 -> b1
{
  t := 685;

  if temp_seq_b = b0 then
    temp_seq_b := b1;
}

R2: b1 -> b2
{
  t := 2285;

  if temp_seq_b = b1 and temperature >= 26 then
    temp_seq_b := b2;
    trying_to_cool_system := True;
    cooling := on;
}

R3: b1 -> b3
{
  t := 1730;

  if temp_seq_b = b1 and temperature < 26 then
    temp_seq_b := b3;
}

R4: b2 -> b2
{
  t := 1625;

  if temp_seq_b = b2 and temperature > 22 then

```

Behavior

Solve

Save to file

Solver

SAT Solver

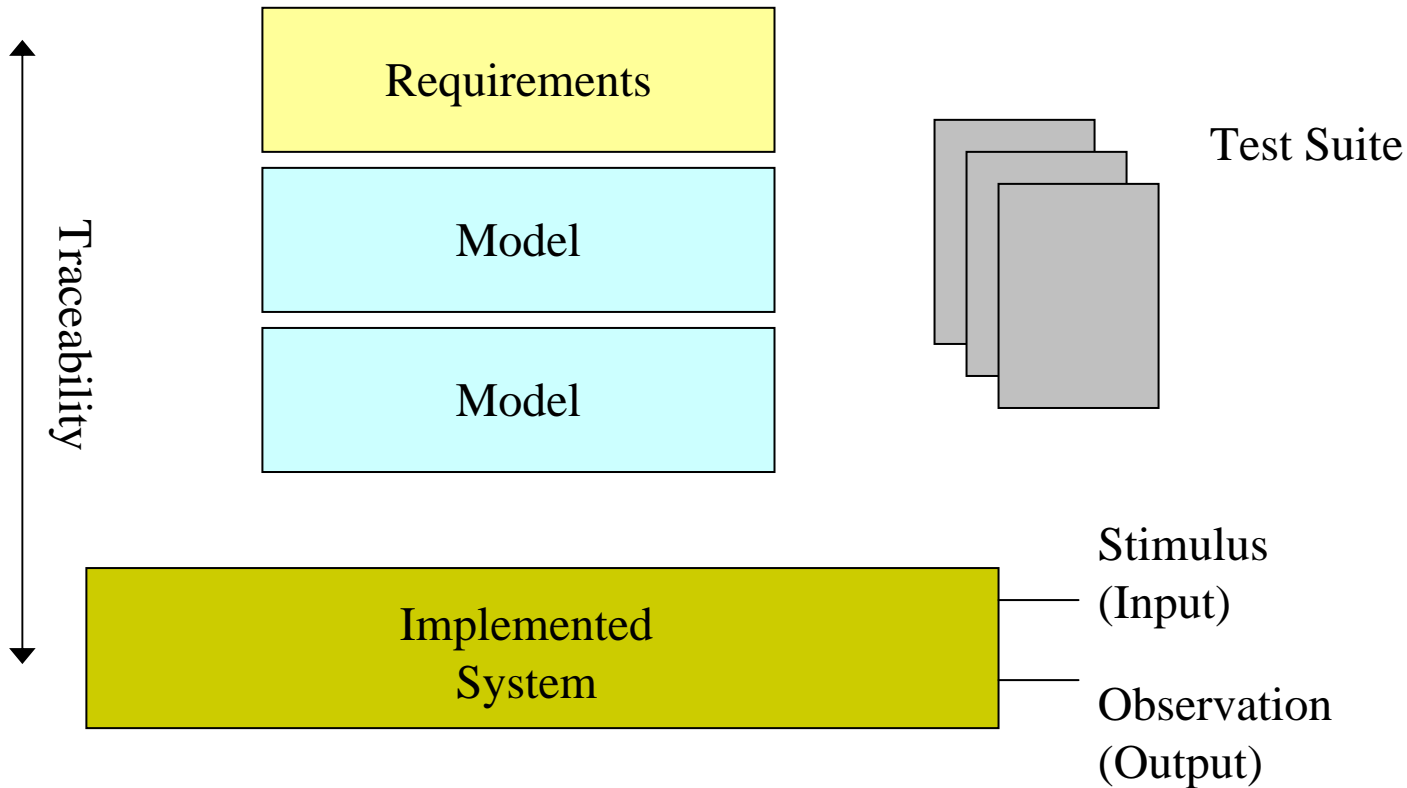
MIP Solver

Default Values

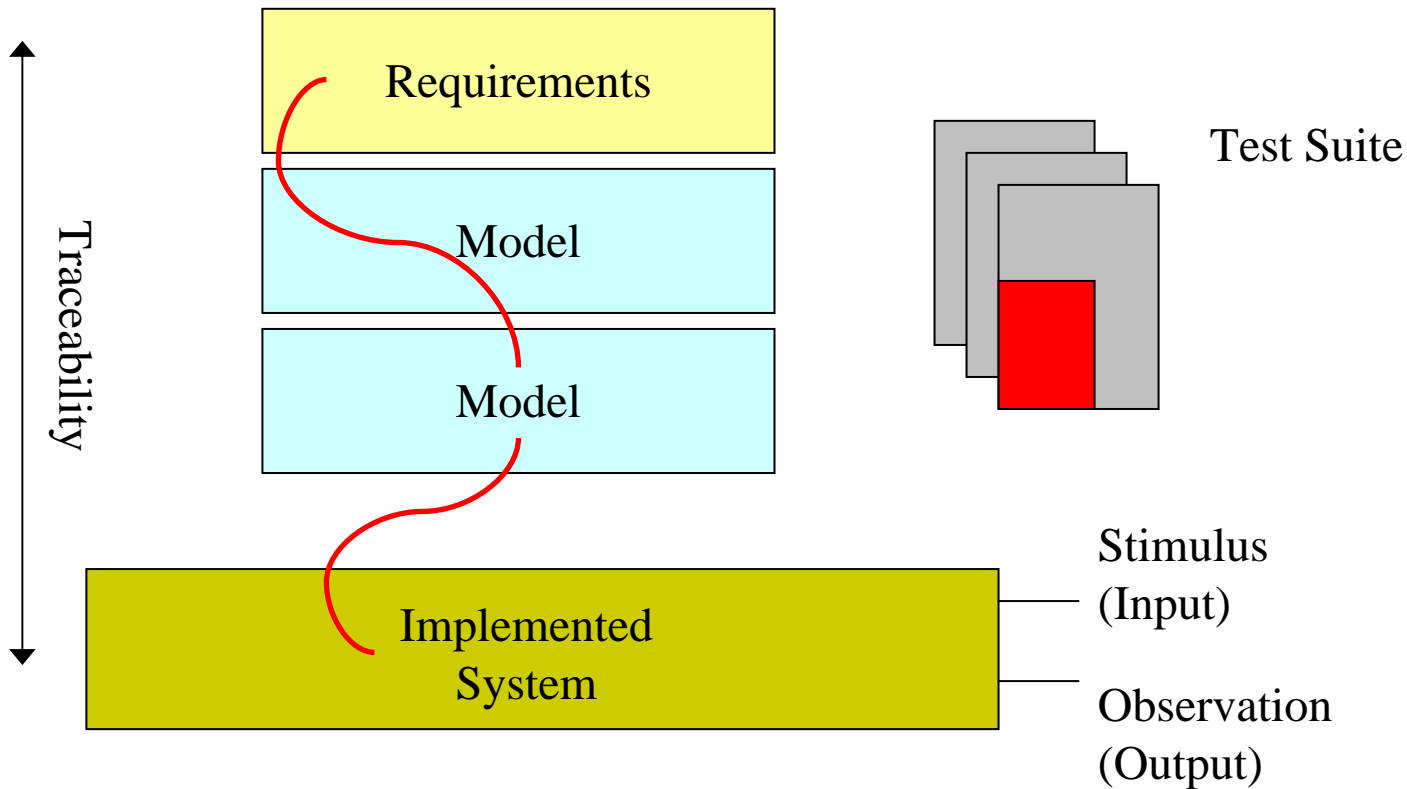
completeness

consistency

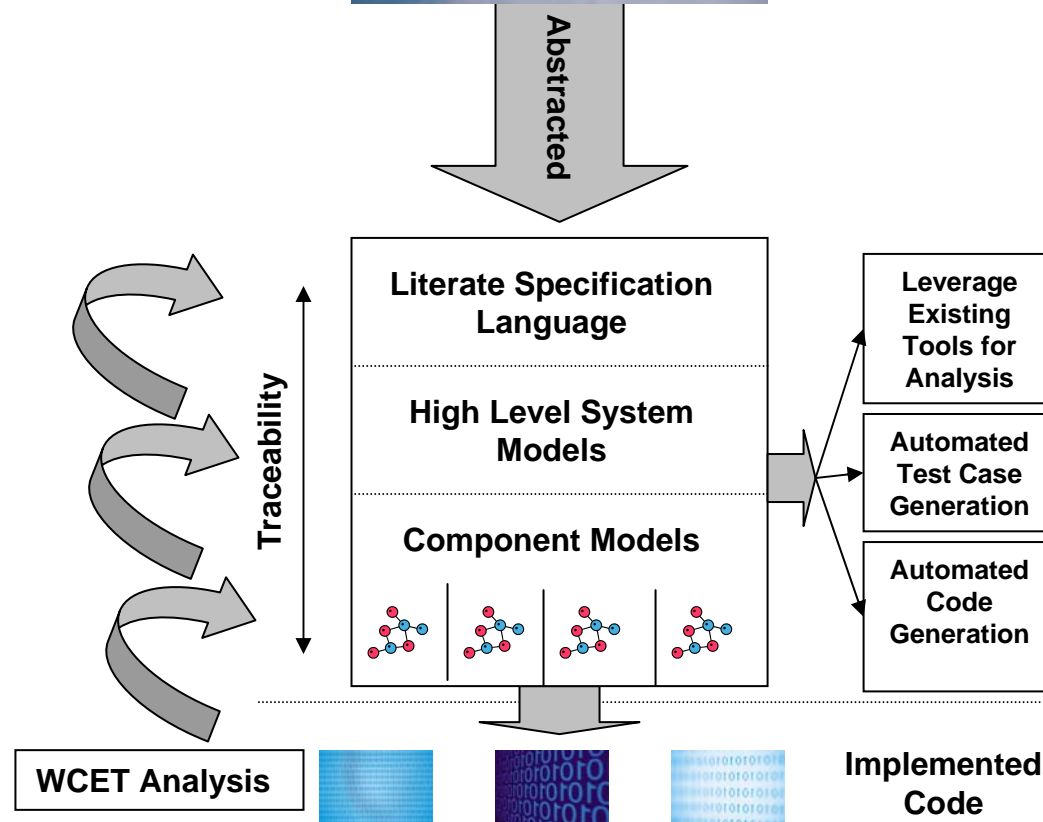
Bi-Directional Traceability



Bi-Directional Traceability



Overview of Hi-Five



Case Study

- The Timeliner System
 - How long should the **timeslice** be?
 - What is the maximum execution time for one “**pass**”
 - How about the minimum **execution time**?
 - What are the timing properties of scripts?



<http://quest.arc.nasa.gov/space/photos/images/images/iss7x.jpg>



Other Case Studies

- ❑ Electronic Throttle Controller (Ford)
- ❑ N-Modular Redundant Avionics (Draper)
- ❑ Production Cell

Questions?



- Thank you for your time

- For more information
 - <http://esl.mit.edu/tasm>
 - tasm@mit.edu

