

ARTIST2 Summer School 2008 in Europe

Autrans (near Grenoble), France

September 8-12, 2008

Enforceable Component-Based Real-Time Contracts

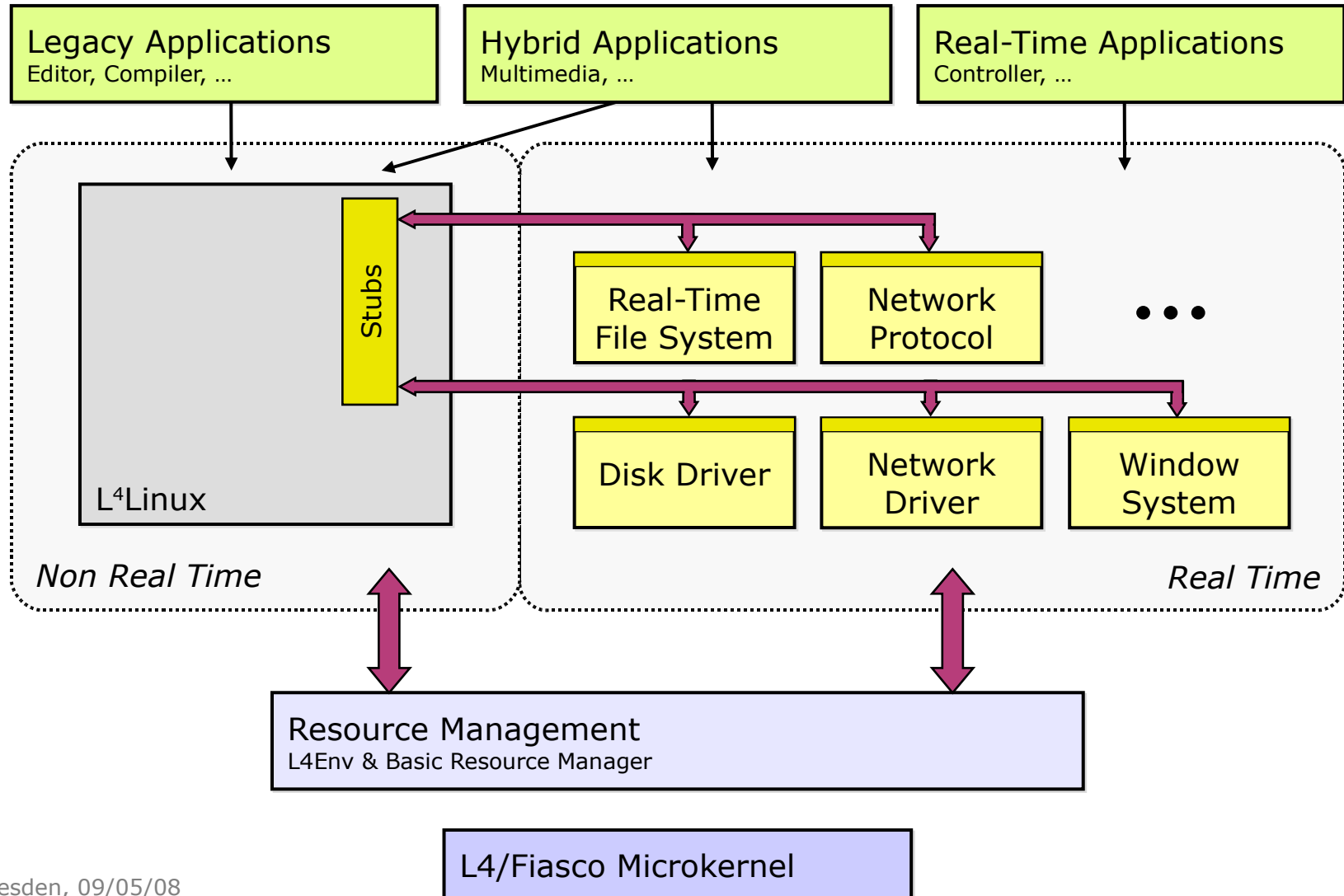
Lecturer: Hermann Härtig

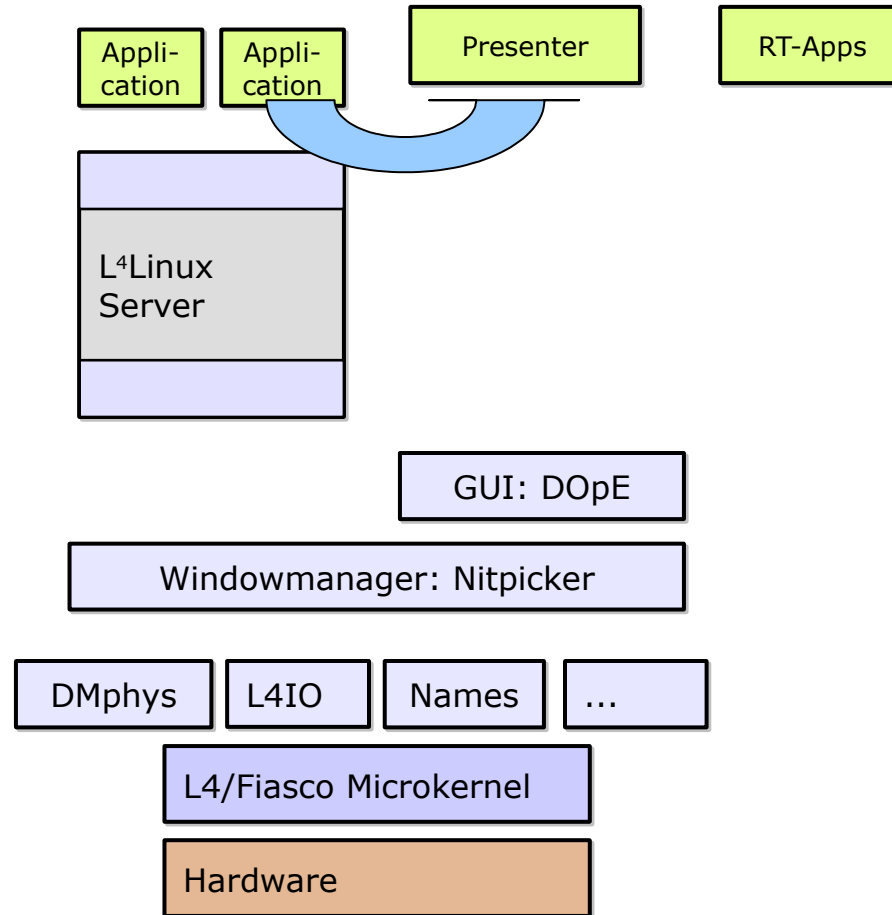
TU Dresden



Enforceable Component-Based Real-Time Contracts Supporting Real-Time Properties from SW Development to Execution

Hermann Härtig, Steffen Zschaler
Department of Computer Science





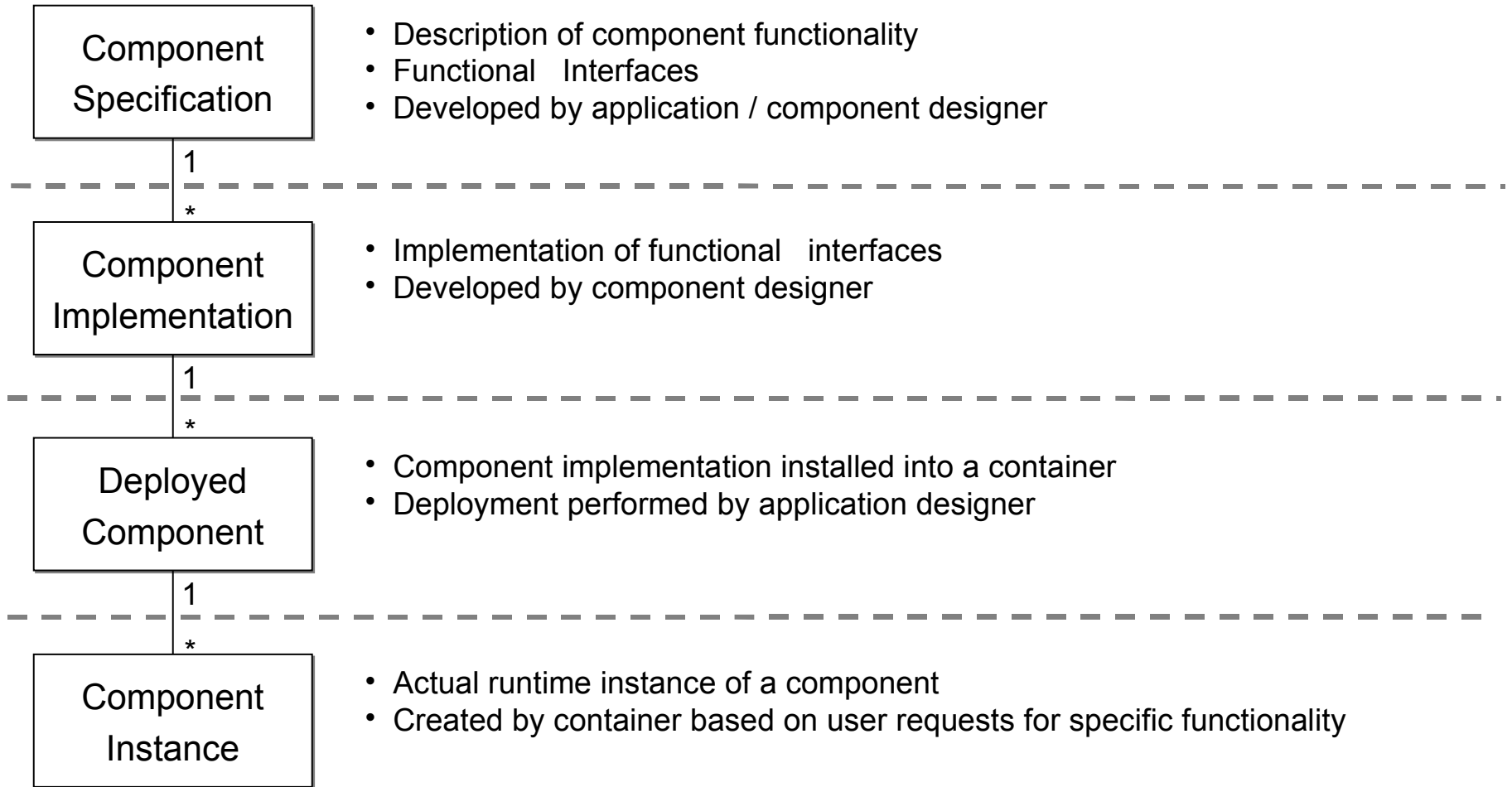
Outline

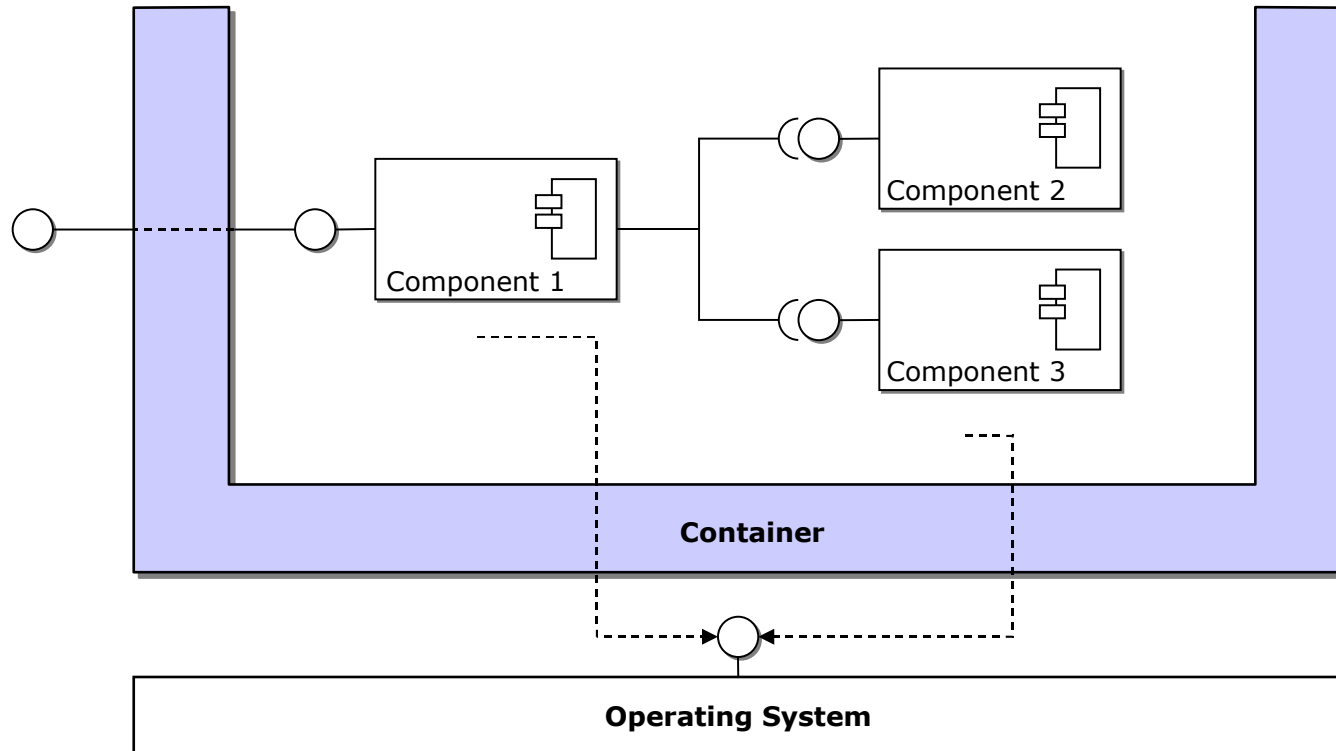
- “Components” in software engineering
- Objectives and limitations
- Short intro into DROPS RT system
- Real-Time Specifications
- Real-Time “Container”
- Lessons learned

“A software component is a unit of decomposition with contractually specified interfaces and explicit context dependencies only. A software component can be deployed independently and is subject to composition by third parties”

Clemens Szyperski (with Dominik Gruntz and Stephan Murer):
Component Software – Beyond Object-Oriented Programming – 2nd Edition
Addison-Wesley / ACM Press, 2002. ISBN 0-201-74572-0.

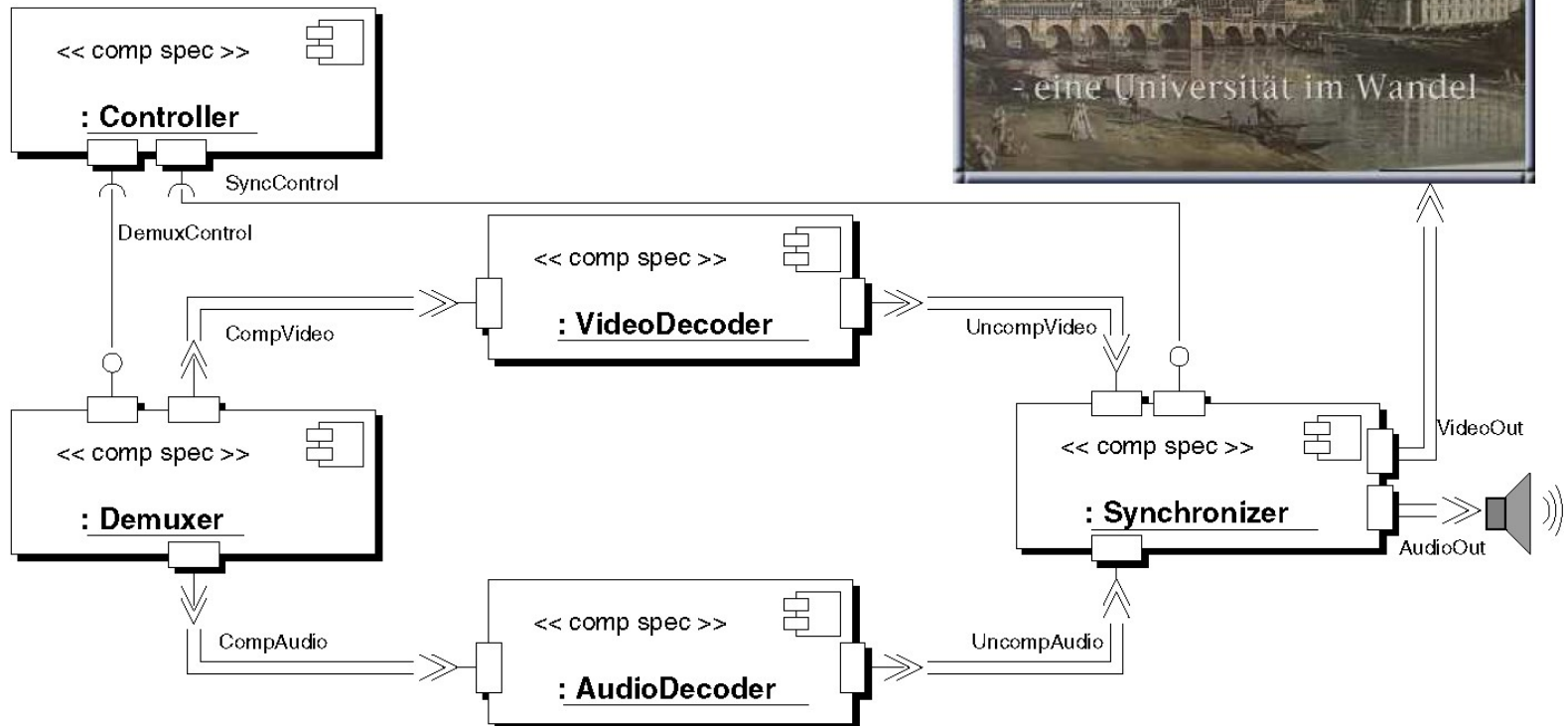
- **Packaged for reuse**
 - Specifications including context dependencies
 - Component repositories / Component markets
 - Standardized run-time infrastructure (“Containers”)
 - “Transparency” goals (location, communication, language, ...)
 - Large chunks of application-level software (business SW, GUI)
- **Examples**
 - Corba
 - Enterprise Java Beans (JBoss)

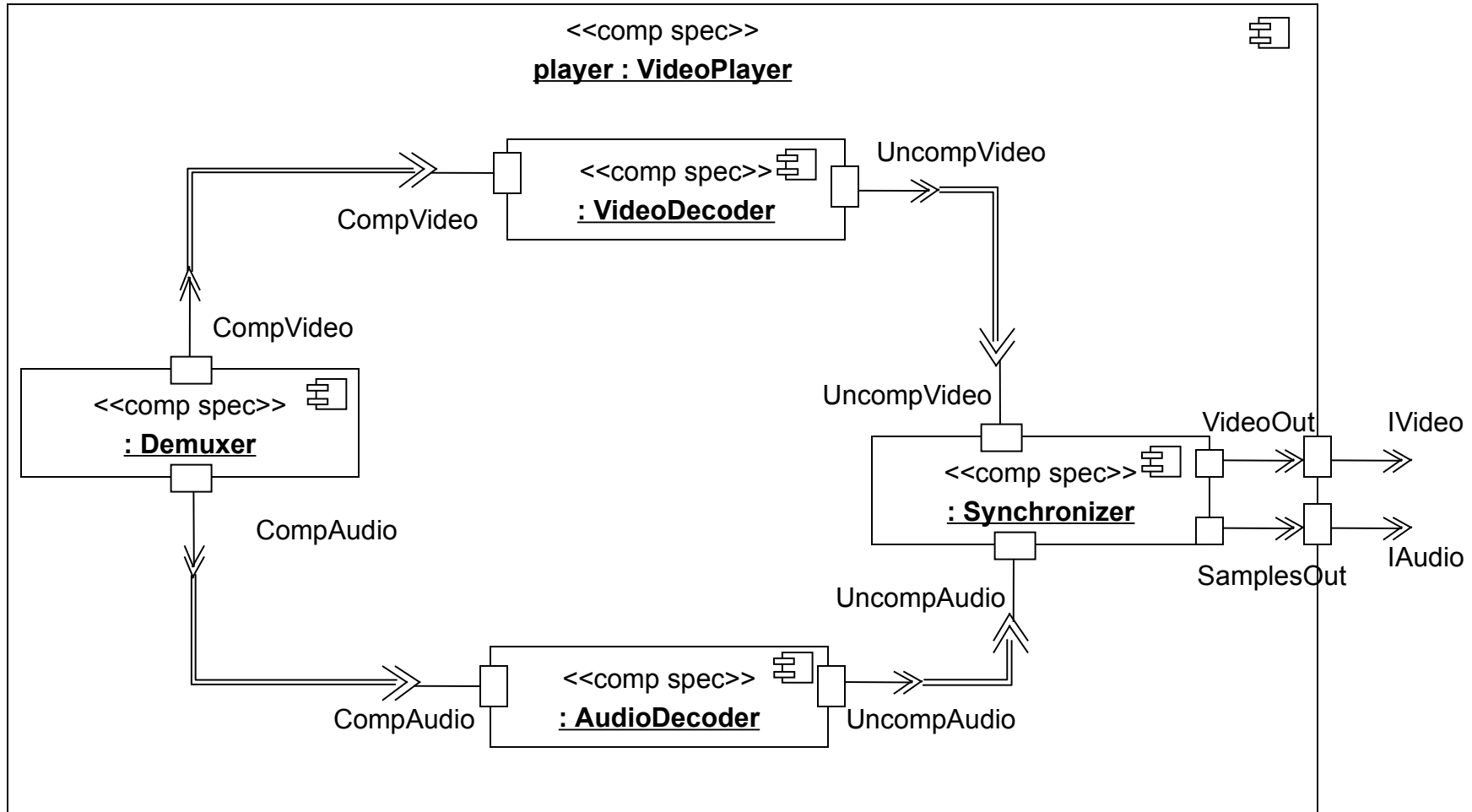






:GUI





```
<template homeplacementref="Synchronizer">
  <instance id="vdec" homeplacementref="VideoDecoder"/>
  <instance id="adec" homeplacementref="AudioDecoder"/>
  <instance id="mux" homeplacementref="Demuxer"/>

  <connectinstance id="this">
    <connect type="stream"
      usesport="uncompressedVideoIn"
      providesport="uncompressedVideoOut"
      instanceref="vdec"/>
    <connect type="stream"
      usesport="uncompressedAudioIn"
      providesport="uncompressedAudioOut"
      instanceref="adec"/>
  </connectinstance>

  <connectinstance id="vdec">
    <connect type="stream"
      usesport="compressedVideoIn"
      providesport="uncompressedVideoOut"
      instanceref="mux"/>
  </connectinstance>
  ...
</template>
```



Instance declaration

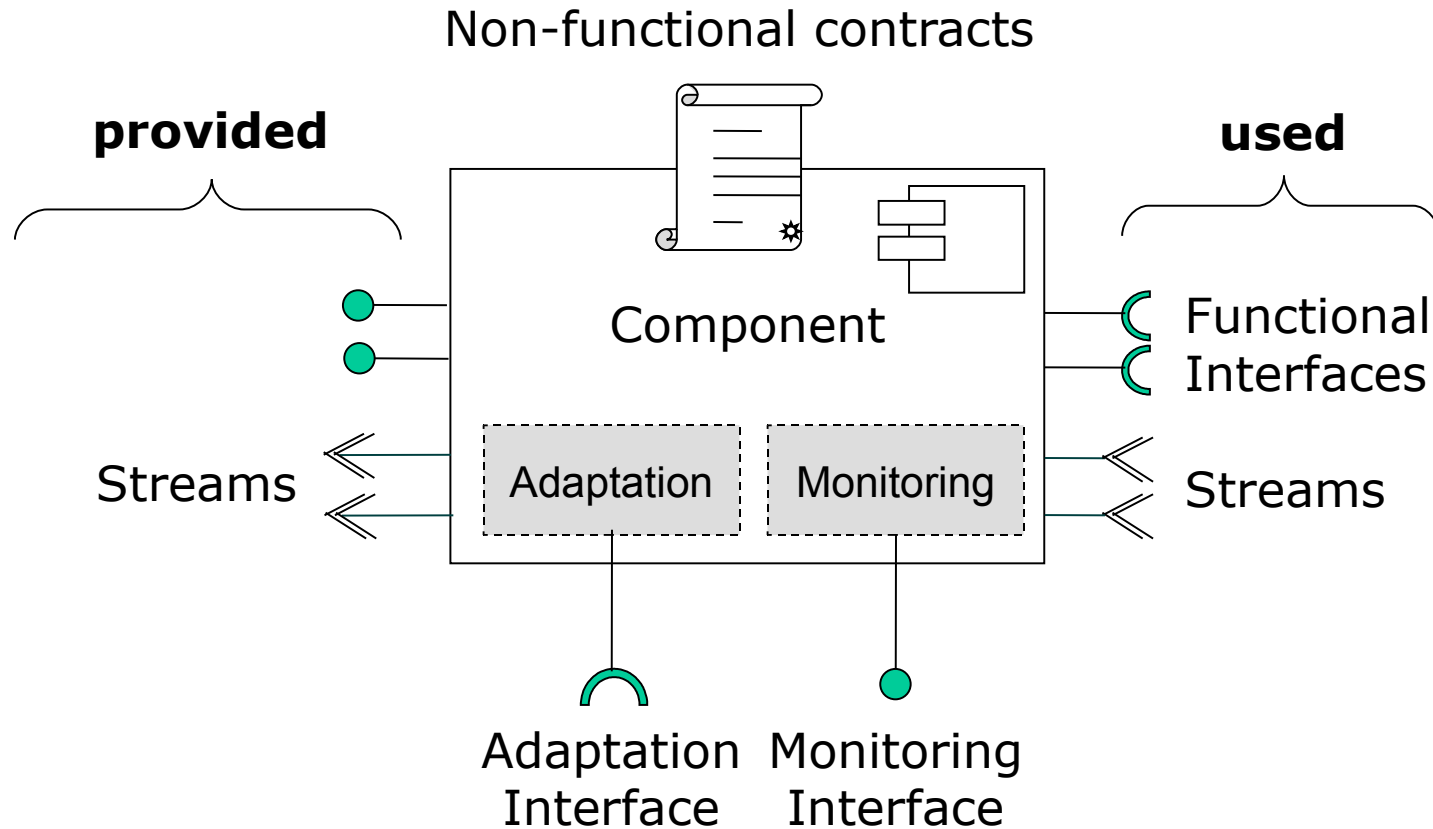
Instance connection

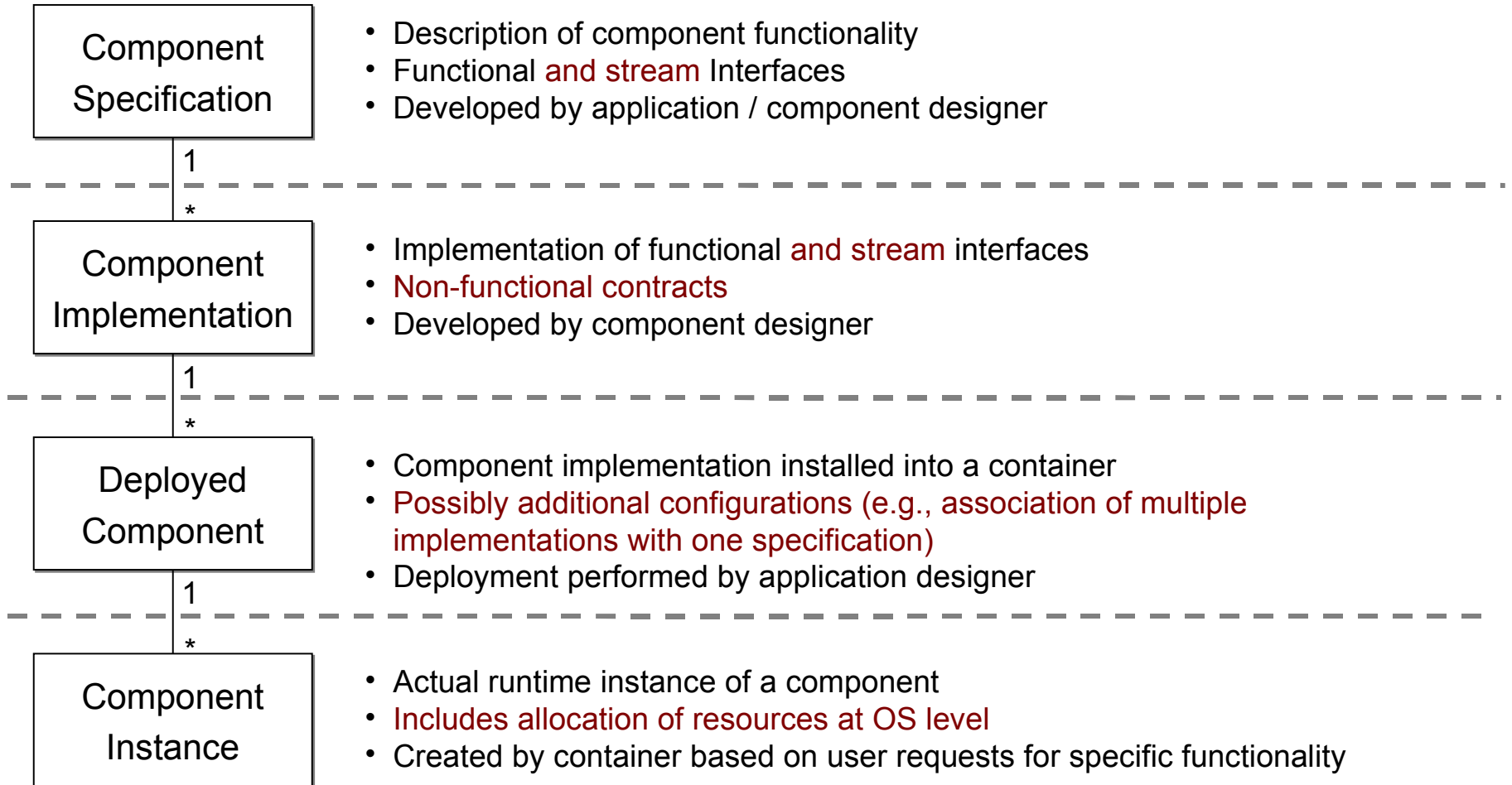
Objectives:

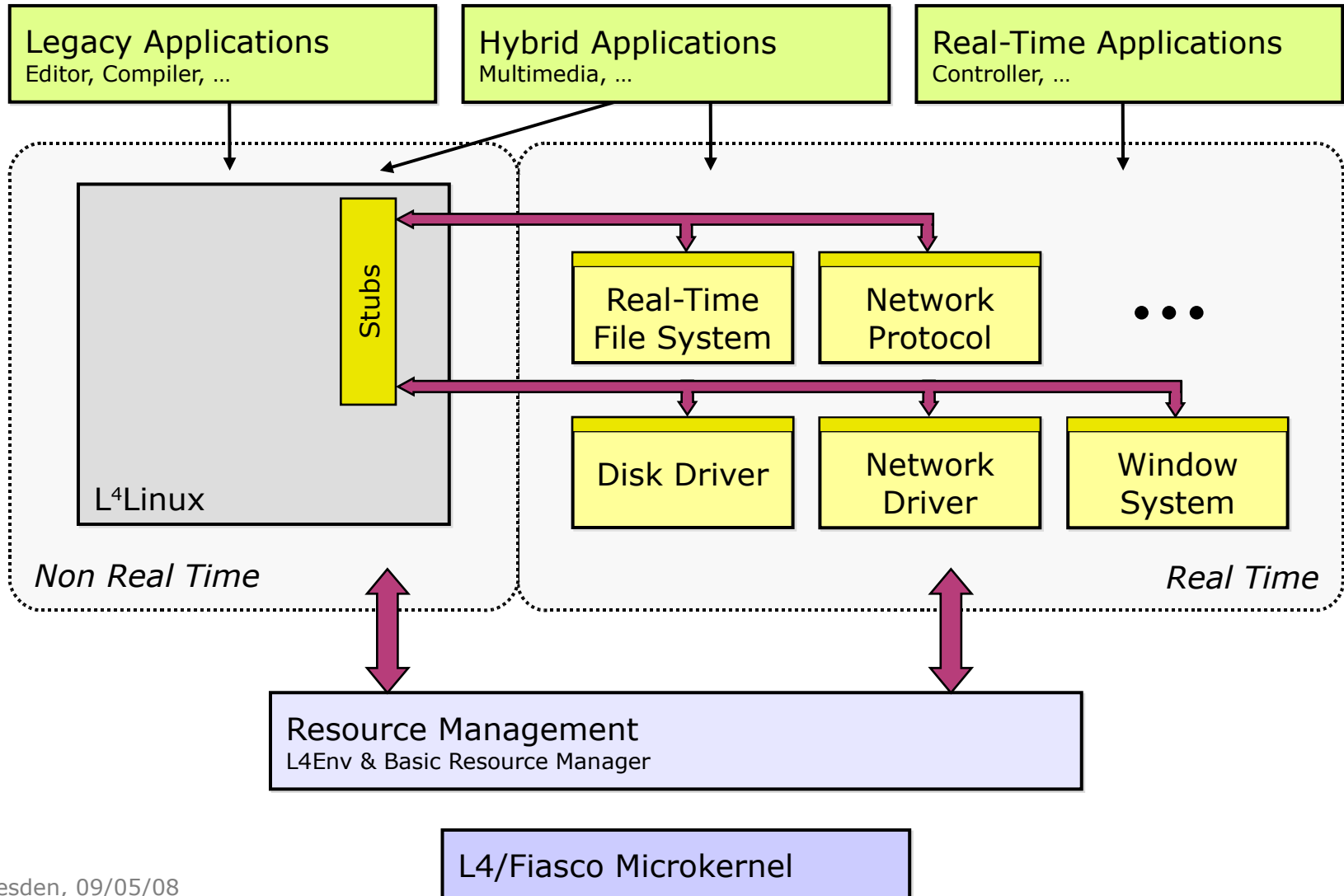
- full fledged components: specs, repositories, containers
- hard real-time + soft real-time + non-real-time
- adaptation
- application-specific description of non-functional properties

Simplifications:

- streams only (only few thoughts on other interfaces)
- no dependencies except stream concatenation
- pipelining assumed
- simple scheduling

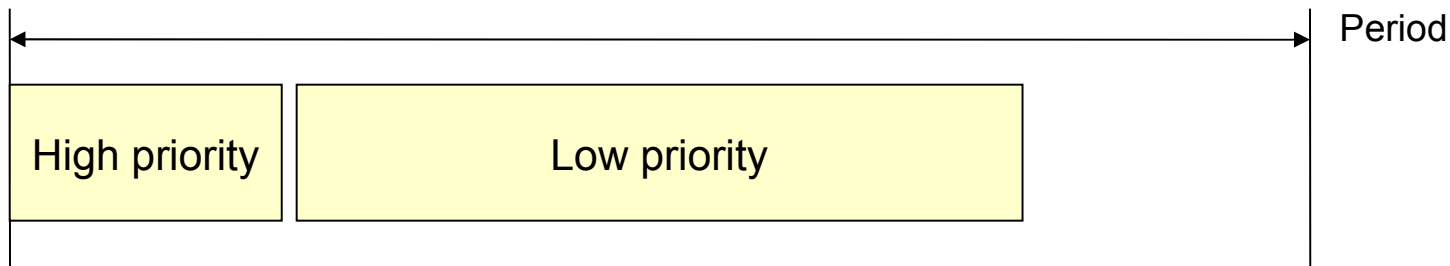







```

while (true) {
    next_period();
    // Mandatory part
    next_reservation();
    // Optional part
}
    
```

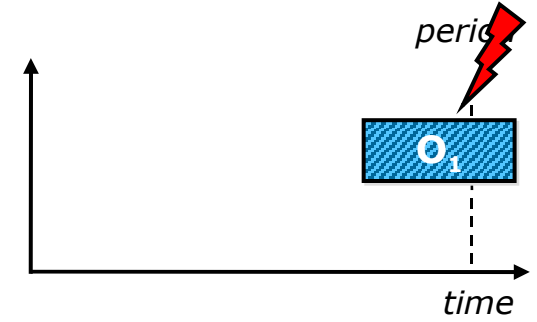
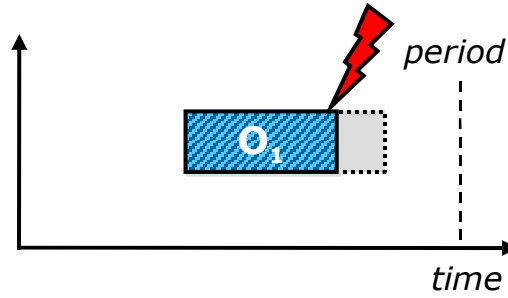
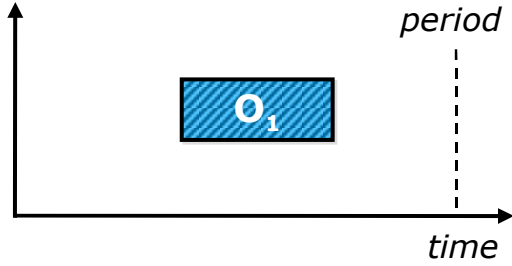


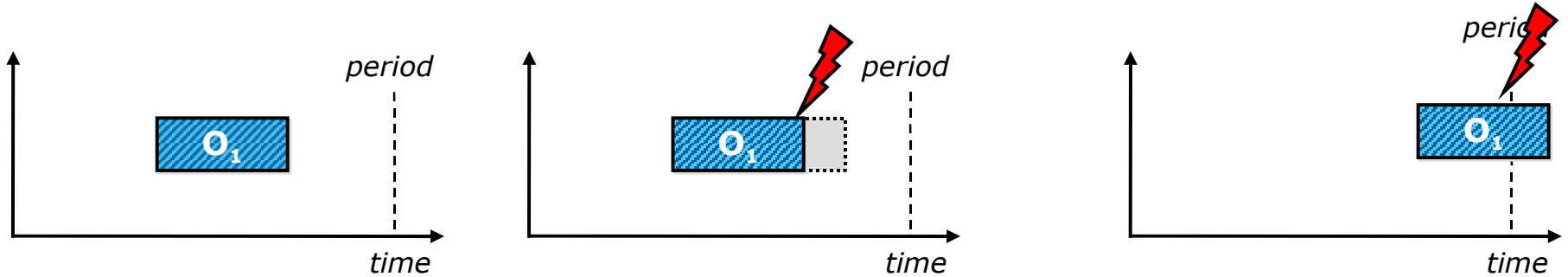
- **Periodic Processes**

- Receive a number of quanta of a certain priority per period

- **End of quantum < end of period (missed deadline) or still work to do after end of quantum (exceeded quantum)**

- Notification message

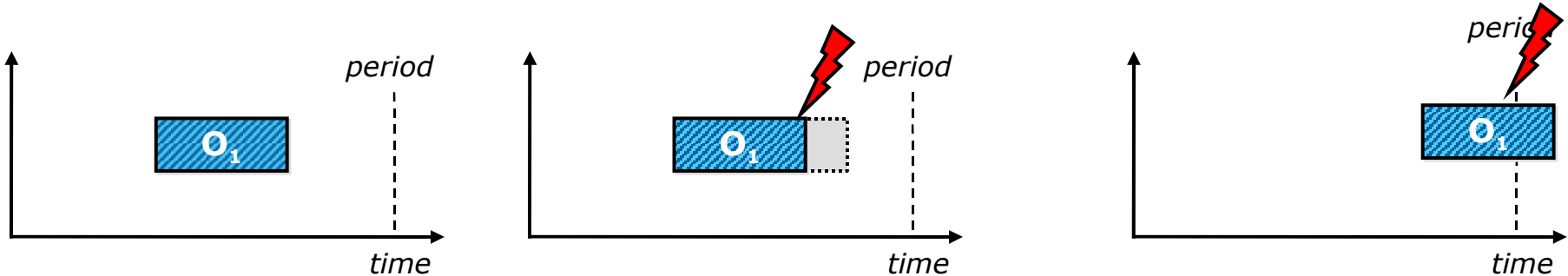




```

while (true) {
    message = receive_preemption_msg (theComponent, task_id);
    if ((message.type == MISSING_NEXT_RESERVATION) ||
        (message.type == MISSING_NEXT_PERIOD)) {
        run_optional = false;
    }
}

```

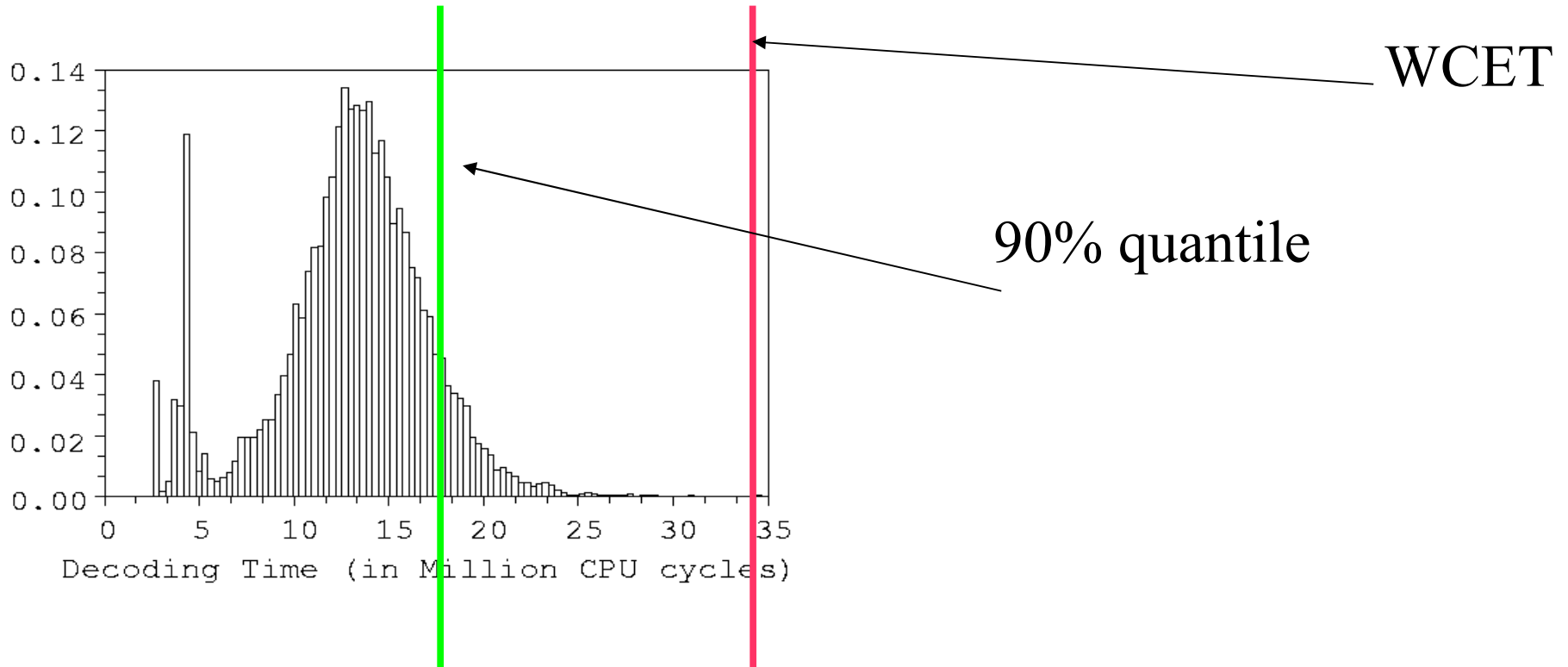


```

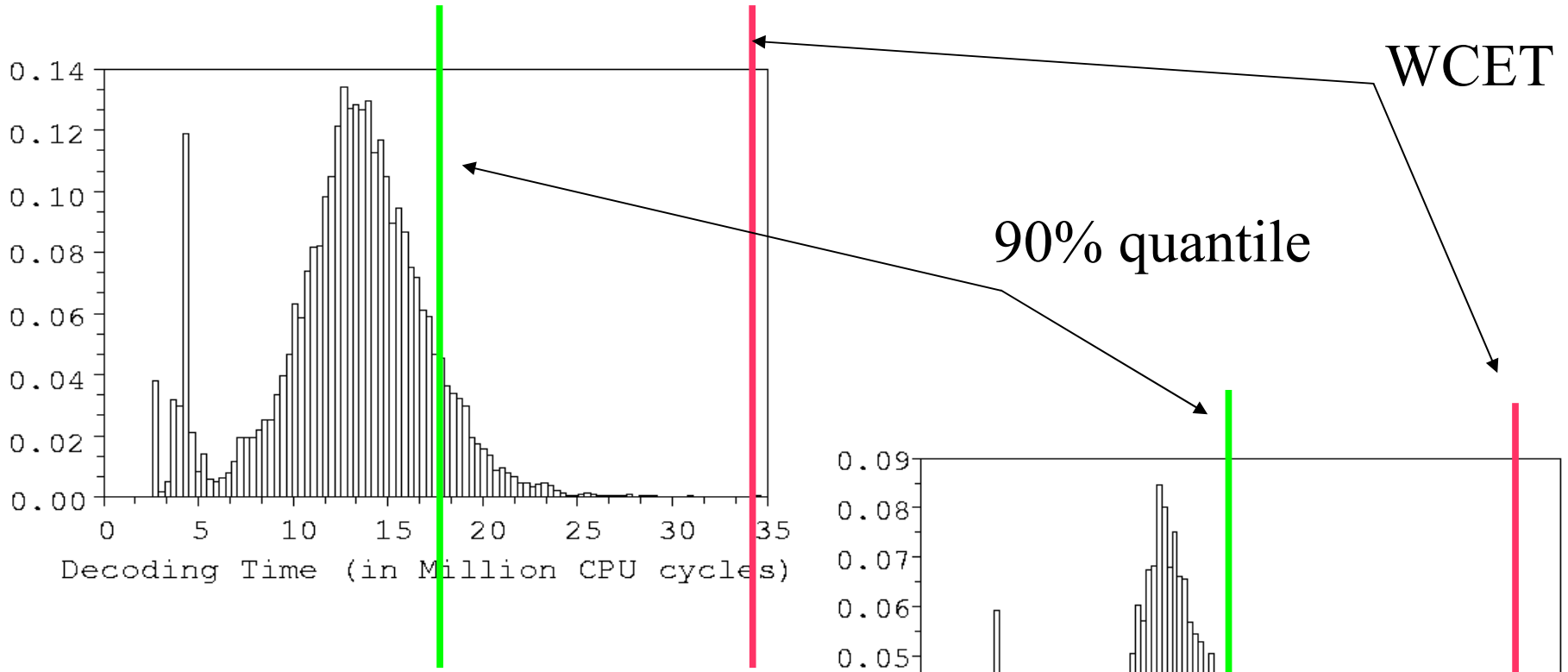
while (true) {
    message = receive_preemption_msg (theComponent, task_id);
    if ((message.type == MISSING_NEXT_RESERVATION) ||
        (message.type == MISSING_NEXT_PERIOD)) {
        run_optional = false;
    }
}
  
```

```

while (true) {
    next_period(); // Mandatory part
    next_reservation();
    if (run_optional){ // Optional part }
}
  
```

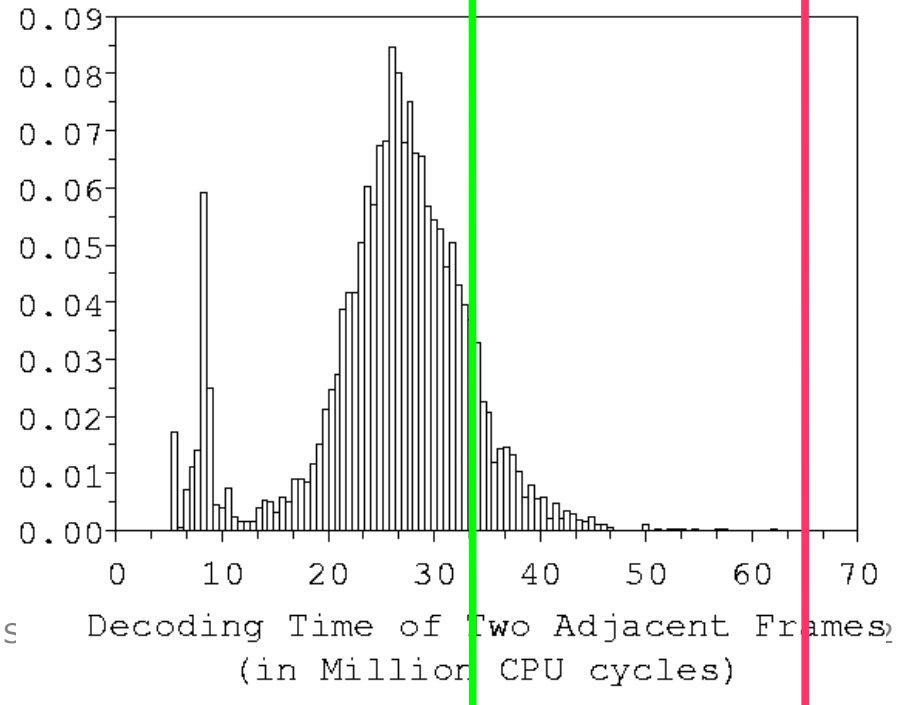


one frame

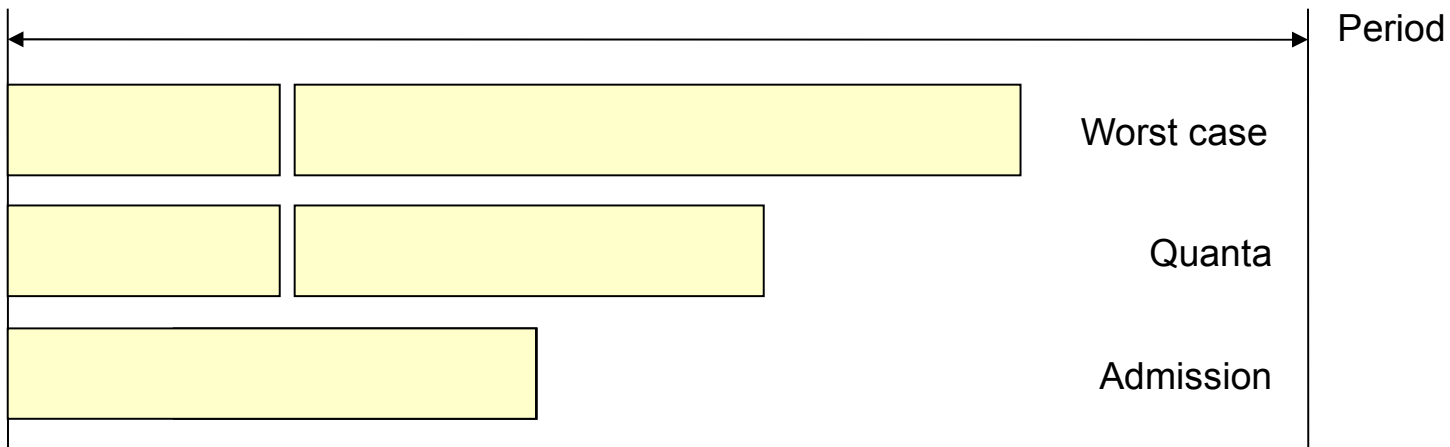


one frame

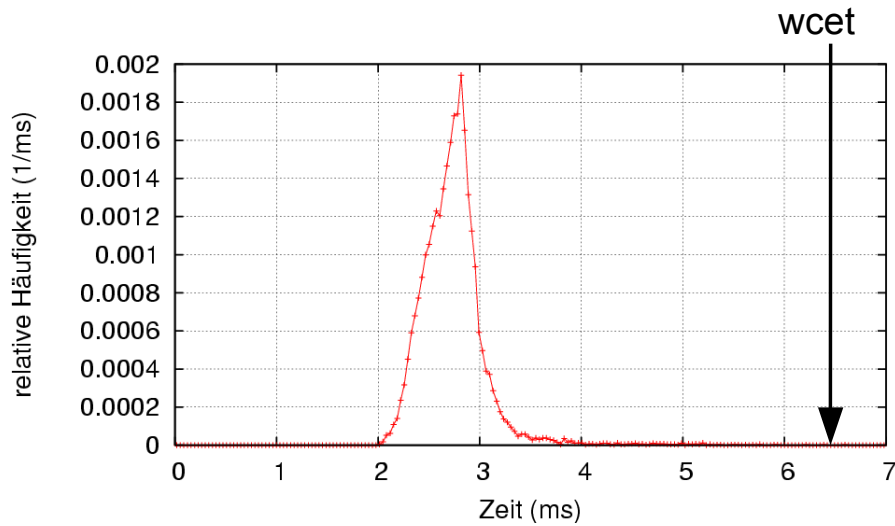
two frames



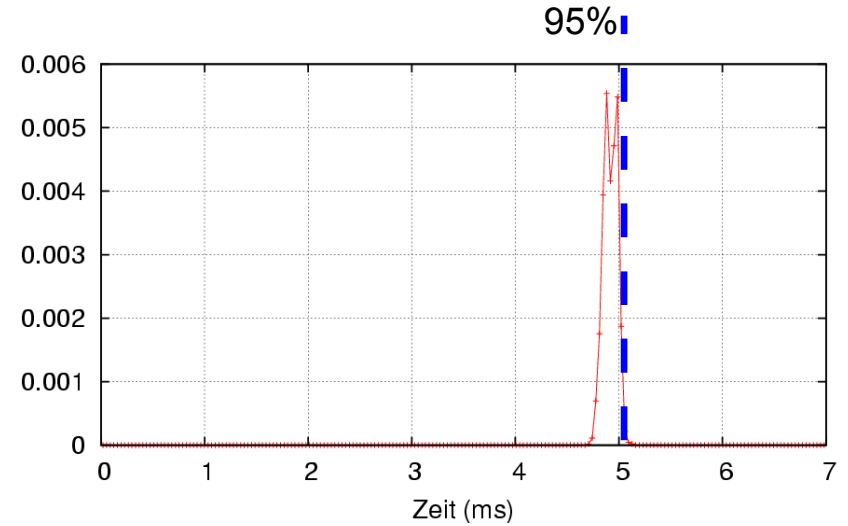
```
while (true) {  
    next_period();  
    decode  
}
```



- **On average, only partial quanta are used**
 - Controlled overbooking by the resource manager
 - Requires execution time distributions

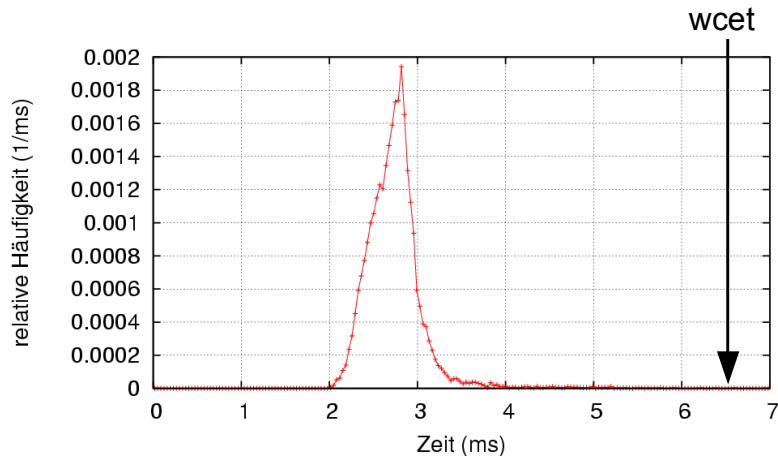


Mandatory Part



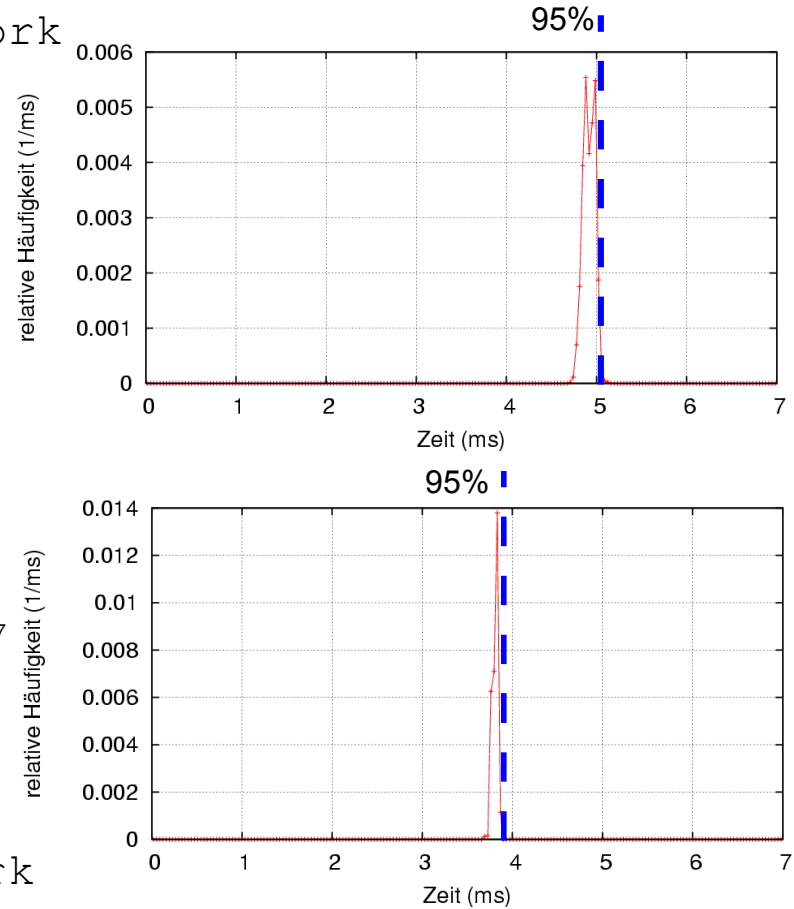
Optional Part

Optional Part **good_work**



Mandatory Part

Optional Part **ok_work**



```
profile decodingBehavior for VernerVideoDecoder {
  profile good_work {
    provides decoder_quality_q3;
    uses demuxer_speed_25fps;
    resources decoder_good_cpu and decoder_good_memory;
  }
  profile ok_work {
    provides decoder_quality_q1;
    uses demuxer_speed_25fps;
    resources decoder_ok_cpu and decoder_good_memory;
  }

  transition good_work -> ok_work {
    setPostProcessQuality (Quality.q1);
  }

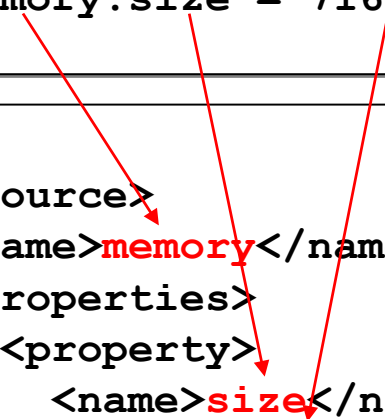
  ...
}
```

```
resource memory {
  quality_characteristic size {
    domain: numeric kilobyte;
  }
}

quality decoder_good_memory {
  memory.size = 7168; -- 7 MB
}
```

XML:

```
<resource>
  <name>memory</name>
  <properties>
    <property>
      <name>size</name>
      <value>7168</value>
    </property>
  </properties>
</resource>
```



XML simplified:

```
{ "memory",
  { "size", "7168" }
}
```

```
resource cpu {
  quality_characteristic task_quality {
    domain: numeric [0..100] percent;
  }
  quality_characteristic execution_time {
    domain: distribution;
  }
  quality_characteristic task {
    domain: tuple {
      task_quality,
      execution_time
    };
  }
  quality_characteristic mandatory : task {
    domain: tuple {
      task_quality,
      execution_time
    };
    invariant: task_quality = 100;
  }
  quality_characteristic optional : task {}
}
```

...

```
...
    quality_characteristic period {
        domain: numeric microseconds;
    }
    quality_characteristic demand {
        domain: tupel {
            period,
            mandatory,
            optional
        };
    }
}
```

```
quality decoder_good_cpu {  
    cpu.period = 40000;  
    cpu.mandatory.task_quality = 100;  
    cpu.mandatory.execution_time = "vdecoder_mand.dist";  
    cpu.optional.task_quality >= 95;  
    cpu.optional.execution_time = "vdecoder_opt_q3.dist";  
}
```

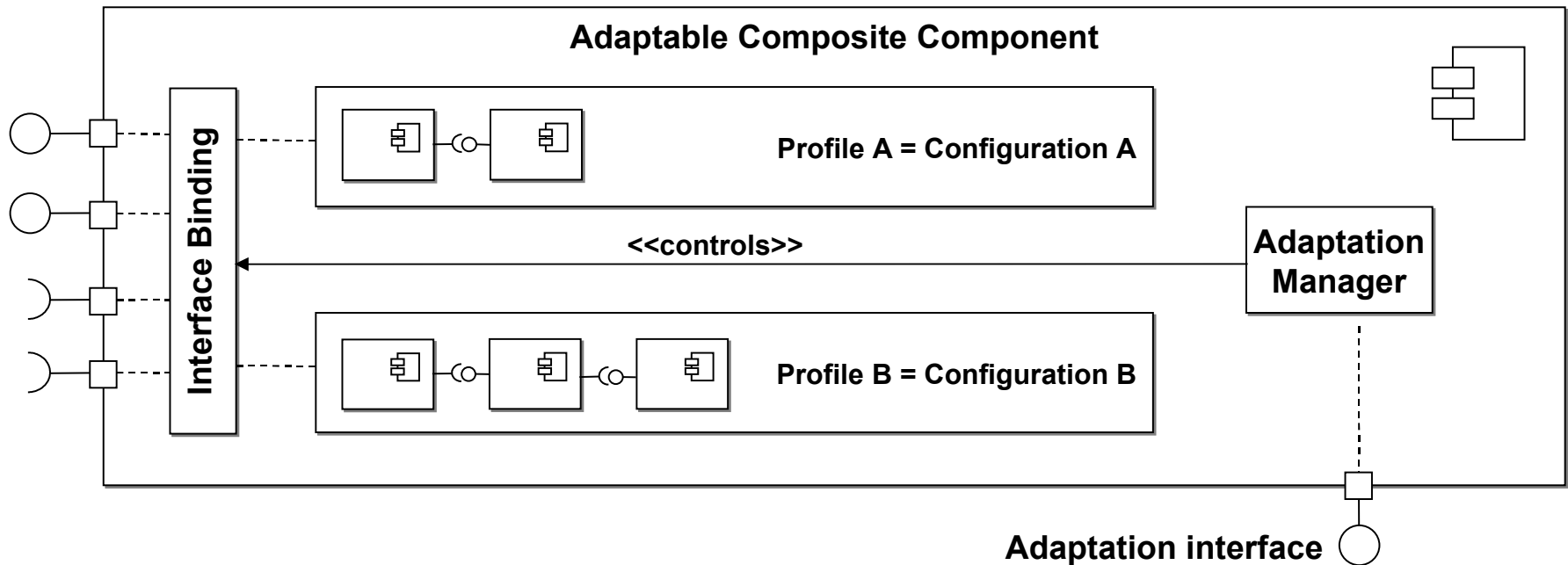
XML simplified:

```
{ "cpu",  
  { "period", "40000" },  
  { "mandatory.task_quality", "100" },  
  { "mandatory.execution_time", "vdecoder_mand.dist" },  
  { "optional.task_quality", "95" },  
  { "optional.execution_time", "vdecoder_opt_q3.dist" }  
}
```

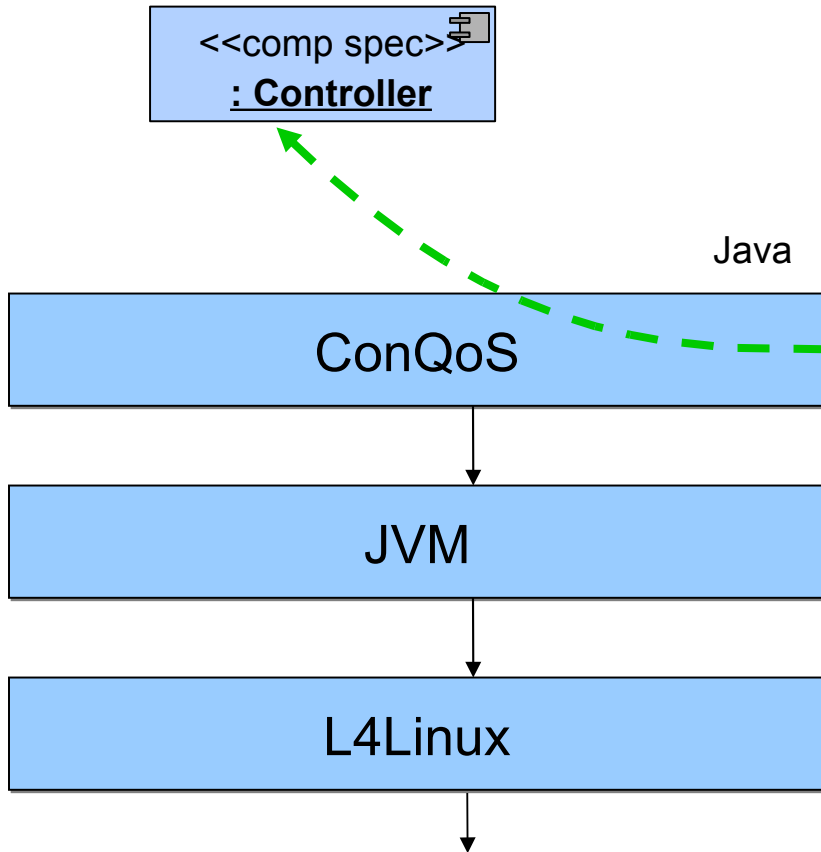
```
quality decoder_ok_cpu {  
    cpu.period = 40000;  
    cpu.mandatory.task_quality = 100;  
    cpu.mandatory.execution_time = "vdecoder_mand.dist";  
    cpu.optional.task_quality >= 95;  
    cpu.optional.execution_time = "vdecoder_opt_q1.dist";  
}
```

XML simplified:

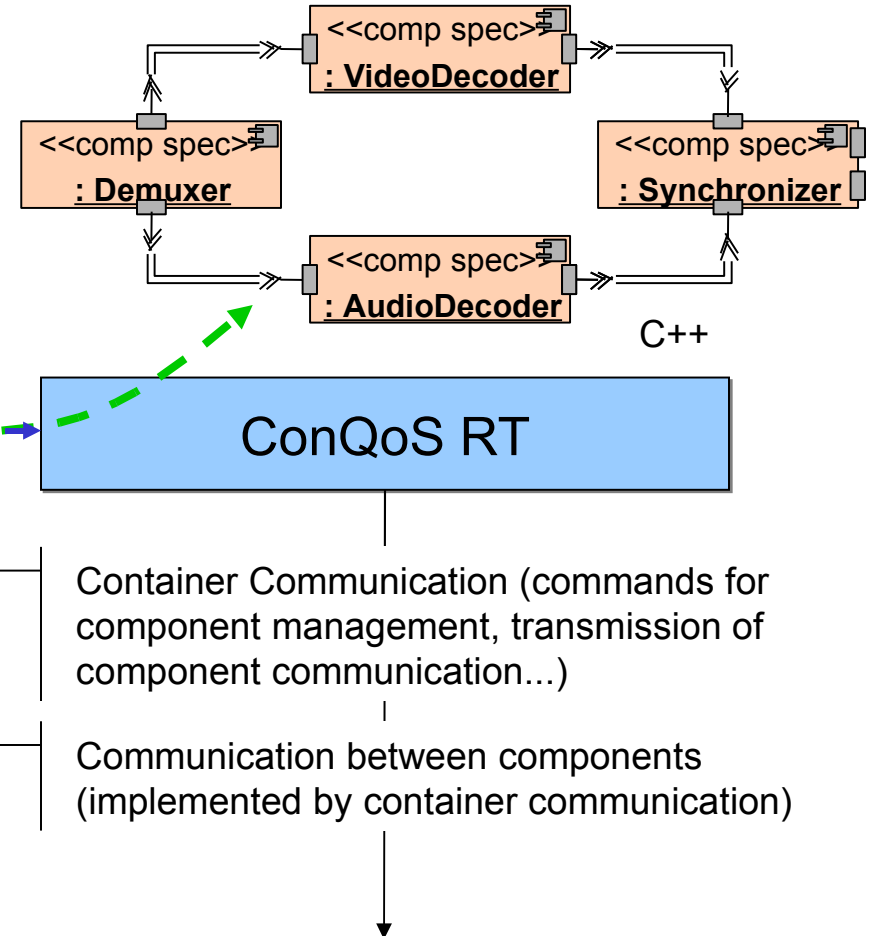
```
{ "cpu",  
  { "period", "40000" },  
  { "mandatory.task_quality", "100" },  
  { "mandatory.execution_time", "vdecoder_mand.dist" },  
  { "optional.task_quality", "95" },  
  { "optional.execution_time", "vdecoder_opt_q1.dist" }  
}
```



Not QoS-aware



QoS-aware



- **Prediction-Enabled Component Technology (PECT)**
 - Software Engineering Institute at Carnegie Mellon University, USA
 - Components are transformed into task structure for execution
 - Components not visible at run time
 - No adaptation support
- **Safe-CCM**
 - PROGRESS institute at Mälardalen University, Sweden
 - Component model for embedded systems / automotive
 - Components are transformed into run-time structures → No components at run time
- **Real-Time CORBA (RT-CORBA)**
 - Object Management Group
 - Extension at the container level only
 - Real-time support must be imperatively implemented for each application
- **Framework for real-time embedded systems based on contracts (Frescor)**
 - Ongoing European project
 - Some parallels to presented approach, much more ambitious

- Ronald Aigner
- Steffen Göbel
- Christoph Pohl
- Martin Pohlack
- Simone Röttger
- Claude-Joachim Hamann
- Heinrich Hußmann

Operating Systems Group
<http://os.inf.tu-dresden.de/>

Software Engineering Group
<http://st.inf.tu-dresden.de/>

Computer Networks Group
<http://rn.inf.tu-dresden.de/>

Hermann Härtig, Steffen Zschaler, Martin Pohlack, Ronald Aigner, Steffen Göbel, Christoph Pohl, and Simone Röttger: *Enforceable Component-Based Realtime Contracts – Supporting Realtime Properties from Software Development to Execution*.

In **Springer Real-Time Systems Journal**, 35(1)2007, Springer, January, 2007.

DOI: 10.1007/s11241-006-9002-1

Claude-Joachim Hamann and Steffen Zschaler: *Scheduling Real-Time Components Using Jitter-Constrained Streams*. Journal of Object Technology, Special Issue on Quality of Service Management. 6(11)2007, http://www.jot.fm/issues/issue_2007_12/

Simone Röttger and Steffen Zschaler: *Tool Support for Refinement of Non-functional Specifications*. Journal on Software and Systems Modeling (SoSyM) 6(2)2007, Springer.

Steffen Göbel, Christoph Pohl, Ronald Aigner, Martin Pohlack, Simone Röttger, Steffen Zschaler: *The COMQUAD component container architecture*. J. Magee, C. Szyperski, and J. Bosch eds., 4th Working IEEE/IFIP Conference on Software Architecture (WICSA), pp. 315-318, Oslo, Norway. IEEE, 2004.

Steffen Göbel, Christoph Pohl, Simone Röttger, and Steffen Zschaler: *The COMQUAD Component Model – Enabling Dynamic Selection of Implementations by Weaving Non-functional Aspects*. Int'l Conference on Aspect-Oriented Software Development (AOSD'04), Lancaster. ACM, 2004.

Simone Röttger and Steffen Zschaler: *CQML +: Enhancements to CQML*. J.-M. Bruel, ed., Proc. 1st Int'l Workshop on Quality of Service in Component-Based Software Engineering, Toulouse, France, pages 43-56. Cépaduès- Éditions, 2003.

Jan Øyvind Aagedal. *Quality of Service Support in Development of Distributed Systems*. PhD thesis, University of Oslo, 2001.

- No fundamental difficulties encountered
- Communication between RTOS and SWE worlds can be difficult