

A comparative study of FIACRE and TASM to define AADL real time concepts

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Outline

- 1 Motivation
- 2 Background
 - AADL
 - Target formalisms
- 3 Comparative Modeling
 - FIACRE
 - TASM
- 4 Conclusion

TOPCASED

(Meta)-modeller

Modelling languages

Editors



Model Transformations

ATL, Kermeta

Intermediate language



Compilers

Translation

Model-Checkers
Simulators



Motivation

- Formal expression of Architecture Analysis & Design Language (AADL) semantics
- Analysis of AADL models
 - end-to-end flow latency
 - schedulability
 - buffer overflows
 - users properties



Outline

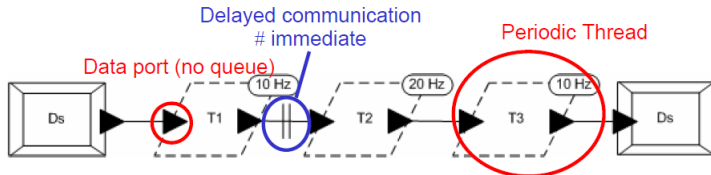
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AADL

- Hierarchical definition of hardware / software systems
- Real-time models
- communicating threads : port based or shared memory based communications
 - Periodic or sporadic threads
 - Immediate and delayed communications
 - Execution time of tasks (WCET)



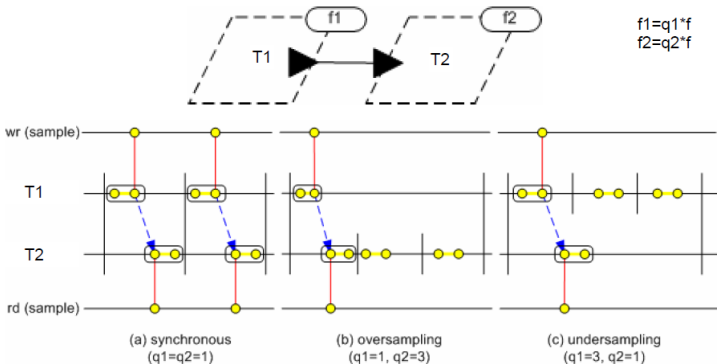
Synchronous subset of AADL



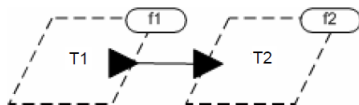
- Periodic threads
- data port communication
- immediate and delayed communication

Immediate Communications

AADL implementation of instantaneous communications of the synchronous model

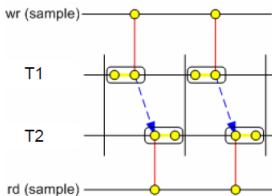


Immediate Communications



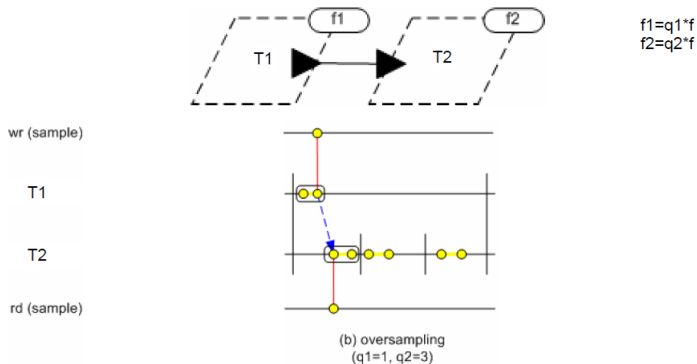
$$f1=q1*f$$

$$f2=q2*f$$

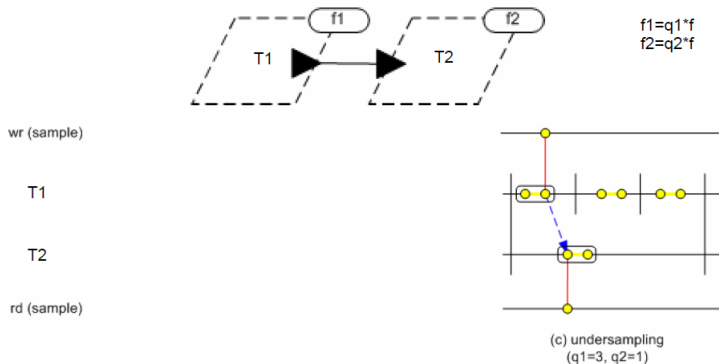


(a) synchronous
 $(q1=q2=1)$

Immediate Communications

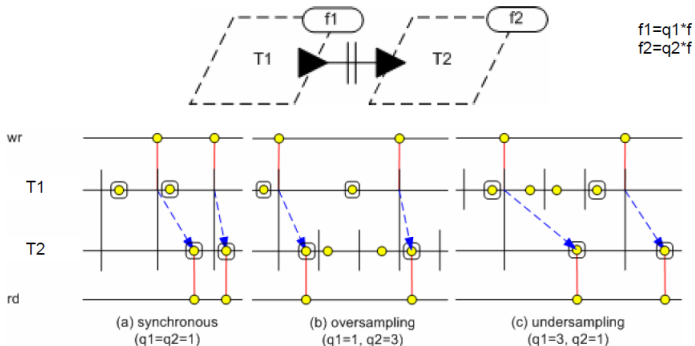


Immediate Communications



Delayed Communications

AADL implementation of the delay operator of the synchronous model



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Comparison

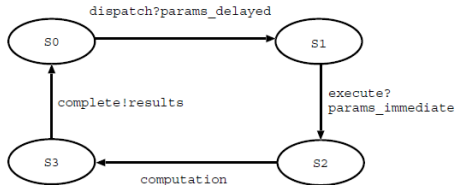
	Communication	Synchronization model	Time model	Resource management
FIACRE	port/shared data	Communicating Sequential Processes	Timed Transition Systems implicit	no
TASM	shared data	Calculus Communication Systems	continuous implicit	yes

Outline

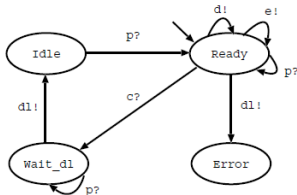
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Modeling periodic thread execution in FIACRE



Thread automaton



Scheduler automaton

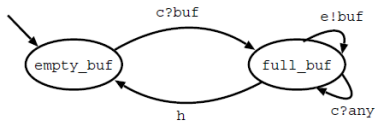
```

process P1 [dispatch1 : in none,
            execute1 : in none,
            computation1 : in none,
            completion1 : out int] is
  states s0, s1, s2, s3
  var x : data
  init to s0
  from s0 dispatch1; to s1
  from s1 execute1; to s2
  from s2 computation1; to s3
  from s3 completion1!x; to s0
  
```

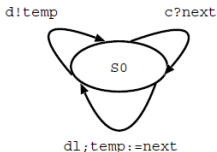
```

process P2 [dispatch2 : in int,
            execute2 : in dataOption,
            computation2 : in none,
            completion2 : out none] is
  states s0, s1, s2, s3
  var x : data, o : dataOption
  init to s0
  from s0 dispatch2?x; to s1
  from s1
  select
    execute2?None; to s2
    [] execute2?Some x; to s2
  end
  from s2 computation2; to s3
  from s3 completion2; to s0
  
```


Modeling communication semantics in FIACRE



Immediate communication



Delayed communication

```
process Buf_immediate [e : out dataOption,
                      c : in int, h : none]is
  states empty_buf, full_buf, wait
  var buf : int := 0
  init to empty_buf
  from empty_buf
    select c?buf; to full_buf
  end
  from full_buf
    select c?any; to full_buf
    [] e!buf; to full_buf
    [] h; to empty_buf
  end
end
```

```
process Buf_delayed [d : out int,
                    c : in int, dl : out none]is
  states s0
  var temp : int := 0,
      next : int := 0
  init to s0
  from s0
    select c?next; to s0
    [] d!temp; to s0
    [] dl; temp := next; to s0
  end
end
```

Modeling communication semantics in FIACRE

component sys is

```
port t1 : none in [2,2], t2 : none in [3,3], t3 : none in [4,4], tmp : none in [6,6],  
    e1 : none in [0,0], e2 : dataOption in [0,0], e3 : dataOption in [0,0],  
    w1 : none in [0,1], w2 : none in [0,1], w3 : none in [0,1],  
    d1 : none in [0,0], d2 : int in [0,0], d3 : int in [0,0],  
    c1 : int in [0,0], c2 : none in [0,0], c3 : none in [0,0],  
    dl1 : none in [2,2], dl2 : none in [3,3], dl3 : none in [4,4]
```

priority

```
c1>t1, c2>t2, c3>t3,  
t1|t2|t3>d1|d2|d3,  
d1>d2, d1>d3,  
d1|d2|d3>e1|e2|e3,  
e1>e2
```

par

```
P1[d1, e1, w1, c1] || P2[d2, e2, w2, c2] || P2 [d3, e3, w3, c3]  
|| Buf_immediate[e2, c1, tmp]  
|| Buf_delayed[d3, c1, dl1]  
|| scheduler[t1, t2, t3, c1, c2, c3, d1, d2, d3, e1, e2, e3, dl1, dl2, dl3]  
end
```

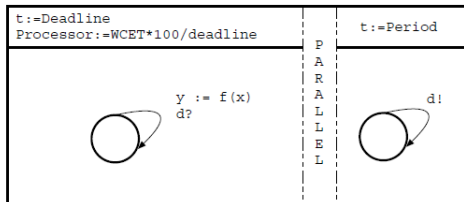


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Modeling periodic thread execution in TASM



Periodic Thread

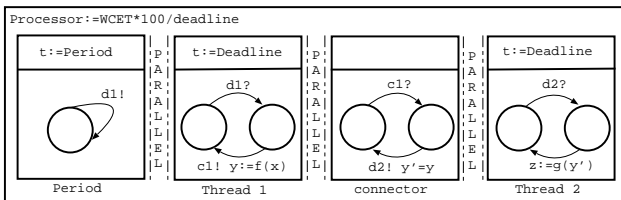
MAIN MACHINE: *Period*

```
Rule: period
{ t := period;
  if Nextdispatch = false then
    Nextdispatch := true;
    d!;
}
```

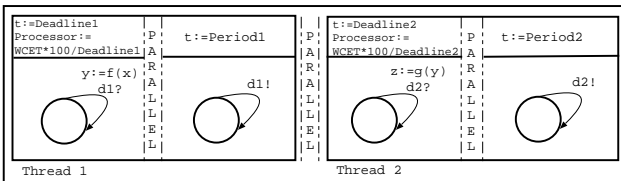
MAIN MACHINE: *Execution*

```
Rule: execution
{ t := [0, deadline];
  processor := WCET*100 / deadline;
  if Complete = false then
    Complete := true;
    d?;
}
```

Modeling communication semantics in TASM



Immediate communication



Delayed communication



Conclusion

- Schemas for expressing some real-time concepts in FIACRE and TASM.
 - AADL periodic threads.
 - AADL delayed and immediate communications
 - FIACRE powerful for real time - verification through timed Petri nets.
 - TASM powerful abstraction for resource management (including time) - verification through priced timed automata.
- ~> better understanding of AADL.
- ~> ideas for defining FIACRE extensions.

