

# WCET-aware Software Based Cache Partitioning for Multi-Task Real-Time Systems

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# Outline

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2. Software Based Cache partitioning
3. WCET-aware Cache Partitioning
4. ILP Formulation
5. Workflow
6. Results
7. Conclusion

# WCET-aware Cache Partitioning

## Problem:

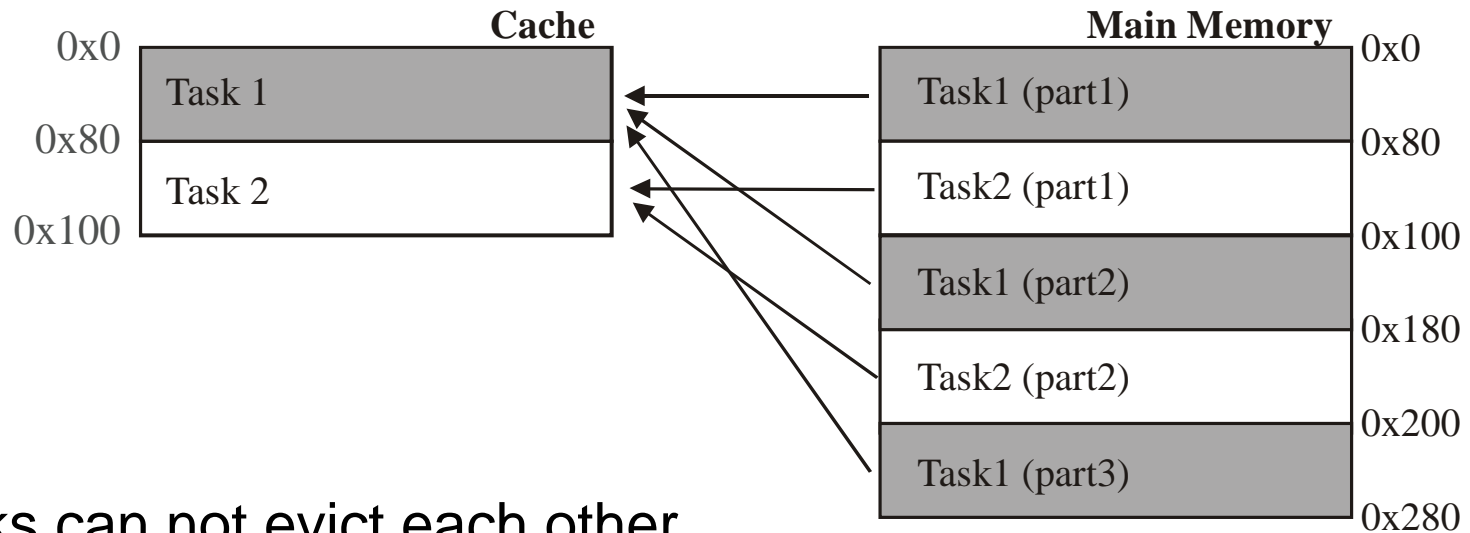
- Caches are a source of unpredictability
- Behaviour in general unpredictable in systems performing preemptive scheduling
- Different tasks could replace each other in cache

## Idea:

- Divide the cache into partitions
- Assign one task per partition
- Tasks can not replace each other

# Software Based Cache Partitioning

- Exploit the cache's modulo addressing function
- Distribute tasks in address space
- Ensure mapping to particular cache lines

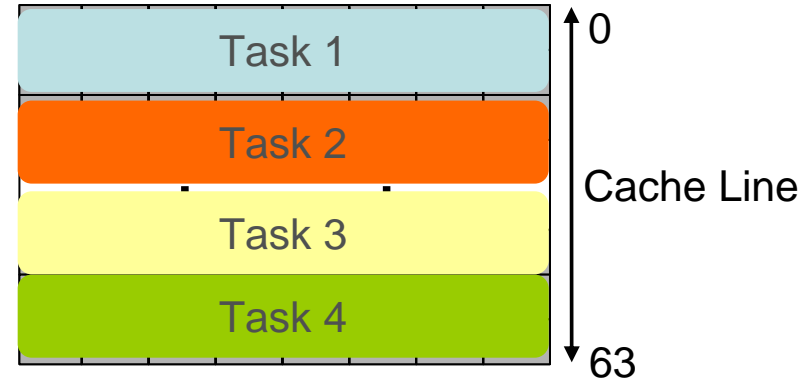


- ✓ Tasks can not evict each other
- Additional jumps have to be inserted, branches corrected

# WCET-aware Cache Partitioning

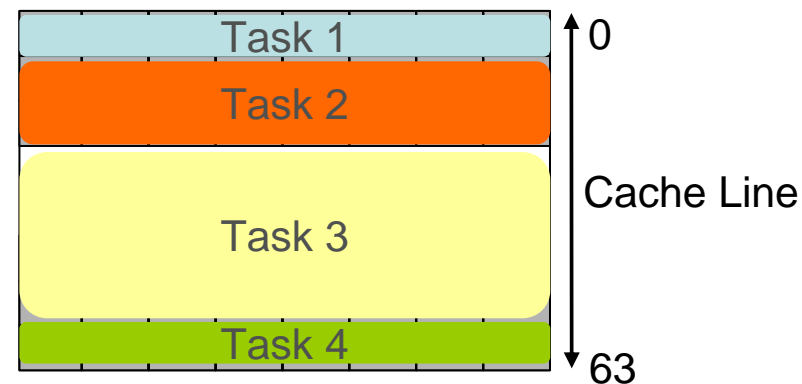
## Greedy approach\*

- Partition size depends on task's code size
- Example: 4 tasks with the same code size



## Better

- Employ an ILP-model to select optimal cache size for every task
- Take execution frequencies into account



[\* Frank Mueller, 1995: Compiler Support for Software-Based Cache Partitioning]

# ILP Formulation

$T$  : set of periodically scheduled tasks  $t_1 \dots t_m$

$P$  : set of partition sizes  $p_1 \dots p_j$

$$x_{ij} = \begin{cases} 1, & \text{if } t_i \text{ assigned to } p_j \\ 0, & \text{else} \end{cases}$$

$WCET_{ij}$  :  $t_i$ 's WCET if assigned to  $p_j$

$I$  : scheduling interval

$c_i$  : task  $t_i$  is executed exactly  $c_i$  times during  $I$

$\Rightarrow |I|$  is the Hyperperiod of  $T$  (LCM of the tasks' periods)

# ILP Formulation

Each task must have a partition assigned:

$$\forall i = 1..m : \sum_{j=1}^n x_{ij} = 1$$

Keep track of the cache size:

$$\sum_{i=1}^m \sum_{j=1}^n x_{ij} * p_j \leq S$$

# ILP Formulation

A tasks WCET is determined:

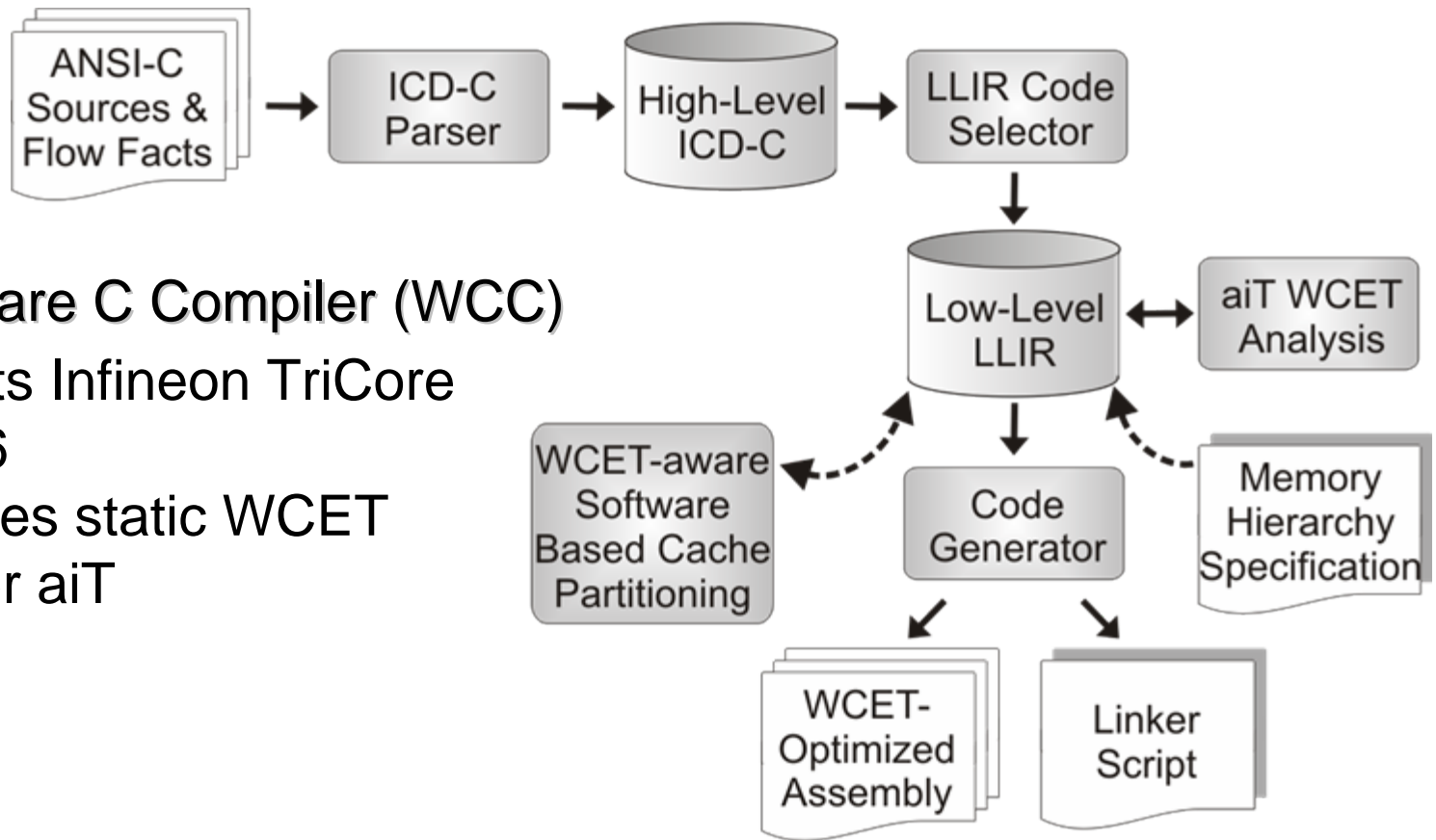
$$WCET(T_i) = \sum_{j=1}^n x_{ij} * WCET_{ij}$$

Objective function to minimize:

$$WCET = \sum_{i=1}^m \sum_{j=1}^n x_{ij} * c_i * WCET_{ij}$$



# Workflow



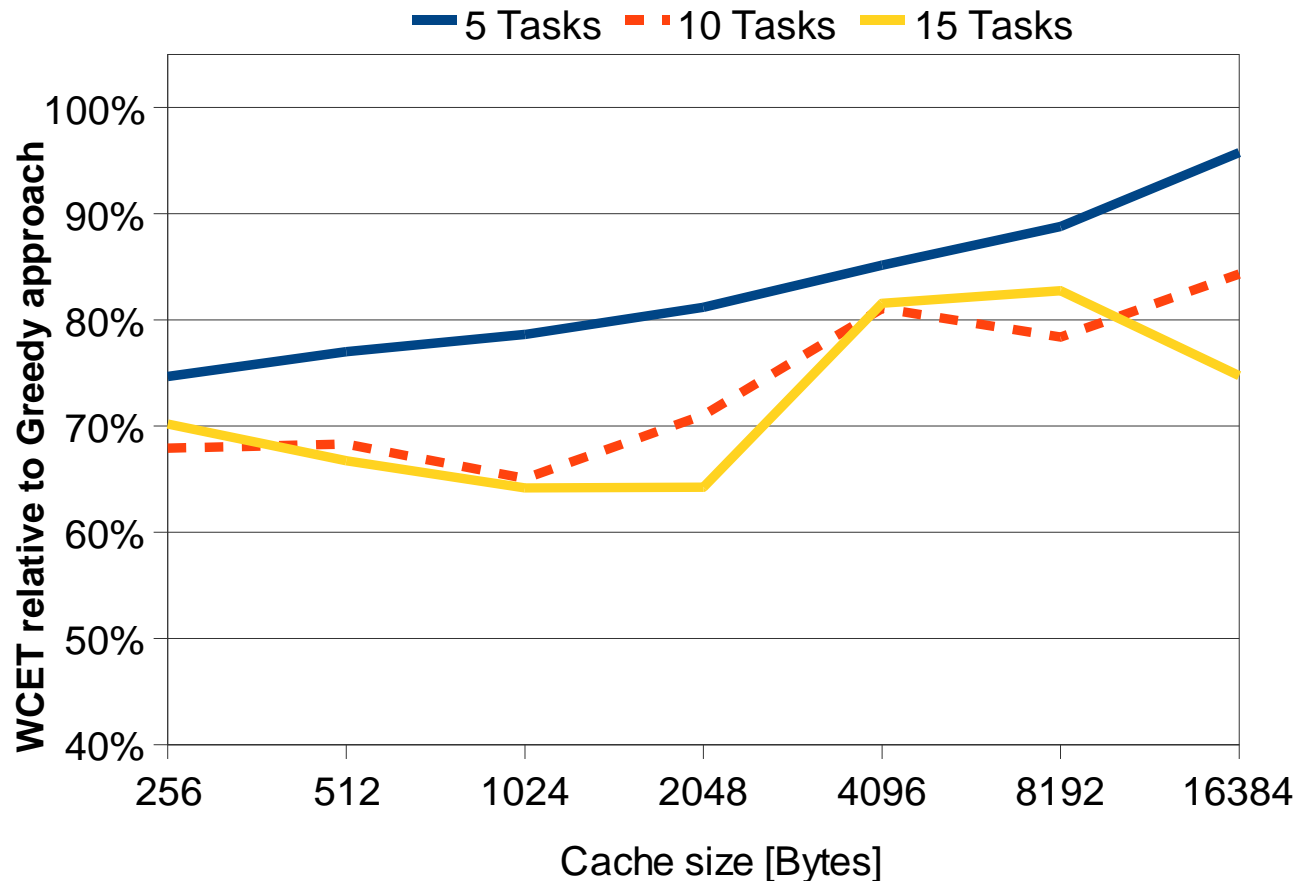
## WCET-aware C Compiler (WCC)

- Supports Infineon TriCore TC1796
- Integrates static WCET analyzer aiT

# Results: UTDSP

Average of 100 sets of randomly selected tasks:

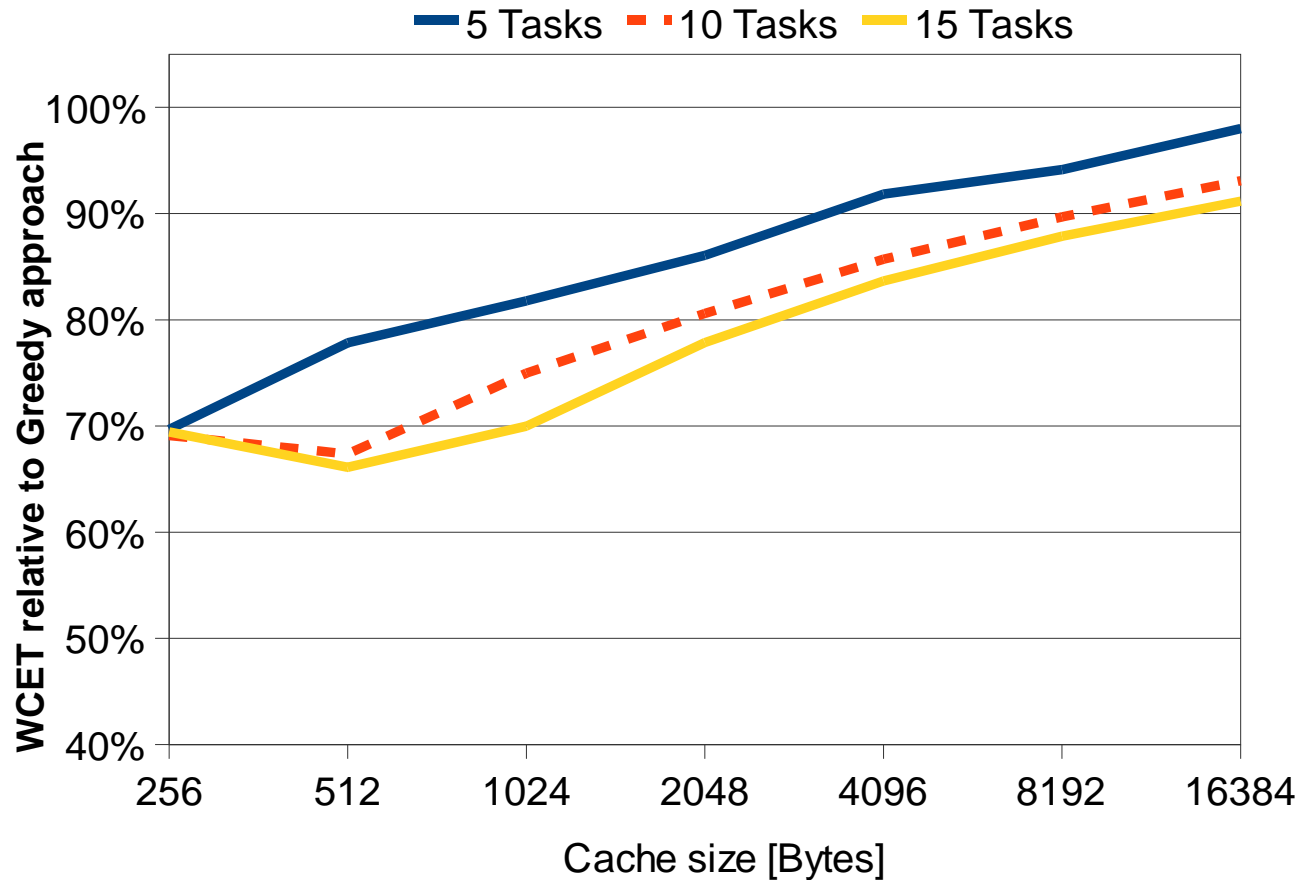
- 5 tasks: ~8kB
- 10 tasks: ~18kB
- 15 tasks: ~26kB



# Results: MRTC

Average of 100 sets of randomly selected tasks:

- 5 tasks: ~6kB
- 10 tasks: ~12kB
- 15 tasks: ~19kB



## Conclusion

- WCET-driven Cache Partitioning presented
- Employed an ILP to select optimal partition sizes w.r.t. the overall system's WCET
- Partitioning introduces predictability for preemptive scheduled systems
- Average WCET reduction of 12% (5 tasks) up to 19% (15 tasks) compared to greedy approach

## Future Work

- Tightly coupling of offline schedulers
- Take task dependencies into account

# Thank you for your attention!

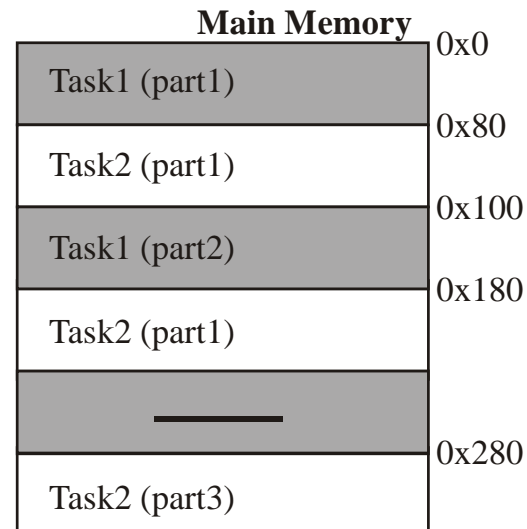


Questions?

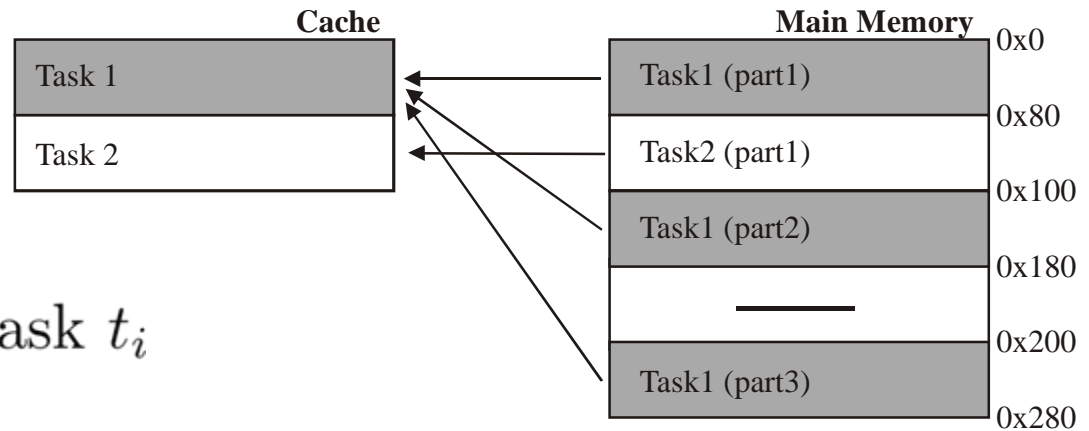
# Distribution of Code

- Achieved by exploiting the linker
- Each portion is assigned to its own section
- Example linker script for two tasks:

```
.text: {
  _text_begin = .;
  *(.task_part1)
  . = _text_begin + 0x80;
  *(.task2_part1)
  . = _text_begin + 0x100;
  *(.task1_part2)
  . = _text_begin + 0x180;
  *(.task2_part2)
  . = _text_begin + 0x280;
  *(.task2_part3)
} > PFLASH-C
```



# Memory usage



$s(t_i)$  : size of task  $t_i$

$p(t_i)$  : partition size of task  $t_i$

$$\#partitions(t_i) = \frac{s(t_i)}{p(t_i)}$$

$$S_{Flash} \geq S_{Cache} * \max(\#partitions(t_i))$$

$$S_{waste} = S_{Flash} - \sum_{i=1}^n s(t_i)$$

# Optimization Time

- Host machine: Dual Xeon L5420 @ 2.50GHz
- Using a single core
- Complete workflow consists of:
  - Compilation : up to 3 minutes
  - Analysis : up to 1 hour / task
  - Optimization: up to 1 minute