

Modeling, Analysis, and Synthesis of Quantitative System Requirements

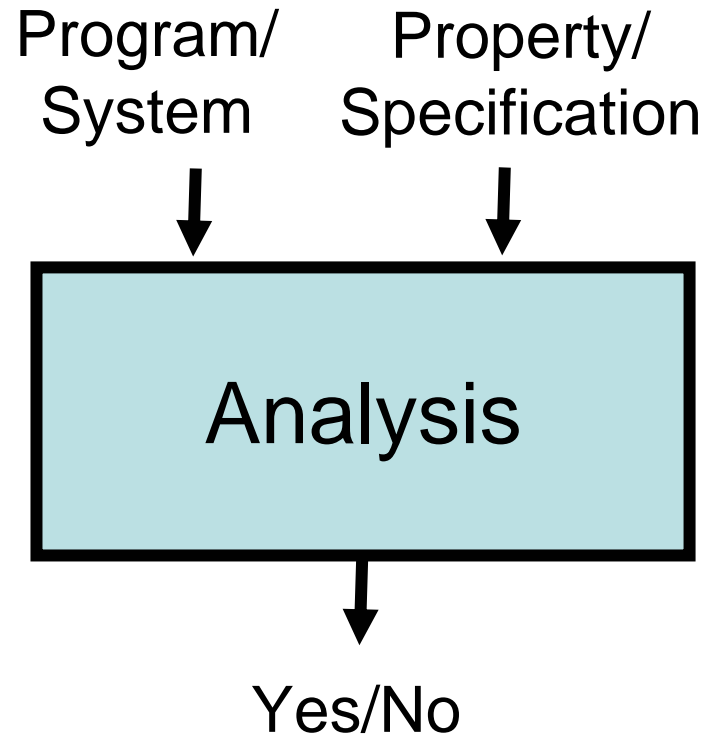
Tom Henzinger
IST Austria

Joint work with Krishnendu Chatterjee and Laurent Doyen.

Outline

- 1 A Quantitative Systems Theory
- 2 Some Basic Open Problems
- 3 Some Promising Directions

Boolean Systems Theories



Boolean Systems Theories

Program/
System Property/
 Specification

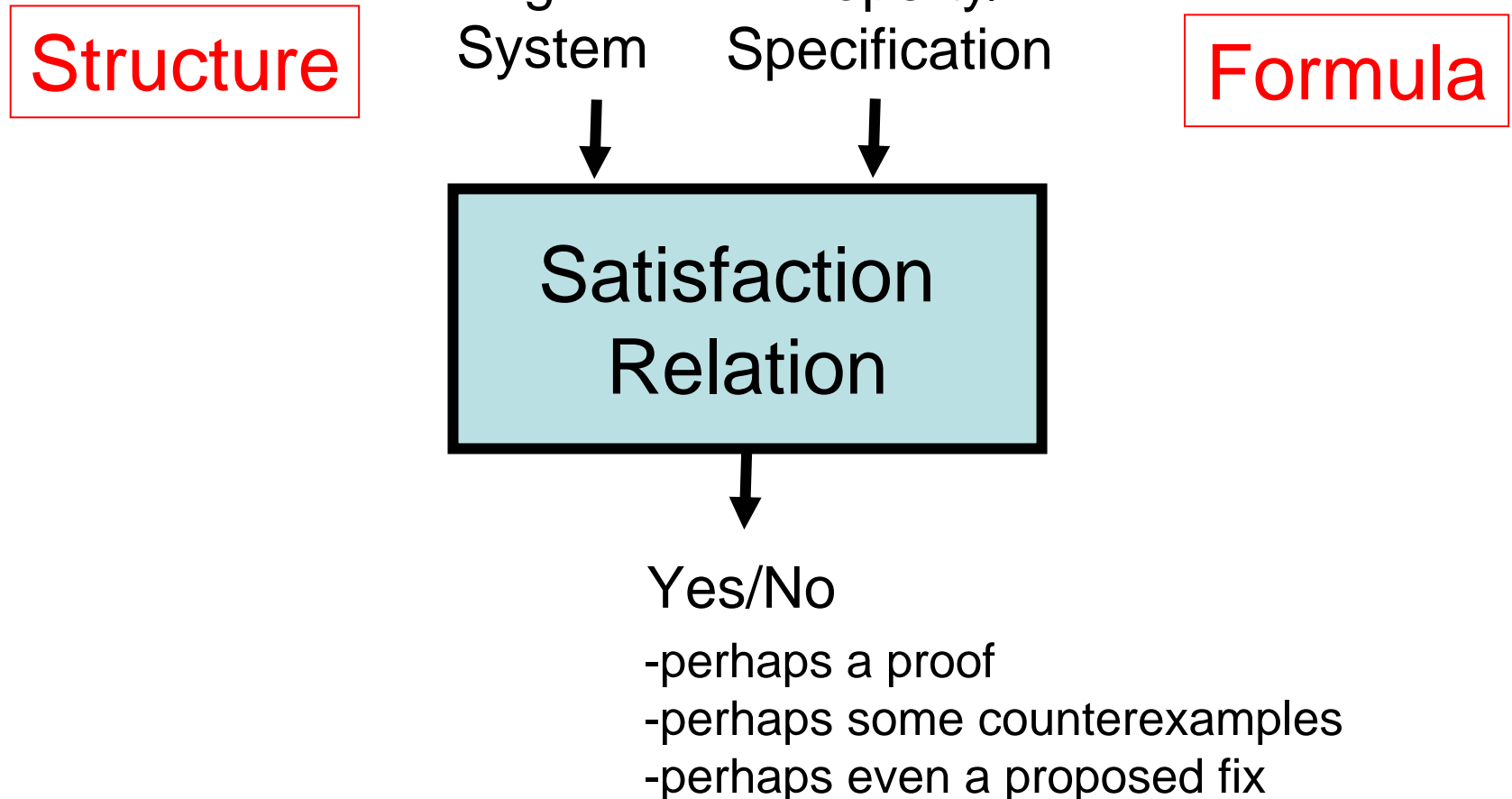
```
graph TD; A[Program/System] --> C[Analysis]; B[Property/Specification] --> C; C --> D[Yes/No];
```



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

Boolean Systems Theories



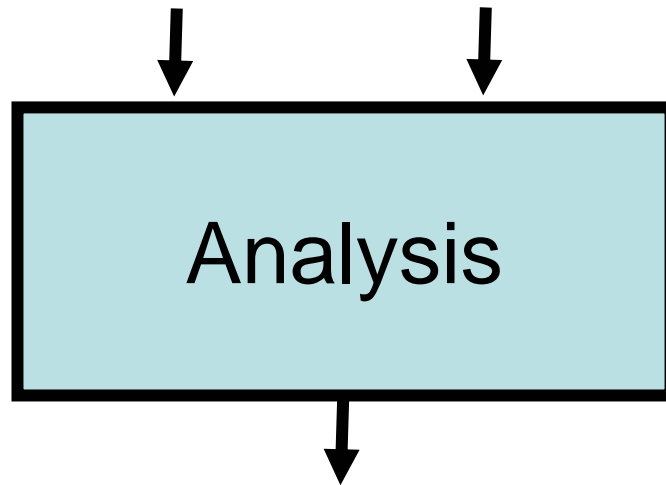
Boolean Systems Theories

Transition
system.

Program/
System

Property/
Specification

Every request is
followed by a grant.



Yes/No

- perhaps a proof
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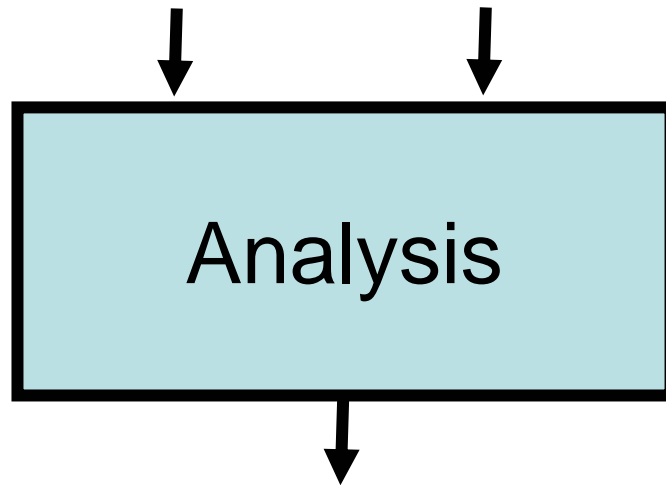
Boolean Systems Theories

Timed
automaton.

Quantitative
Program/
System

Quantitative
Property/
Specification

Every request is
followed by a grant
within 5 time units.



Yes/No

- perhaps a proof
- perhaps some counterexamples
- perhaps even a proposed fix

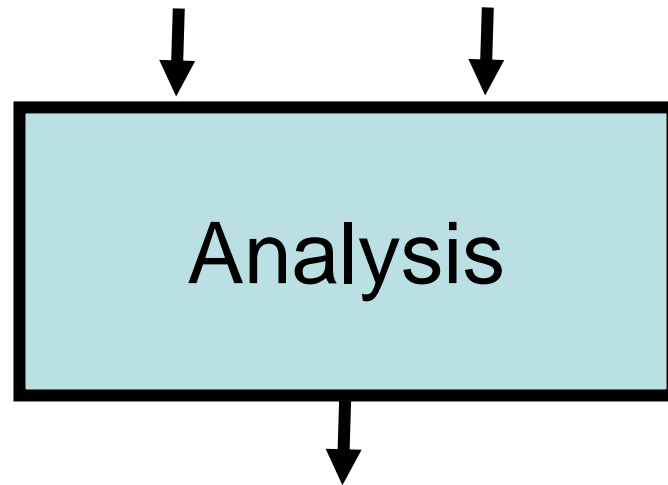
Boolean Systems Theories

Markov
process.

Quantitative
Program/
System

Quantitative
Property/
Specification

Every request is
followed by a grant
within probability $1/2$.



Yes/No

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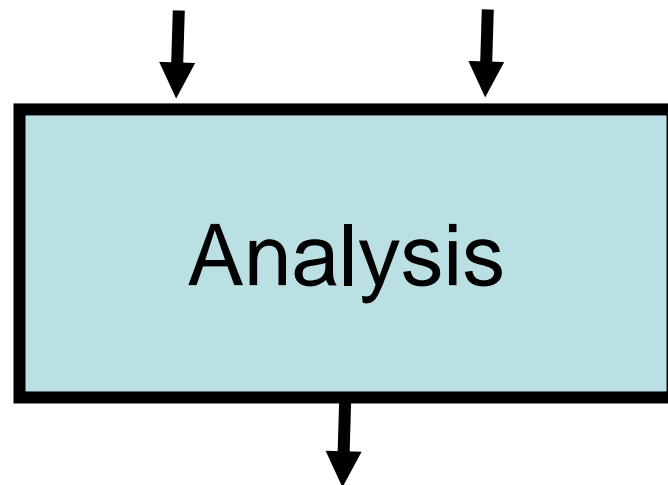
Boolean Systems Theories

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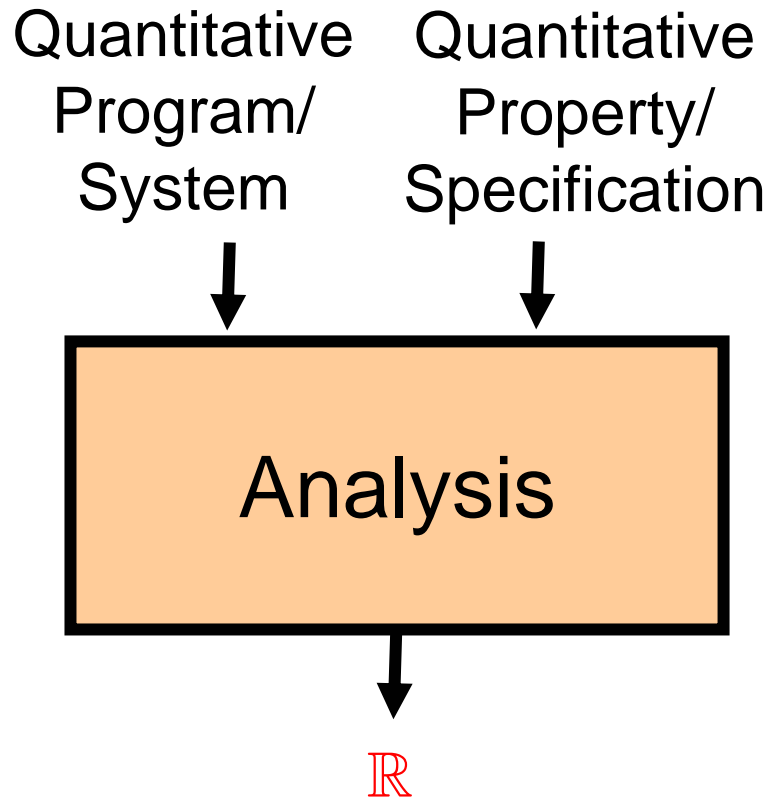
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IB

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- perhaps some counterexamples
- perhaps even a proposed fix

A Quantitative Systems Theory

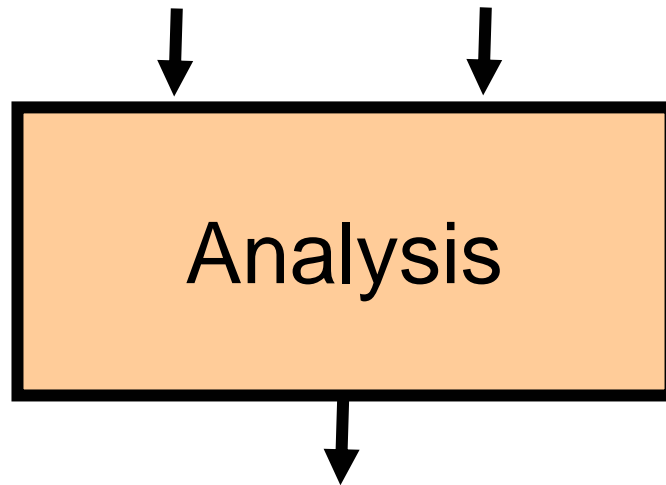


- measure of "fit" between system and spec
- could be cost, quality, etc.

A Quantitative Systems Theory

Quantitative Program/
System ~~Quantitative~~
Property/
Specification

Every request is
followed by a grant.



\mathbb{R}

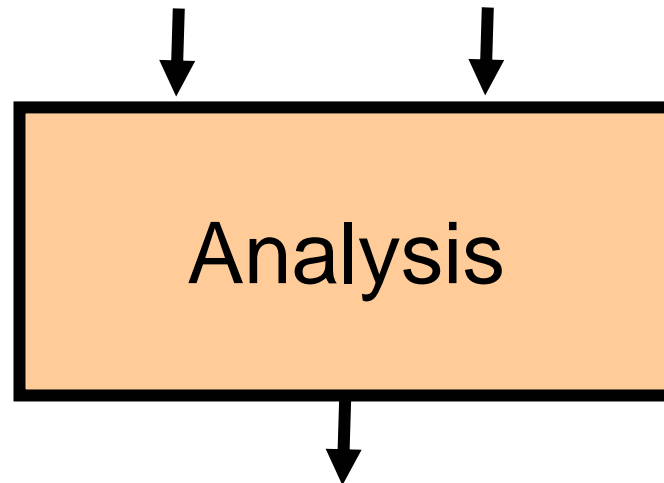
-measure of “fit” between system and spec
-could be cost, quality, etc.

The less time between
requests and grants,
the better.

A Quantitative Systems Theory

~~Quantitative~~ Program/
System ~~Quantitative~~ Property/
Specification

Every request is
followed by a grant.



The fewer unnecessary
grants, the better.

\mathbb{R}

-measure of “fit” between system and spec
-could be cost, quality, etc.

A Quantitative Systems Theory

Q1 Assigning values to behaviors

Q2 Assigning values to systems/properties

Q3 Assigning values to pairs of systems/properties

A Quantitative Systems Theory

Q1 Assigning values to behaviors

Boolean case: correct vs. incorrect behaviors

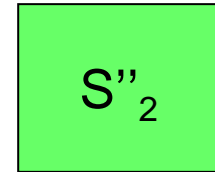
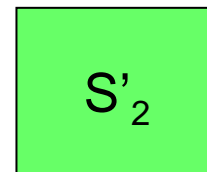
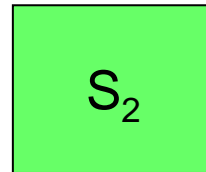
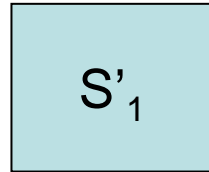
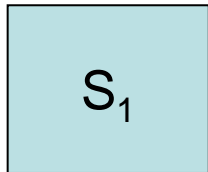
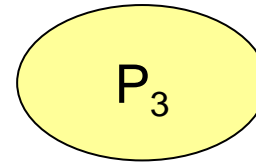
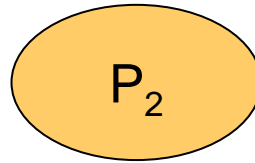
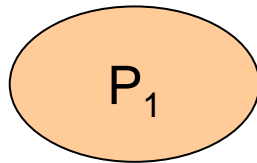
Q2 Assigning values to systems/properties

Boolean case: sets of behaviors (nondeterminism)

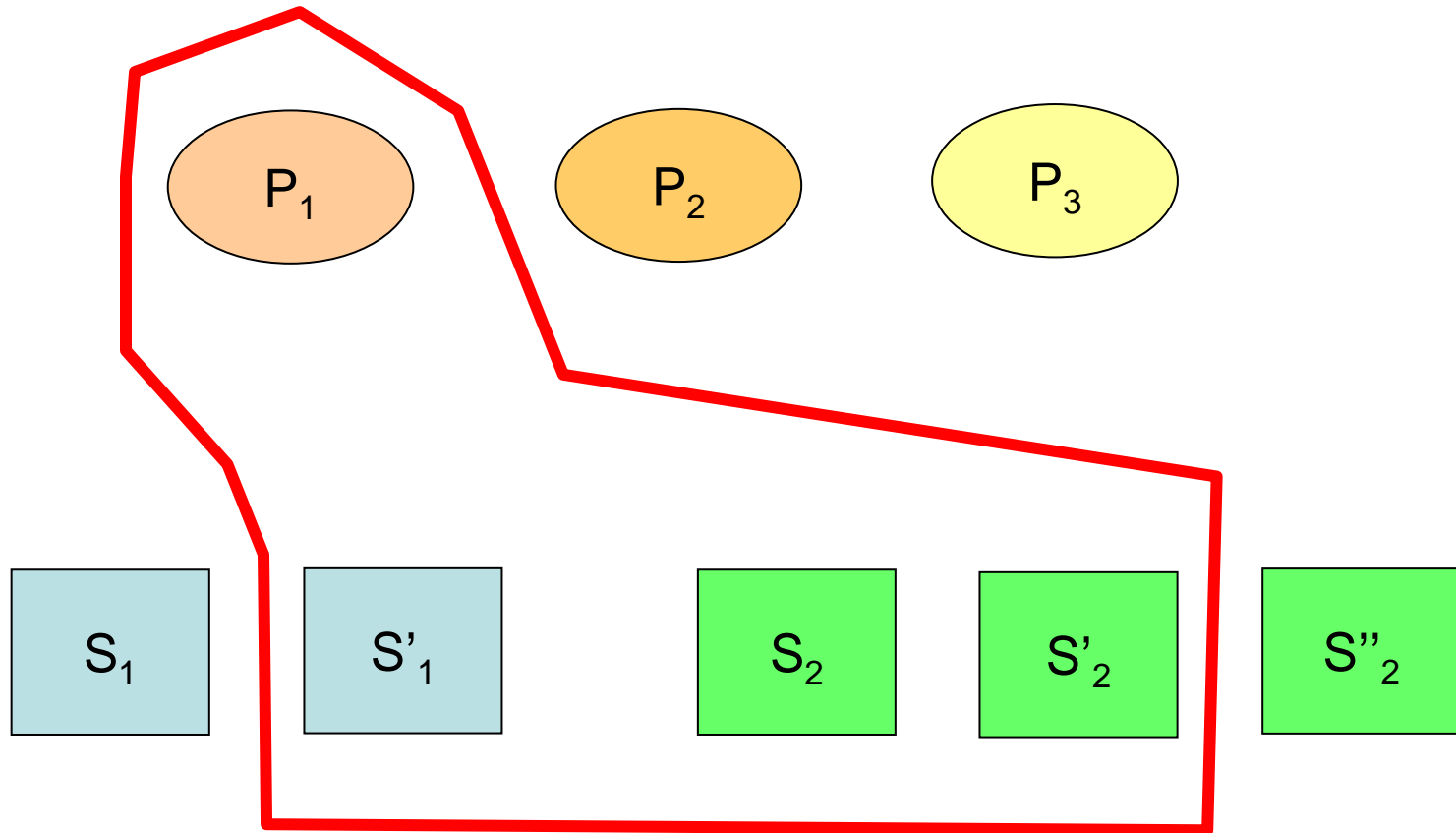
Q3 Assigning values to pairs of systems/properties

Boolean case: preorders (refinement)

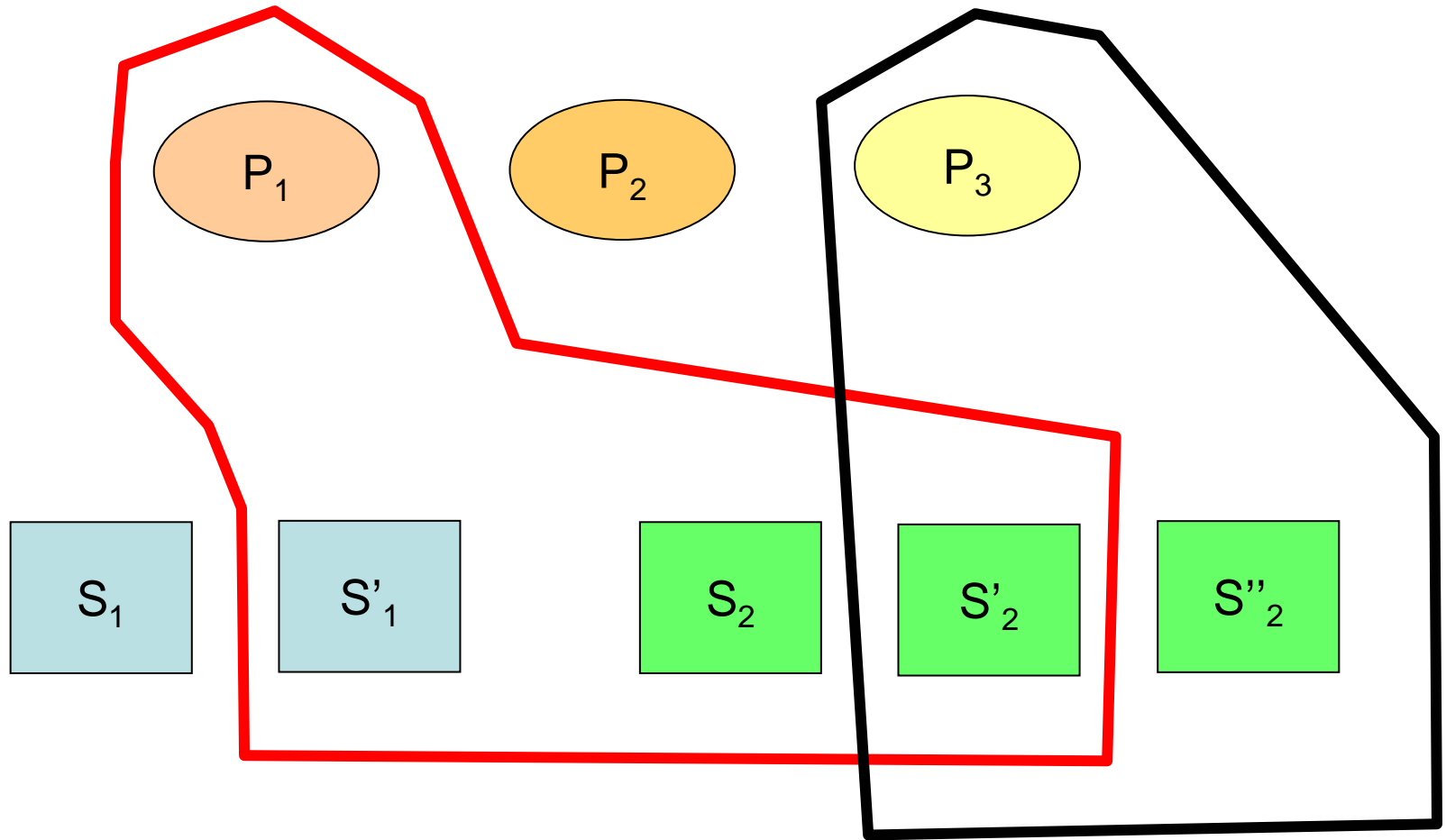
Boolean Systems Theories



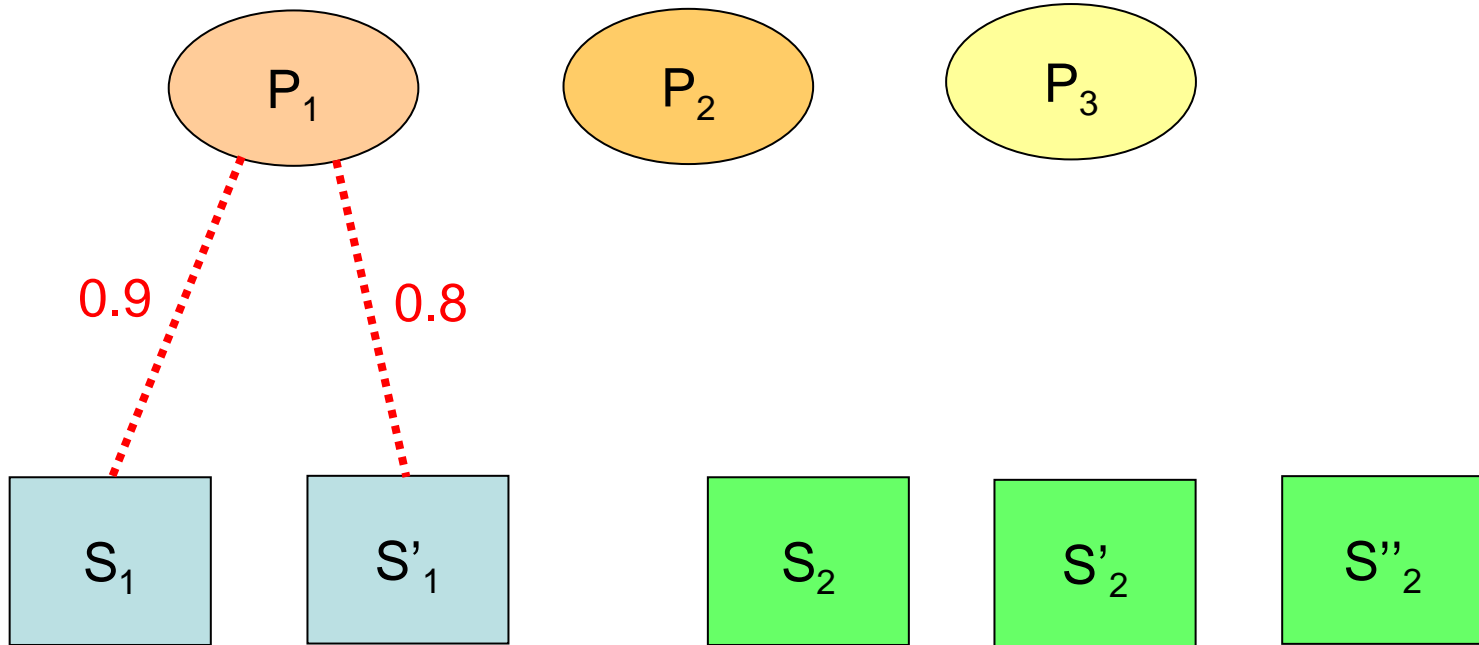
Boolean Systems Theories



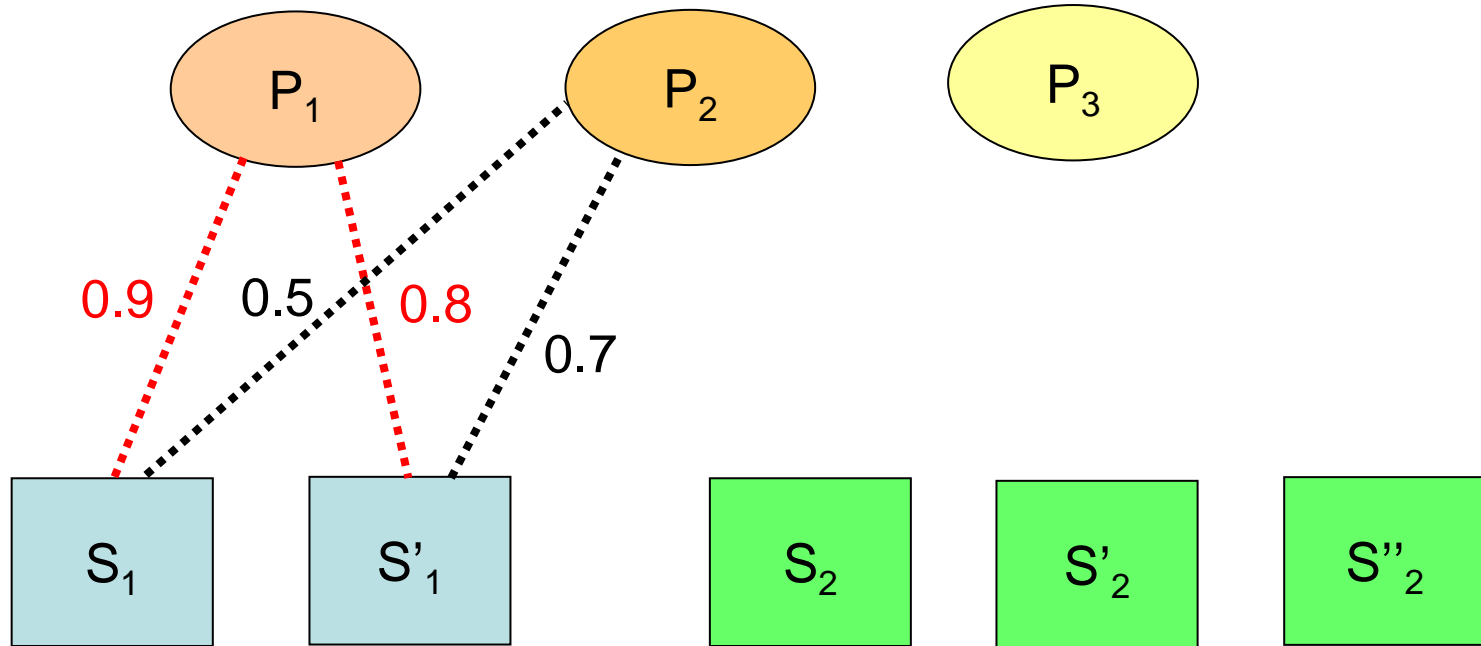
Boolean Systems Theories



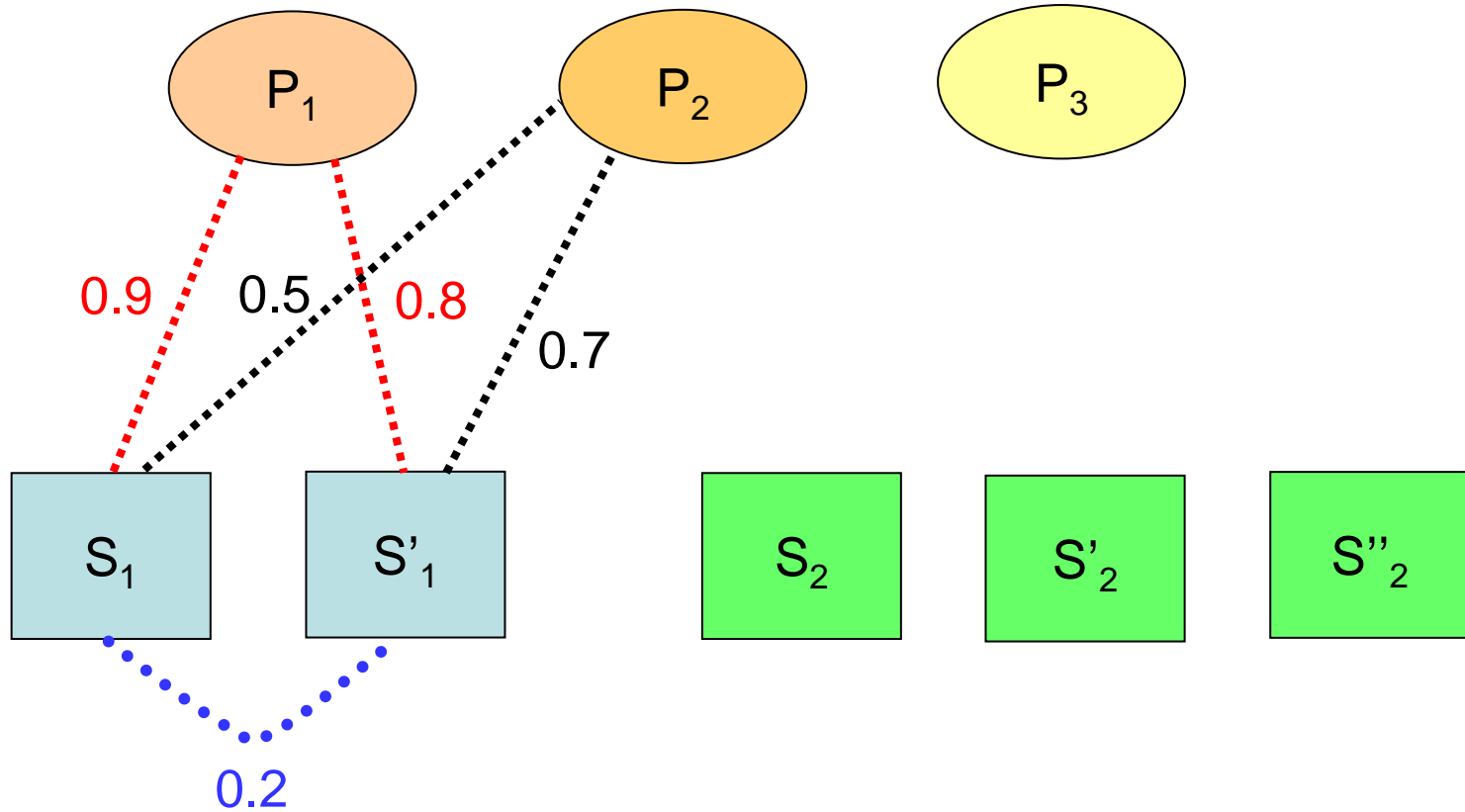
A Quantitative Systems Theory



A Quantitative Systems Theory



A Quantitative Systems Theory



Q1 Assigning Values To Behaviors

a. Probabilities

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b. Resource use

- worst case vs. average case (e.g. response time, QoS)
- peak vs. accumulative (e.g. power consumption)

Q1 Assigning Values To Behaviors

a. Probabilities

b. Resource use

- worst case vs. average case (e.g. response time, QoS)
- peak vs. accumulative (e.g. power consumption)

c. Quality measures

- discounting vs. long-run averaging (e.g. reliability)

Q1 Assigning Values To Behaviors: Safety

a: ok

b: fail

Discounted value ($0 < d < 1$):

aaaaaaaaaa...	1
aaaaaaab...	$1 - d^8$
aab...	$1 - d^3$
b...	0

Q1 Assigning Values To Behaviors: Safety

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b: fail

Discounted value ($0 < d < 1$):

aaaaaaaaaa...	1
aaaaaaaaab...	$1 - d^8$
aab...	$1 - d^3$
b...	0

Long-run average value:

aaaaaaaaaa...	1
abaabaaab...	1
aaabaaabaaab...	$3/4$
babbabbba...	0

Q2

Assigning Values To Systems

x: behaviors

w: observations (infinite words)

A,B: systems

$$A(w) = \sup_x \{ \text{val}(x) : \text{obs}(x) = w \}$$

Q2

Assigning Values To Systems

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$$B(w) = \exp_x \{ \text{val}(x) : \text{obs}(x) = w \}$$

Q2

Assigning Values To Systems

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relative to input distribution

Q3 Assigning Distances To Systems

x: behaviors

w: observations (infinite words)

A,B: systems

$$A(w) = \sup_x \{ \text{val}(x) : \text{obs}(x) = w \}$$

$$B(w) = \exp_x \{ \text{val}(x) : \text{obs}(x) = w \}$$

$$\text{diff}(A,B) = \sup_w \{ |A(w) - B(w)| \}$$

Q3 Assigning Distances To Systems

x: behaviors

w: observations (infinite words)

A,B: systems

$$A(w) = \sup_x \{ \text{val}(x) : \text{obs}(x) = w \}$$

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$$\text{diff}(A,B) = \sup_w \{ |A(w) - B(w)| \}$$

Boolean compositionality: if $A \leq A'$ then $A||B \leq A'||B$

Quantitative compositionality: $\text{diff}(A||B, A'||B) \leq f(\text{diff}(A, A'))$ [AFHMS]

Is there a Quantitative Systems Theory with

- an appealing mathematical formulation,
- useful expressive power, and
- good algorithmic properties?

(Like the boolean theory of ω -regularity.)

Outline

1 A Quantitative Systems Theory

2 Some Basic Open Problems:

- Language inclusion for MDPs

- Language inclusion for weighted automata

3 Some Promising Directions

Property = Language

Alphabet:

Σ

$\Sigma = \{a,b,c\}$

Language:

$L \subseteq \Sigma^\omega$

$L = (a^+b)^+(a^\omega \cup c^\omega) \cup (a^+b)^\omega$

$abaabaaabcccccc... \in L$

$abcabc... \notin L$

Boolean Language

Alphabet:

Σ

$$\Sigma = \{a,b,c\}$$

Language:

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$abaabaaabcccccc... \in L$

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$$L: \Sigma^\omega \rightarrow \mathbb{B}$$

Specification = Automaton

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

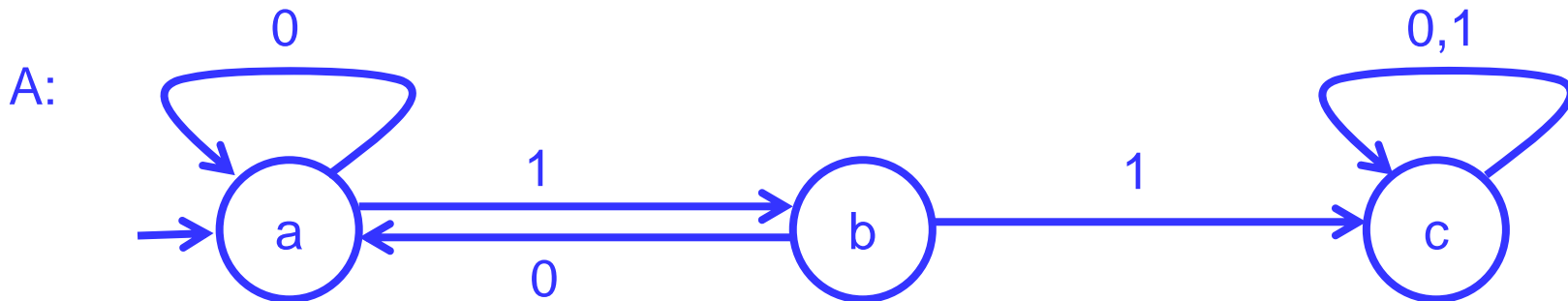
initial state

Γ

choices

$\delta: Q \times \Gamma \rightarrow Q$

transition function



$\Gamma = \{0,1\}$

$L(A) = (a^+b)^+(a^\omega \cup c^\omega) \cup (a^+b)^\omega$

Specification = Automaton

Q

states

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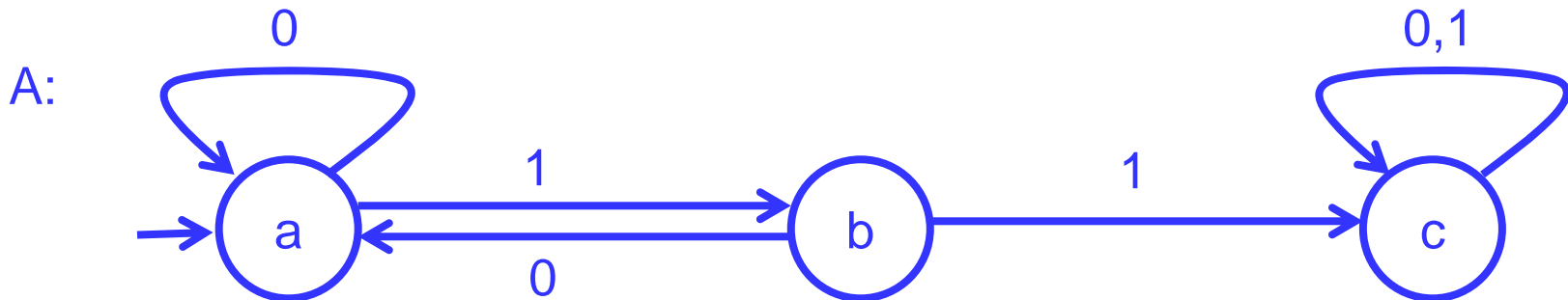
initial state

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transition function



“scheduler”

0101111... → aababccc...

“outcome”

Specification = Automaton

Q	states
$\lambda: Q \rightarrow \Sigma$	labeling
$q_0 \in Q$	initial state
Γ	choices
$\delta: Q \times \Gamma \rightarrow Q$	transition function

Scheduler: $x: Q^+ \rightarrow \Gamma$
 S ... set of schedulers

Outcome: $f(x) = q_0q_1q_2 \dots$
where $\forall i : q_{i+1} = \delta(q_i, x(q_0 \dots q_i))$

Language: $L = \{ \lambda(f(x)) : x \in S \}$

Satisfaction = Language Inclusion

Given two automata A and B , is $L(A) \subseteq L(B)$?

Satisfaction = Language Inclusion

Given two automata A and B, is $L(A) \subseteq L(B)$?

i.e. $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w)$

Satisfaction = Language Inclusion

Given two automata A and B, is $L(A) \subseteq L(B)$?

i.e. $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w)$

For finite/Buechi automata, PSPACE-complete.

Probabilistic Language

Word:	element of Σ^ω
Probabilistic Word:	probability space on Σ^ω
Probabilistic Language:	set of probabilistic words

w: $ab\Sigma^\omega \rightarrow 1/2$
 $aab\Sigma^\omega \rightarrow 1/4$
 $aaab\Sigma^\omega \rightarrow 1/8$
 ...

Markov Decision Process

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

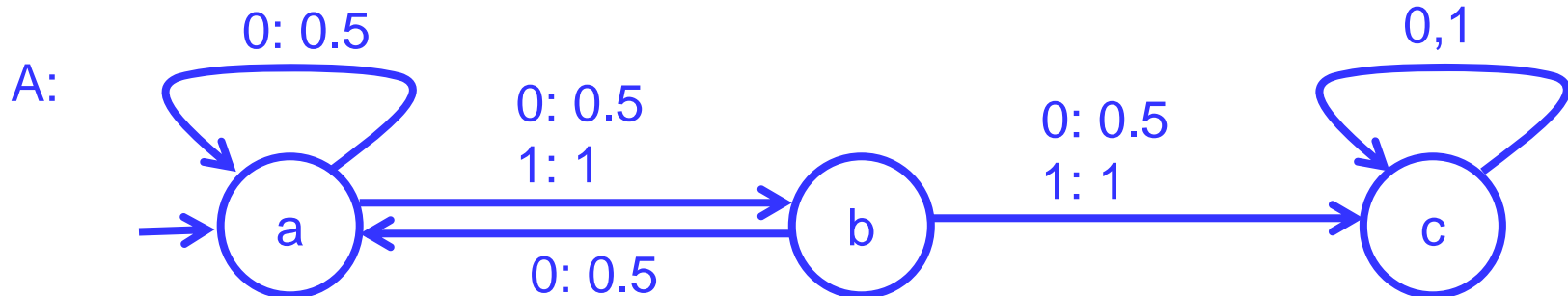
initial state

Γ

choices

$\delta: Q \times \Gamma \rightarrow D(Q)$

transition function



Markov Decision Process

Q

$\lambda: Q \rightarrow \Sigma$

$q_0 \in Q$

Γ

$\delta: Q \times \Gamma \rightarrow D(Q)$

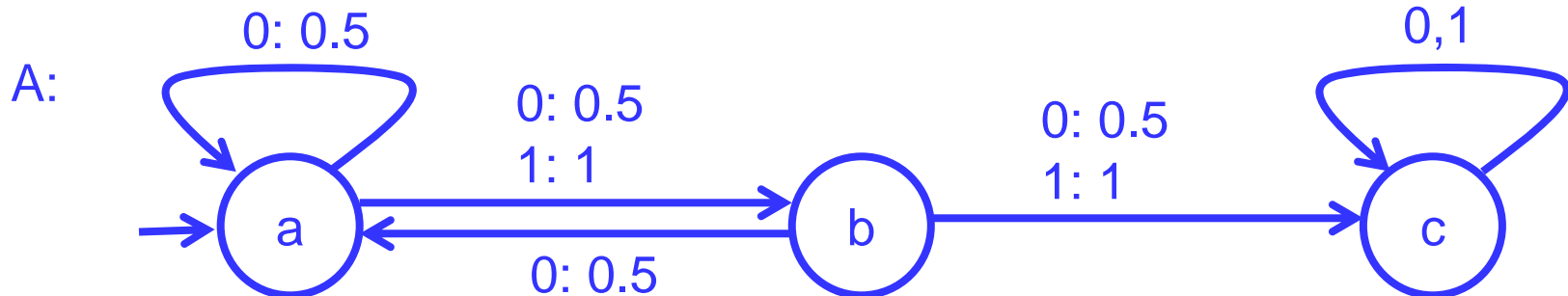
states

labeling

initial state

choices

transition function



0101111... \rightarrow abccc... \rightarrow 1/2
aabccc... \rightarrow 1/4
...

Markov Decision Process

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

initial state

Γ

choices

$\delta: Q \times \Gamma \rightarrow D(Q)$

transition function

Pure scheduler:

$x: Q^+ \rightarrow \Gamma$

Probabilistic scheduler:

$x: Q^+ \rightarrow D(\Gamma)$

Markov Decision Process

Q

$\lambda: Q \rightarrow \Sigma$

$q_0 \in Q$

Γ

$\delta: Q \times \Gamma \rightarrow D(Q)$

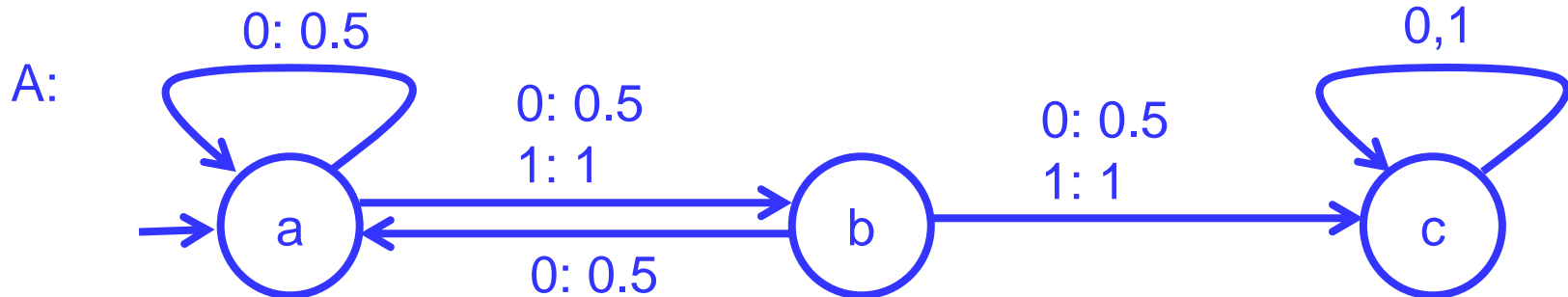
states

labeling

initial state

choices

transition function



$\{0: 0.5, 1: 0.5\}^\omega \rightarrow$ abccc... $\rightarrow 9/16$
aabccc... $\rightarrow 9/64$
...

Probabilistic Language Inclusion

Given two MDPs A and B , is $L(A) \subseteq L(B)$?

Probabilistic Language Inclusion

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Probabilistic Language Inclusion

Given two MDPs A and B , is $L(A) \subseteq L(B)$?



Open even if specification B is deterministic (i.e. $|\Gamma| = 1$) and implementation scheduler required to be pure.

If both sides are deterministic, then it can be solved in polynomial time (equivalence of Rabin's probabilistic automata) [Tzeng, DHR].

Quantitative Language

Language:

$$L: \Sigma^\omega \rightarrow \mathbb{B}$$

Quantitative Language:

$$L: \Sigma^\omega \rightarrow \mathbb{R}$$

$$L(ab^\omega) = 1/2$$

$$L(aab^\omega) = 1/4$$

$$L(aaab^\omega) = 1/8$$

...

Weighted Automaton

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

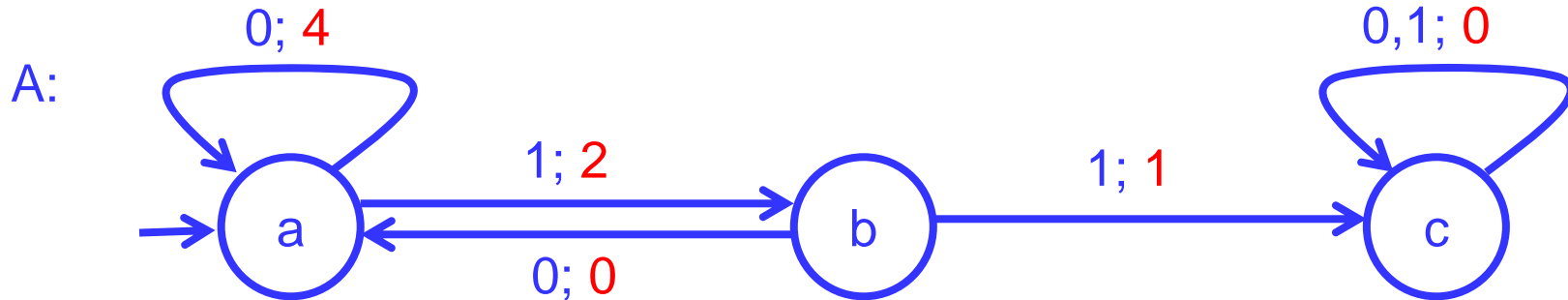
initial state

Γ

choices

$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$

transition function



Weighted Automaton

Q

states

$\lambda: Q \rightarrow \Sigma$

labeling

$q_0 \in Q$

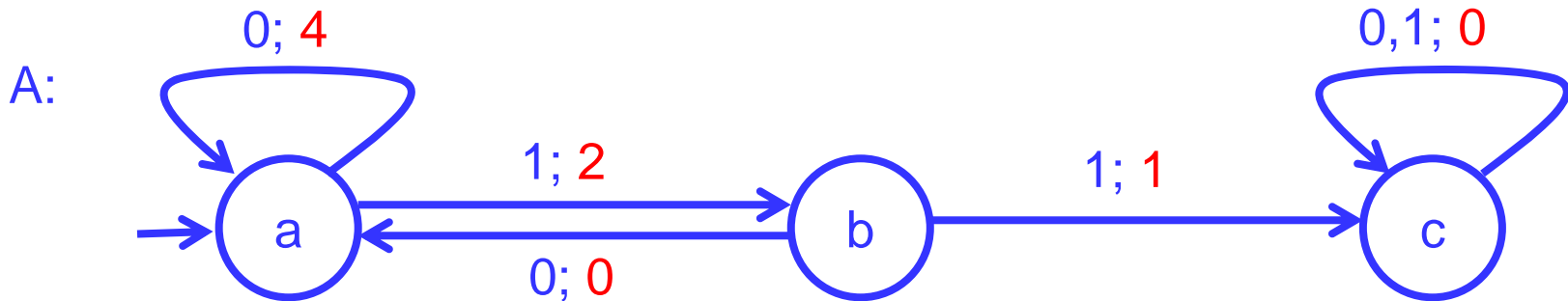
initial state

Γ

choices

$\delta: Q \times \Gamma \rightarrow \mathbb{R} \times Q$

transition function



Value:

0101111... \rightarrow aababccc...; 4

1111111... \rightarrow abccc...; 2

Different Value Functions

Max value: $\text{val}(q_0v_1q_1v_2q_2\dots) = \sup\{ v_i : i \geq 1 \}$

Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$

Different Value Functions

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$
(only 0 and 1 costs: finite automaton)

Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$
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Different Value Functions

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Limavg value: $\text{val} = \lim_{n \rightarrow \infty} 1/n \cdot \sum_{1 \leq i \leq n} v_i$

Different Value Functions

Max value: $\text{val}(q_0 v_1 q_1 v_2 q_2 \dots) = \sup\{ v_i : i \geq 1 \}$
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Limsup value: $\text{val} = \lim_{n \rightarrow \infty} \sup\{ v_i : i \geq n \}$
(only 0 and 1 costs: Buechi automaton)

Limavg value: $\text{val} = \lim_{n \rightarrow \infty} 1/n \cdot \sum_{1 \leq i \leq n} v_i$

Discounted: $\text{val} = \sum_{i \geq 1} d^i \cdot v_i$ for some $0 < d < 1$

Quantitative Language Inclusion

Given two weighted automata A and B , is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w) ?$

Quantitative Language Inclusion

Given two weighted automata A and B, is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w)$?

For max and limsup values: PSPACE.

For limavg and discounted values: Open.

Quantitative Language Inclusion

Given two weighted automata A and B, is
 $\forall w \in \Sigma^\omega : L(A)(w) \leq L(B)(w) ?$

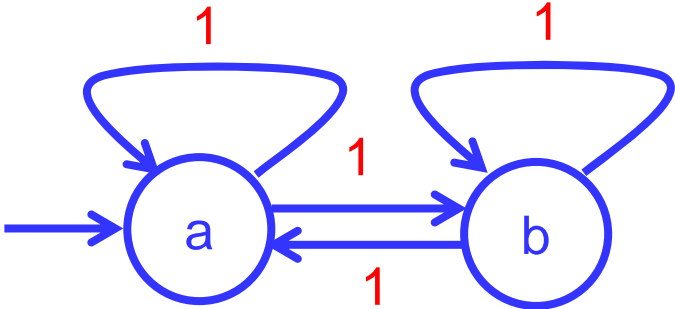
For max and limsup values: PSPACE.

For limavg and discounted values: Open.

If specification B is deterministic,
then it can be solved in polynomial time [CDH].

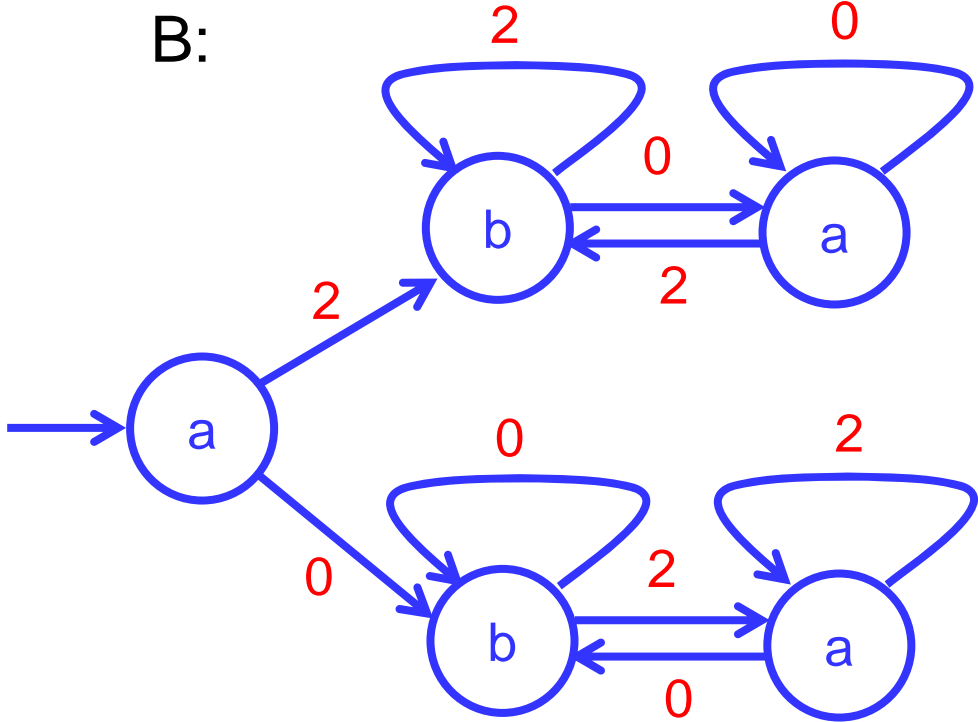
Quantitative Simulation

A:



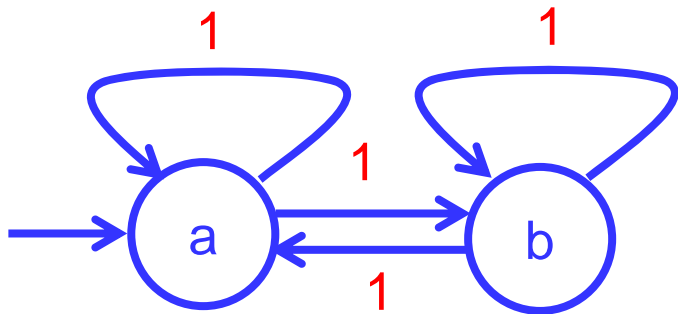
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B:



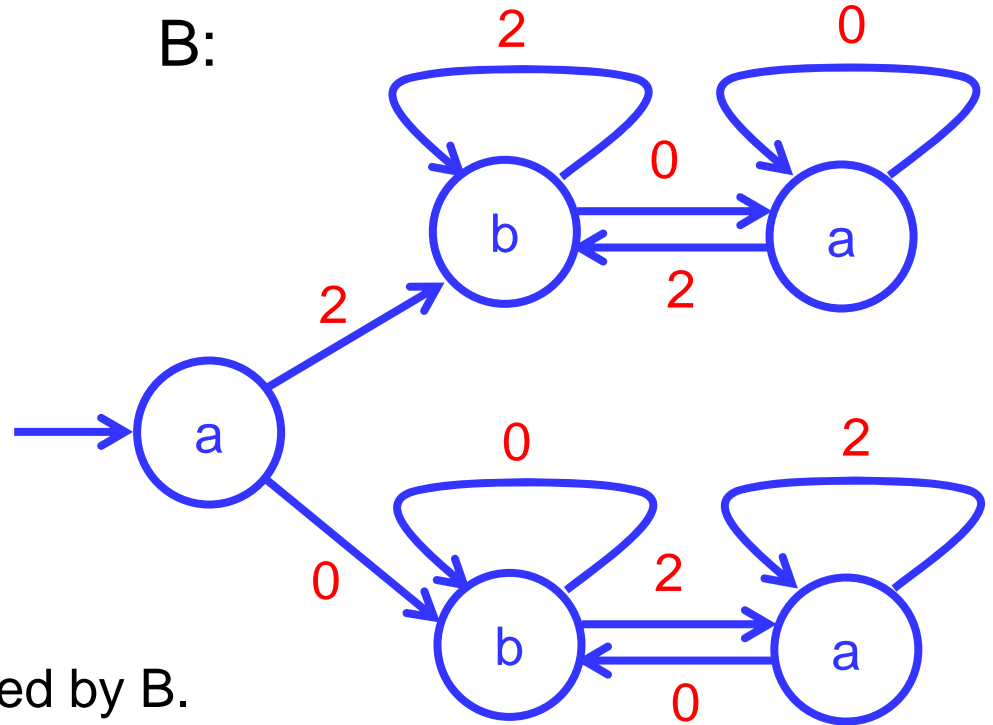
Quantitative Simulation

A:



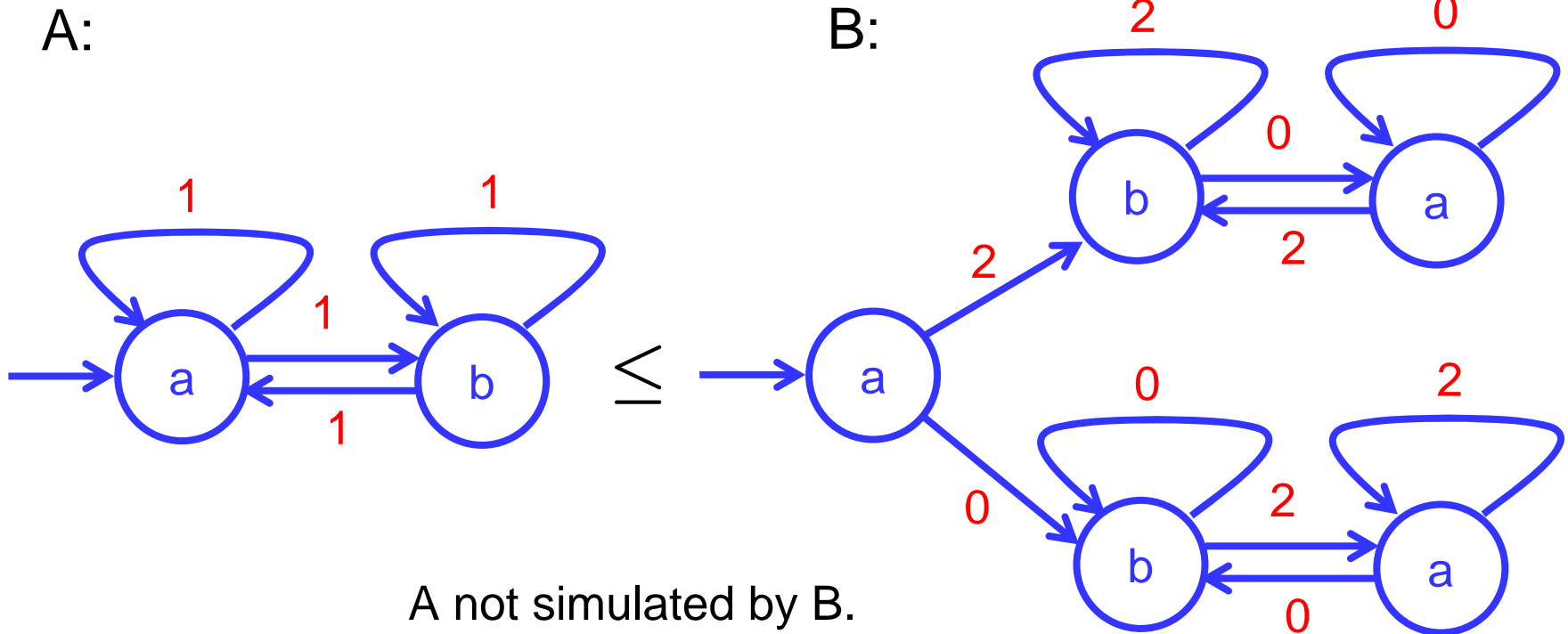
\leq

B:



A not simulated by B.

Quantitative Simulation

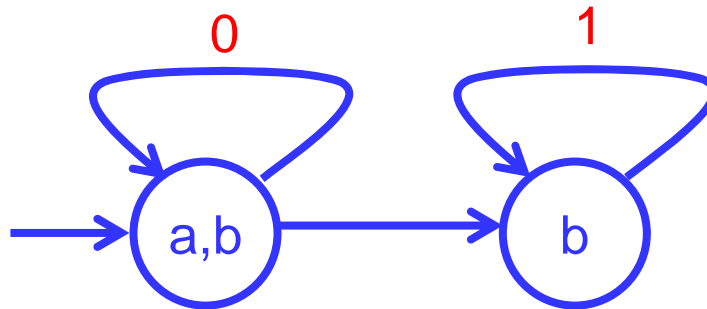


Simulation game solvable in P for max values;
in $NP \cap coNP$ for limsup, limavg, discounted values [CDH].

Quantitative Expressiveness

E.g. **limavg automata not determinizable** [CDH]:

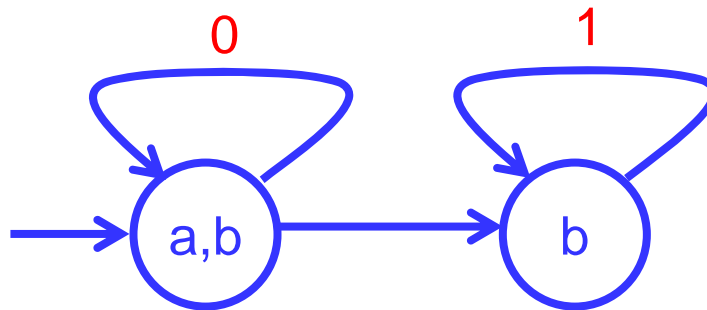
Σ^*b^ω expressible by a nondeterministic limavg automaton.



Quantitative Expressiveness

E.g. **limavg automata not determinizable** [CDH]:

Σ^*b^ω expressible by a nondeterministic limavg automaton.



Σ^*b^ω not expressible by a deterministic limavg automaton.

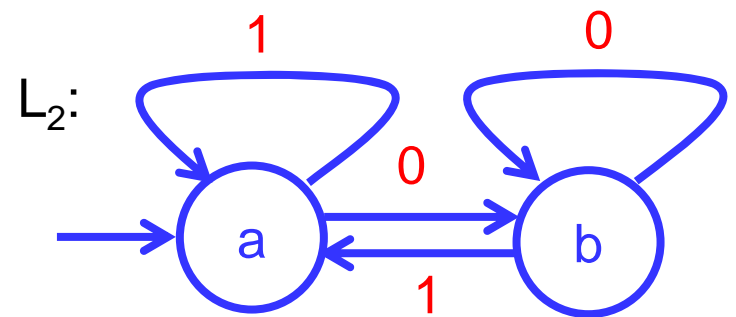
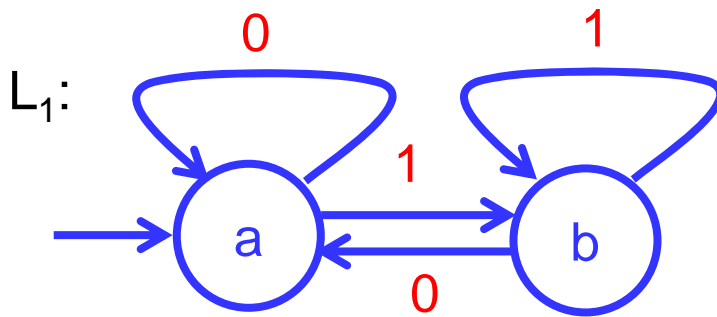
Every b-cycle would need weight 1.

Consider $w_n = (ab^n)^\omega$.

Then $\text{val}(w_n) = 1$ for sufficiently large n , but $w_n \notin \Sigma^*b^\omega$.

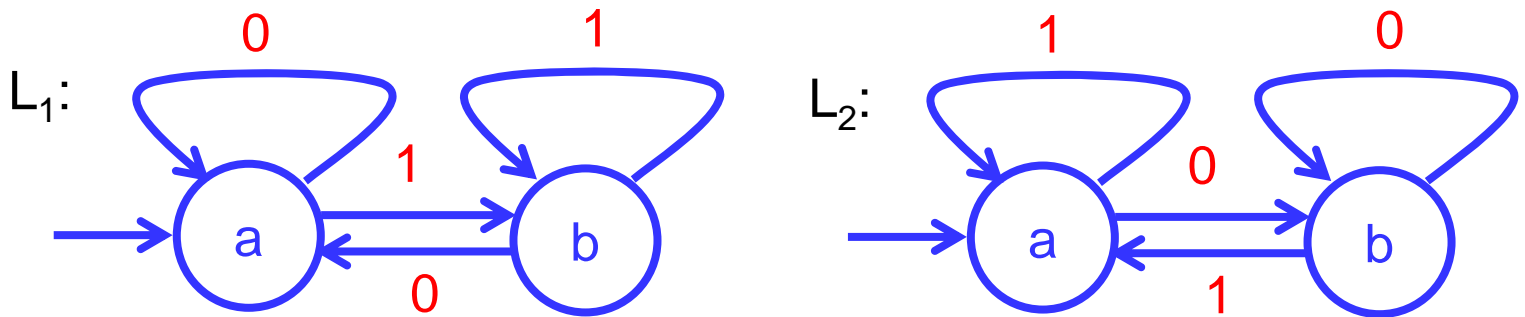
Quantitative Closure Properties

E.g. **limavg automata not closed under min [CDH]:**



Quantitative Closure Properties

E.g. **limavg automata not closed under min** [CDH]:



$\min(L_1, L_2)$ not expressible by a limavg automaton.

Consider $w_n = (a^n b^n)^\omega$ for large n .

Some a -cycle or b -cycle would need average positive weight.

Then some word ua^ω or ub^ω would have a positive value.

Outline

1 The Quantitative Verification Agenda

2 Some Basic Open Problems:

- Language inclusion for MDPs

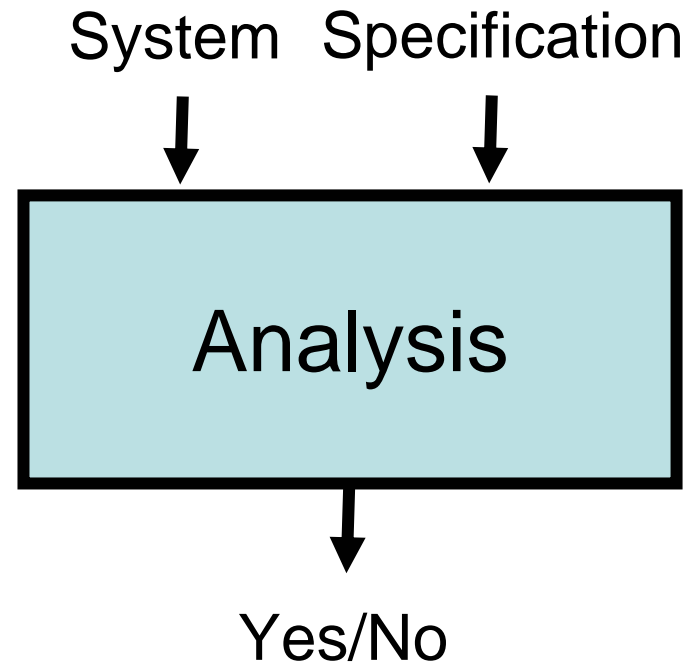
- Language inclusion for weighted automata

3 Some Promising Directions

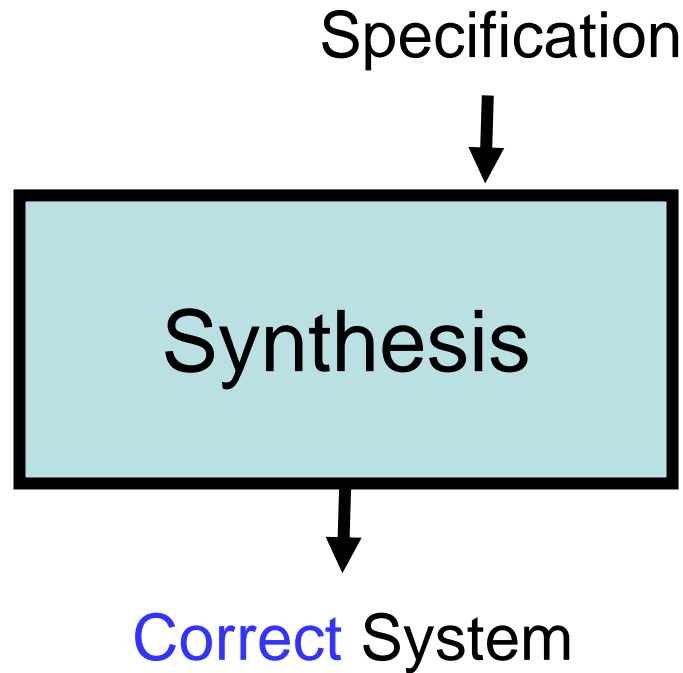
Outline

- 1 The Quantitative Verification Agenda
- 2 Some Basic Open Problems
- 3 Some Promising Directions:
 - Quantitative Synthesis
 - Robust Systems

Boolean Systems Theories



Boolean Systems Theories



Boolean Systems Theories

ω -Regular
Automaton



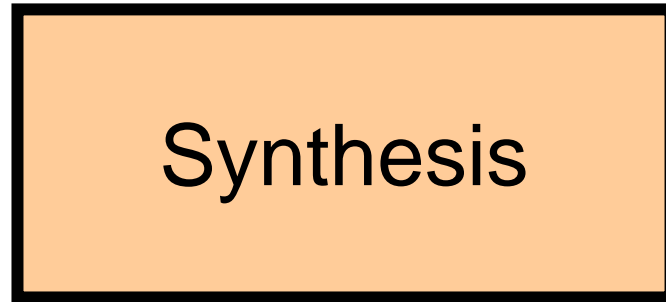
Graph Game with
 ω -Regular Objective



Correct System =
Winning Strategy

Quantitative Synthesis

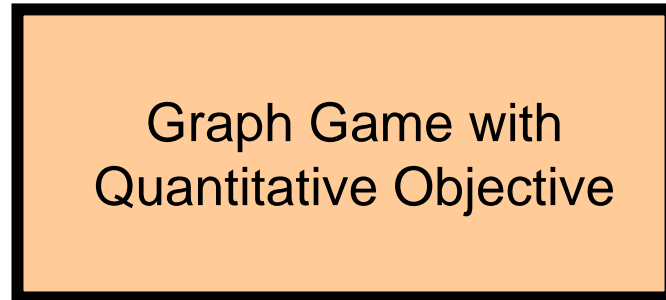
Quantitative
Specification



Optimal System

Quantitative Synthesis

Weighted
Automaton



Optimal System =
Optimal Strategy

Synthesis: From Automata to Games

Automaton states are partitioned into **min** and **max** states.

Game: **minimizer** against **maximizer**

- in min states, minimizer chooses successor

- in max states, maximizer chooses successor

- minimizer tries to minimize value of a word

- maximizer tries to maximize value of a word

Scheduler is replaced by two strategies, one for the **minimizer** and one for the **maximizer**:

$$L(w) = \sup \inf \dots$$

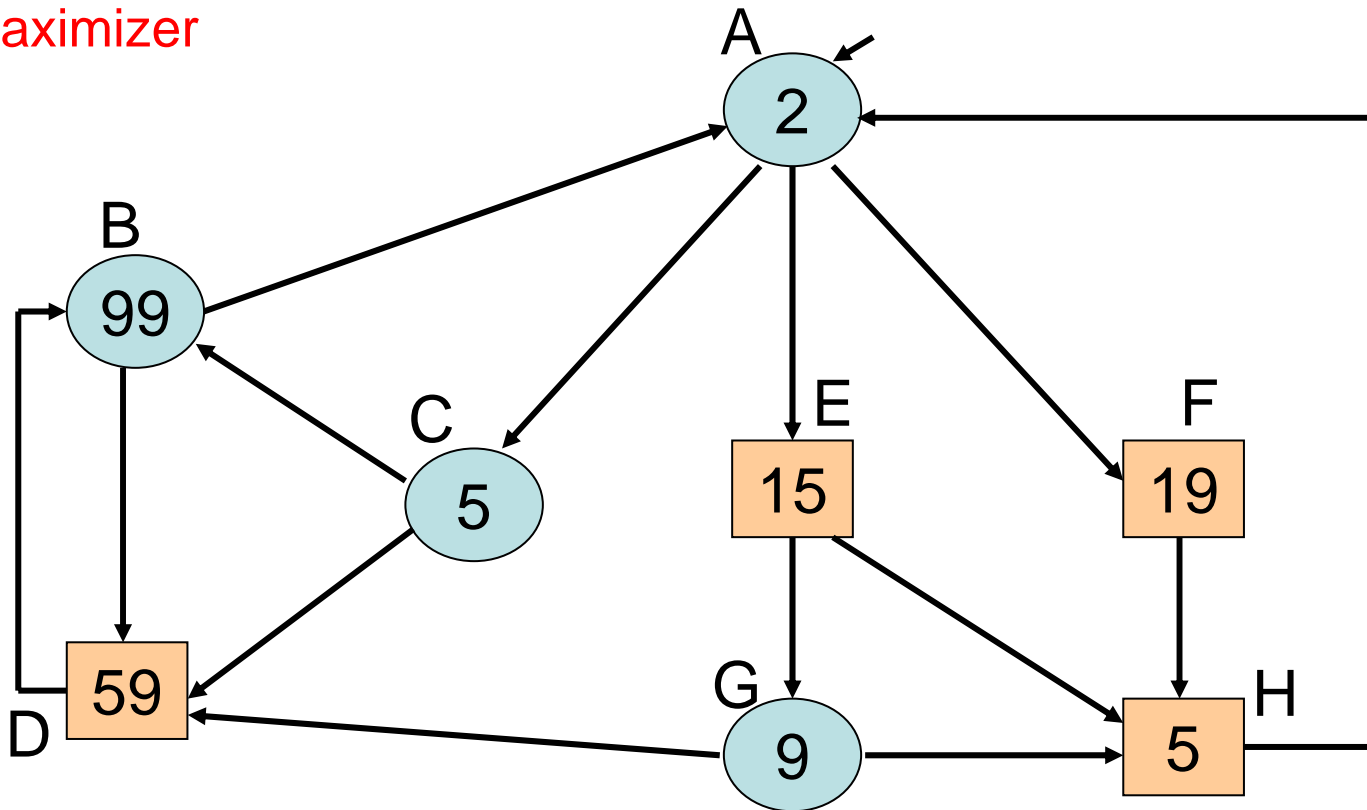
Games for Quantitative Synthesis

1 Constrained Resources

- every weight is a resource cost (e.g. power consumption)
 - optimize peak resource use: **max objective**
 - optimize accumulative resource use: **sum objective**
- [Chakrabarti et al.]

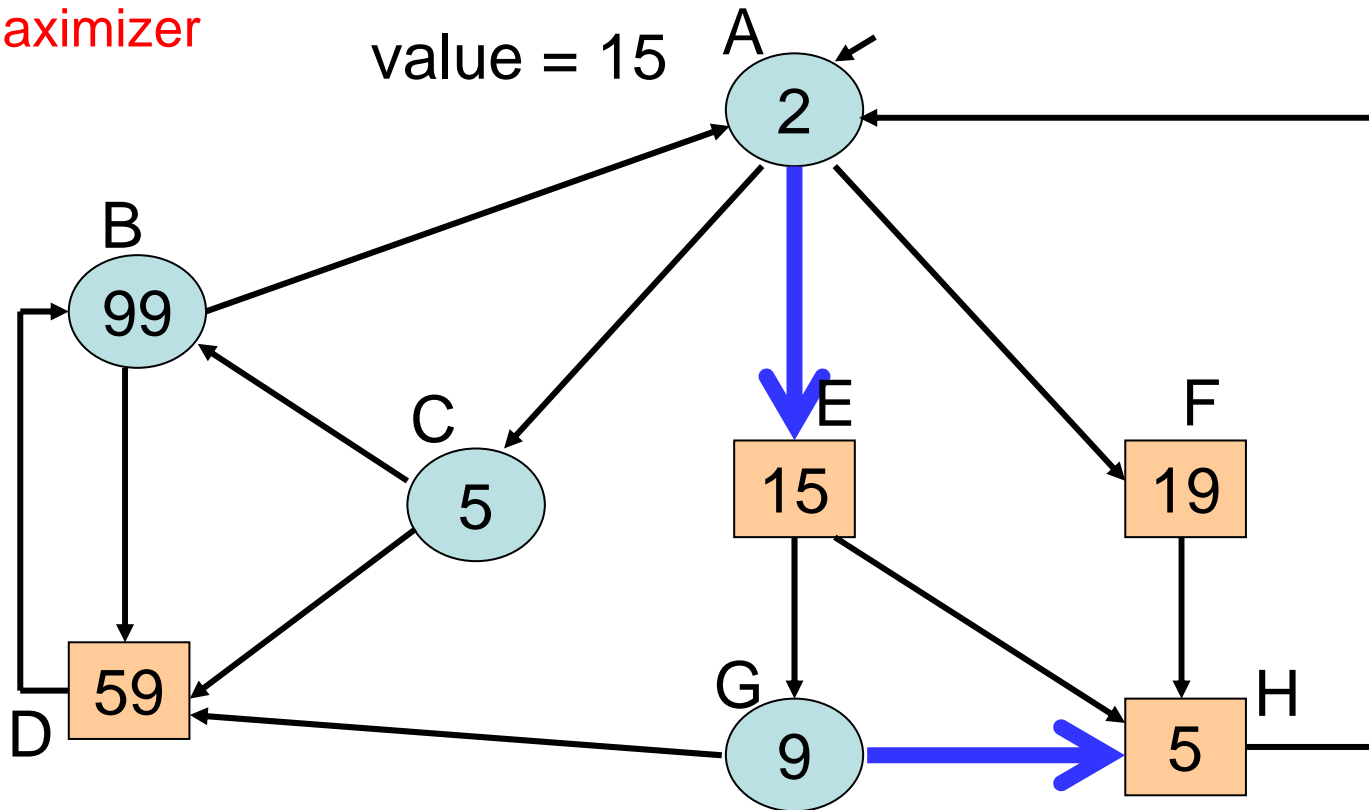
Max Game

minimizer
maximizer



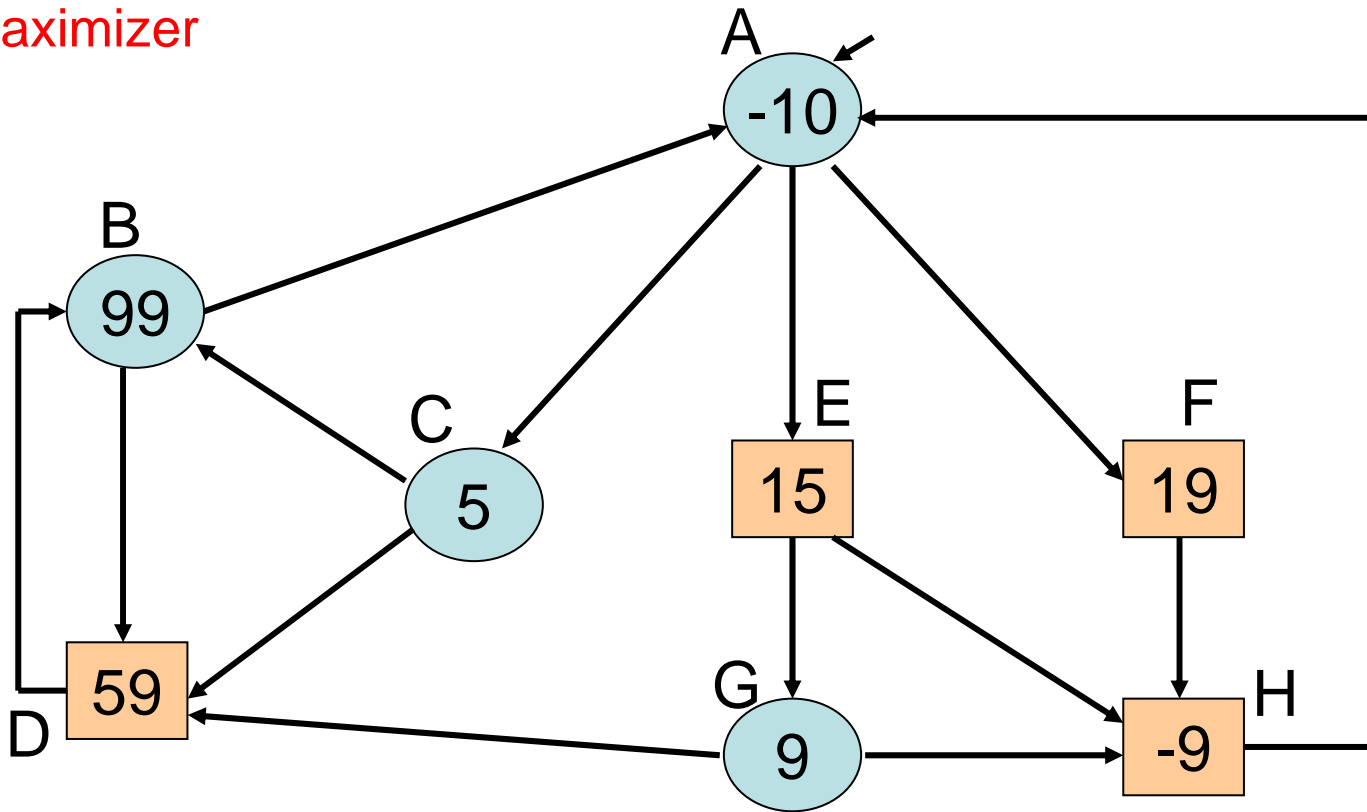
Max Game

minimizer
maximizer



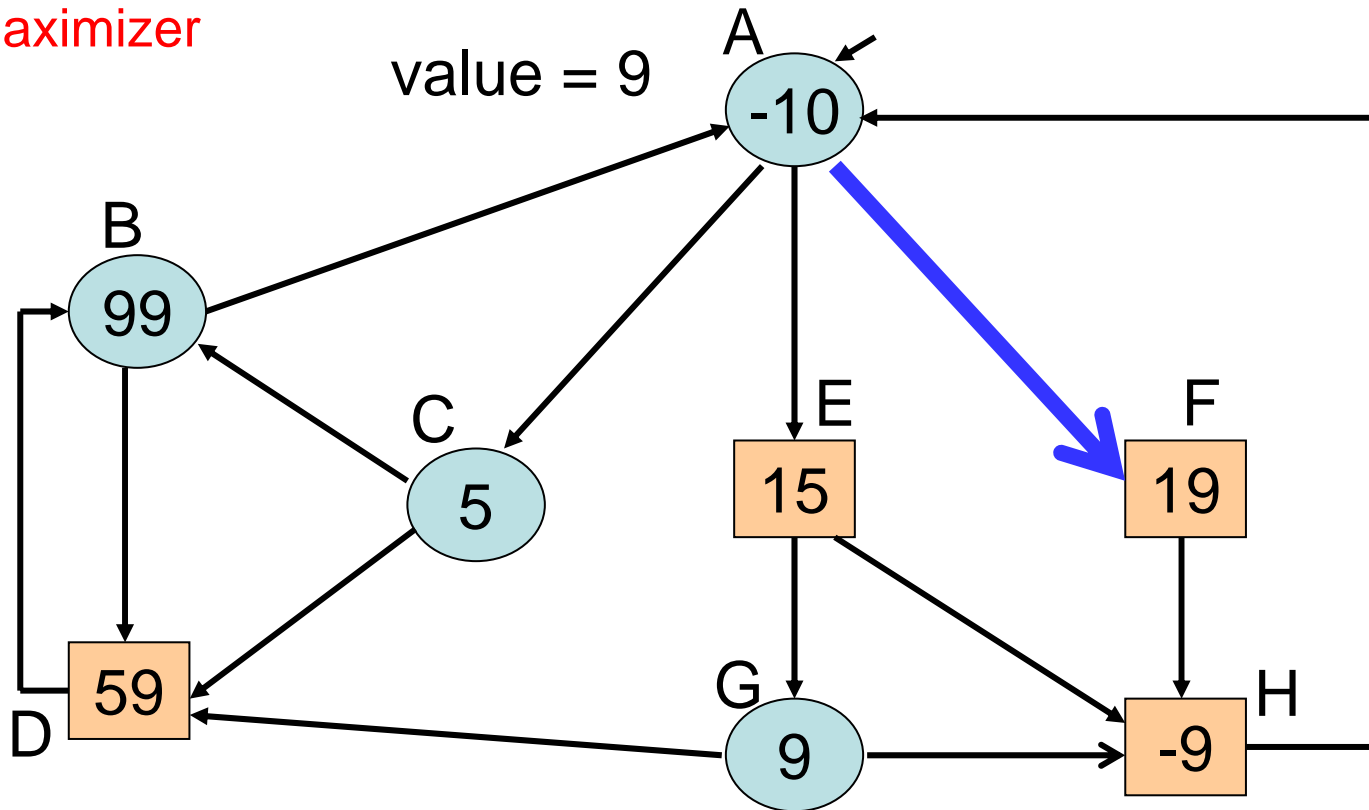
Sum Game

minimizer
maximizer



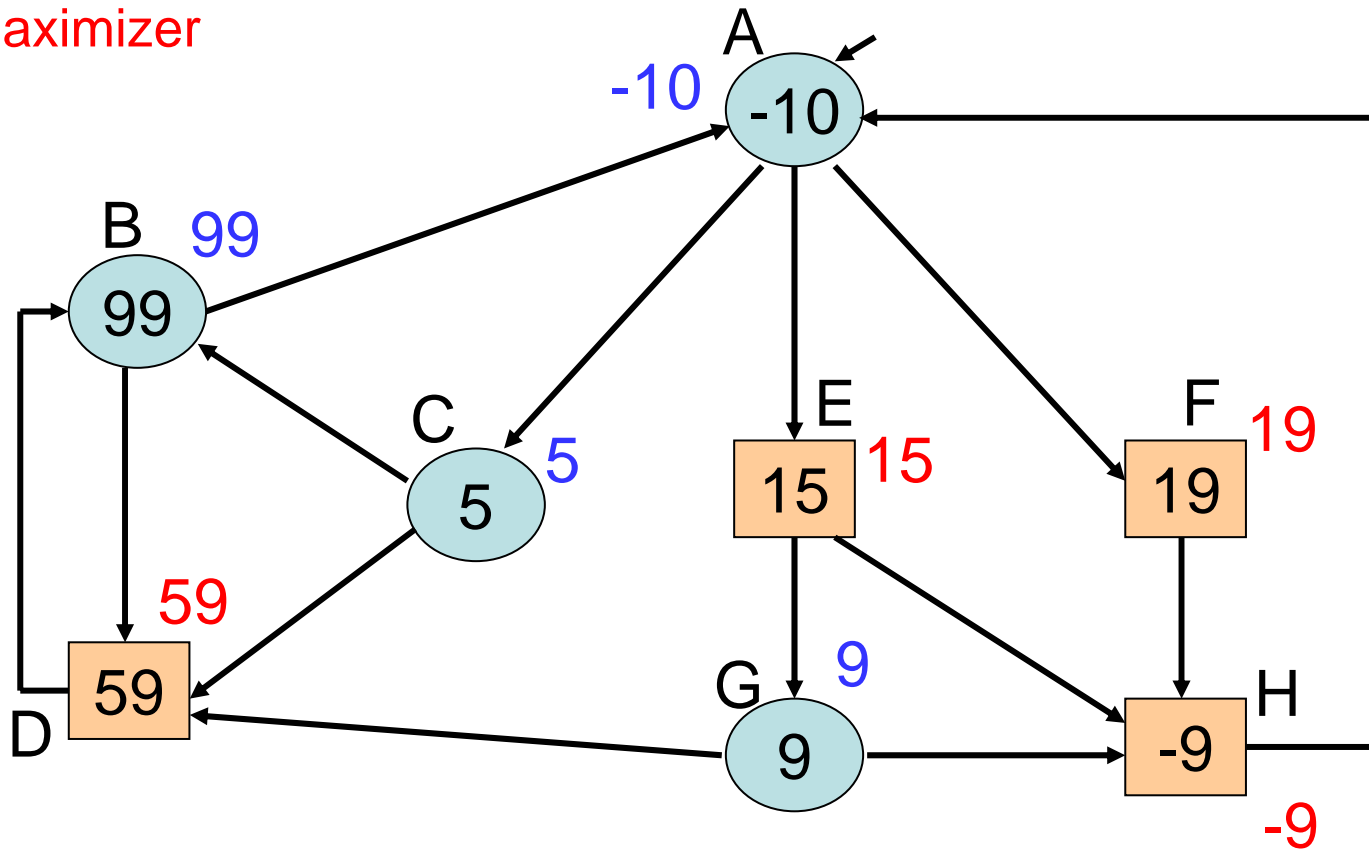
Sum Game

minimizer
maximizer



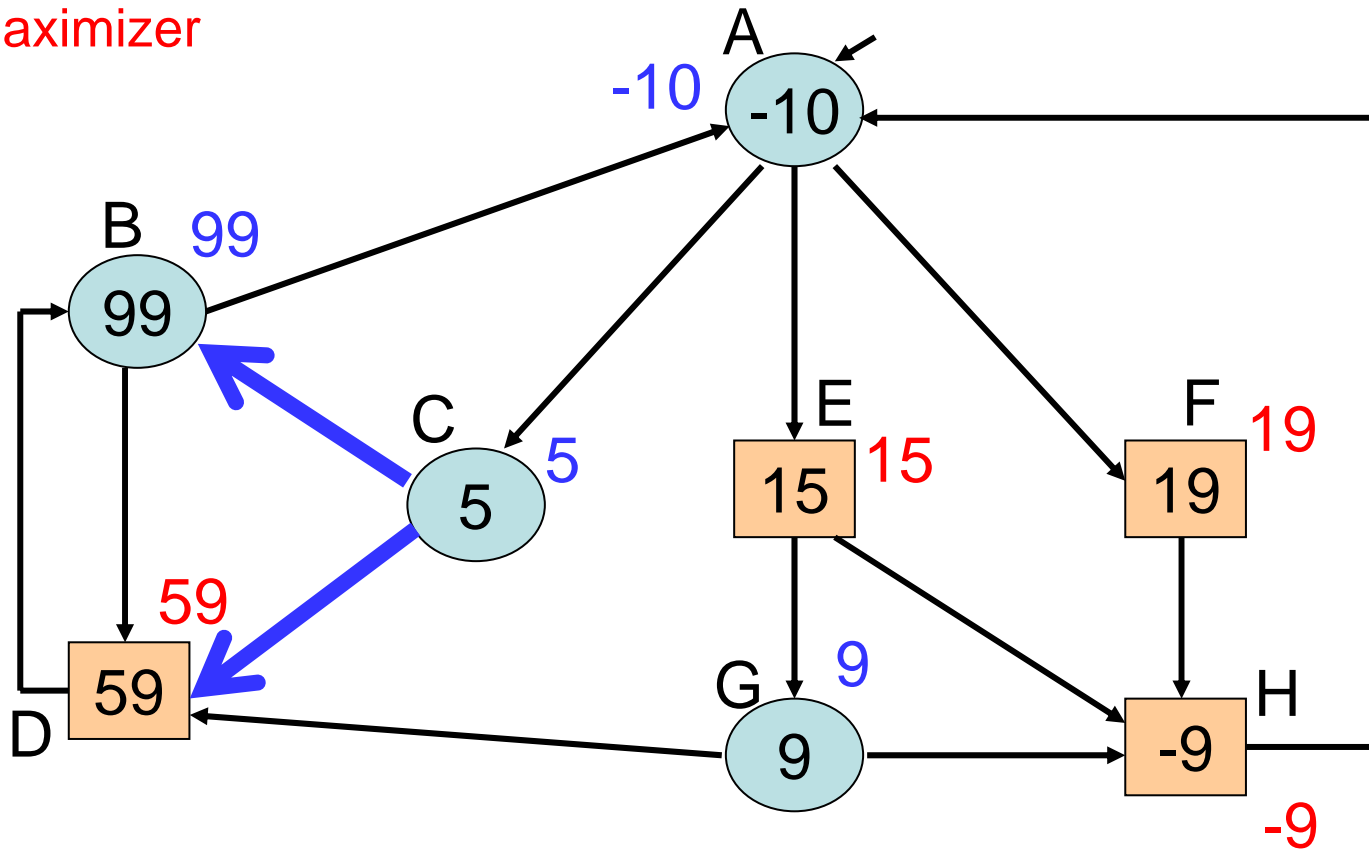
Sum Game

minimizer
maximizer



Sum Game

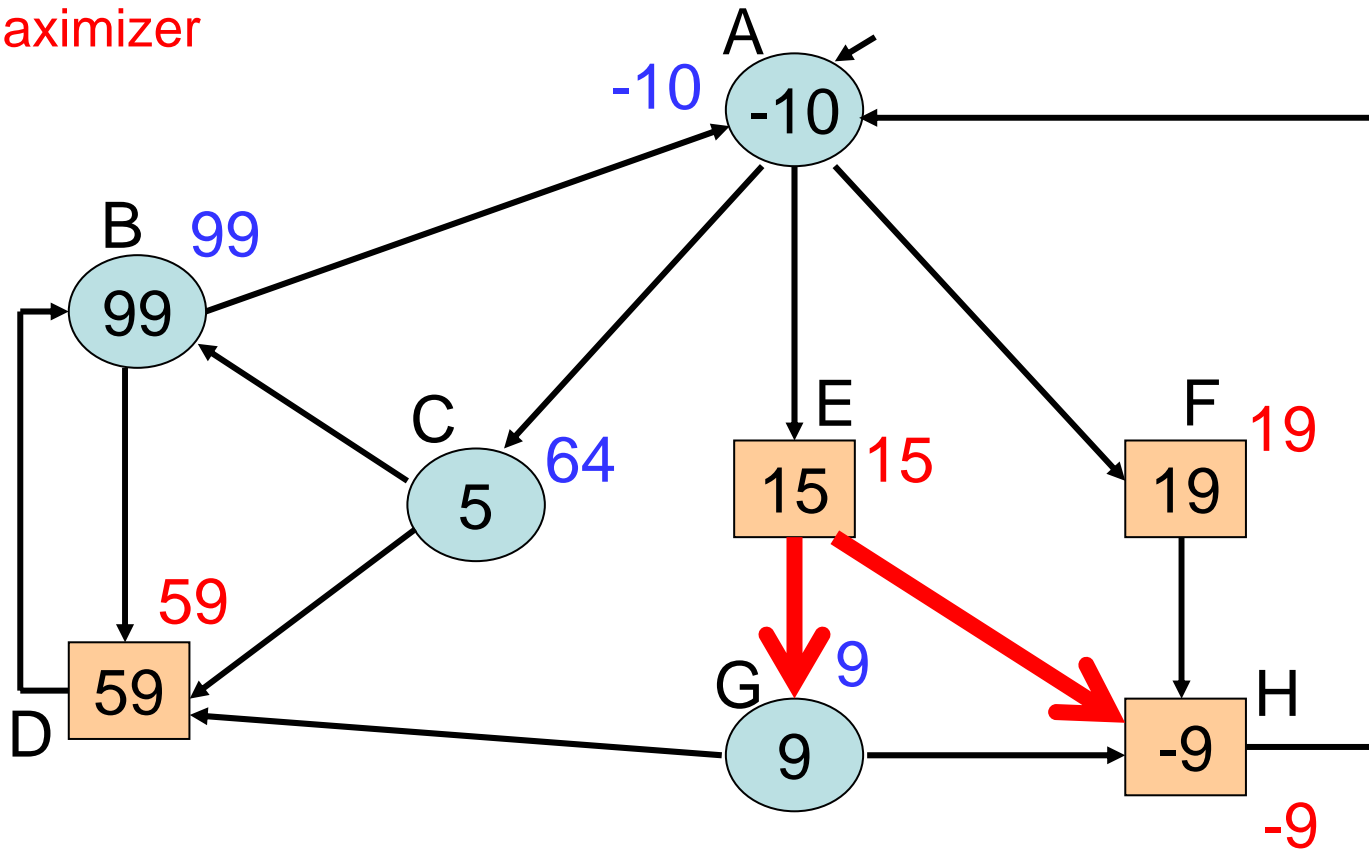
minimizer
maximizer



$$C: 5 + \max(0, \min(59, 99)) = 64$$

Sum Game

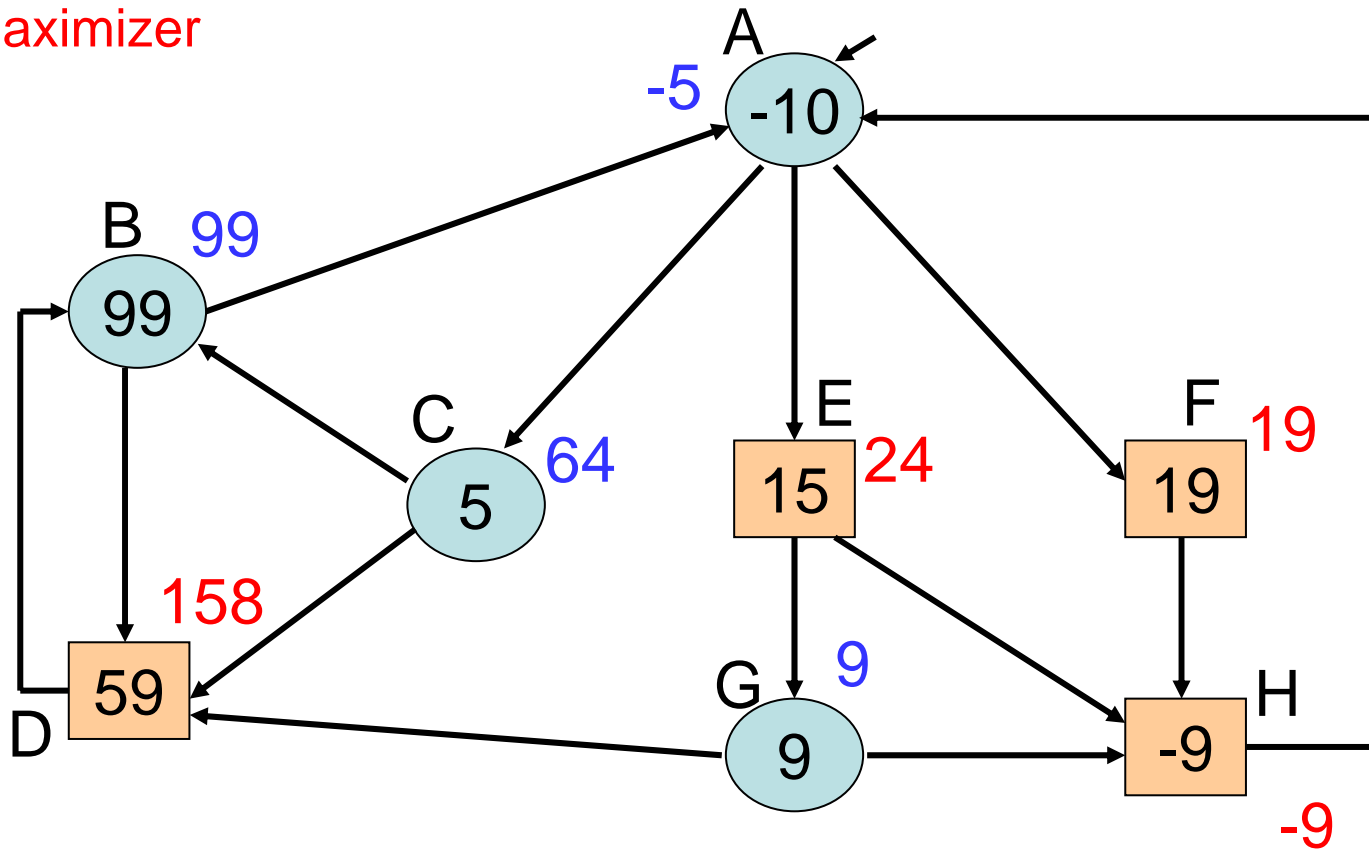
minimizer
maximizer



$$E: 15 + \max(0, \max(9, -9)) = 24$$

Sum Game

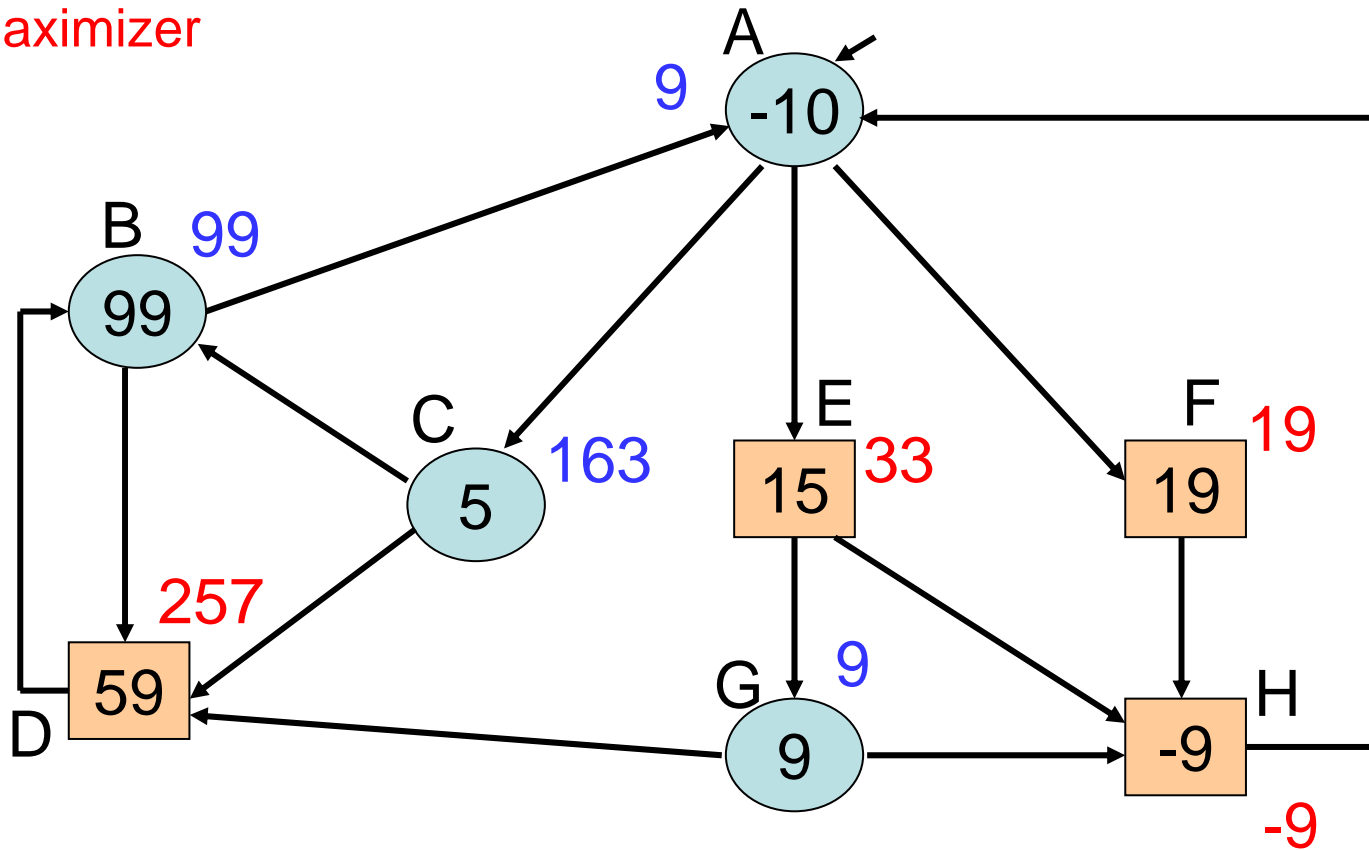
minimizer
maximizer



Iteration 1.

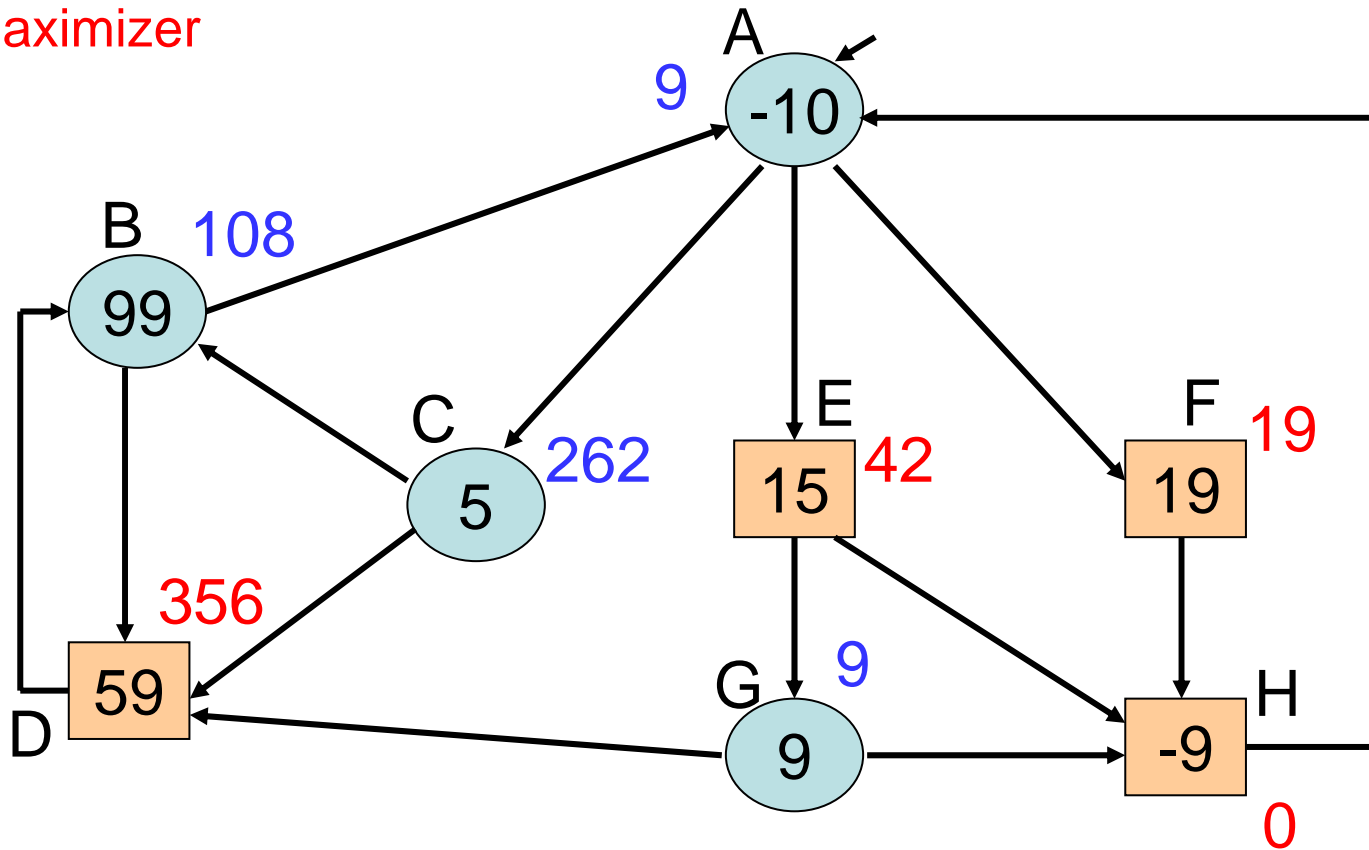
Sum Game

minimizer
maximizer



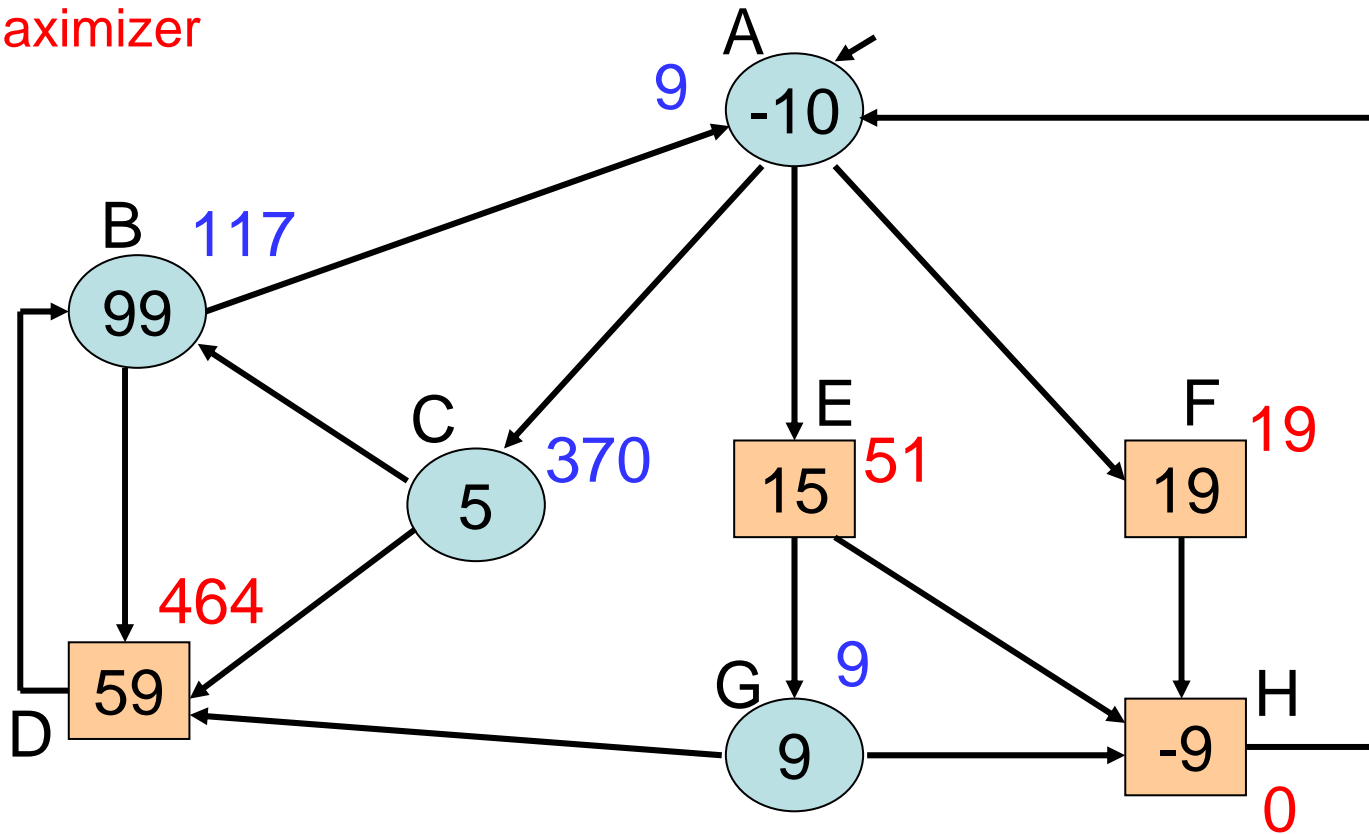
Sum Game

minimizer
maximizer



Sum Game

minimizer
maximizer

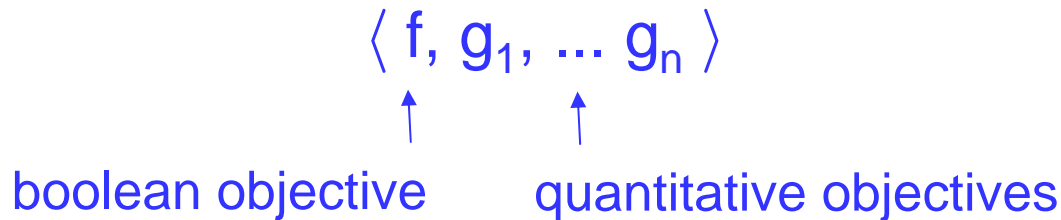


Games for Quantitative Synthesis

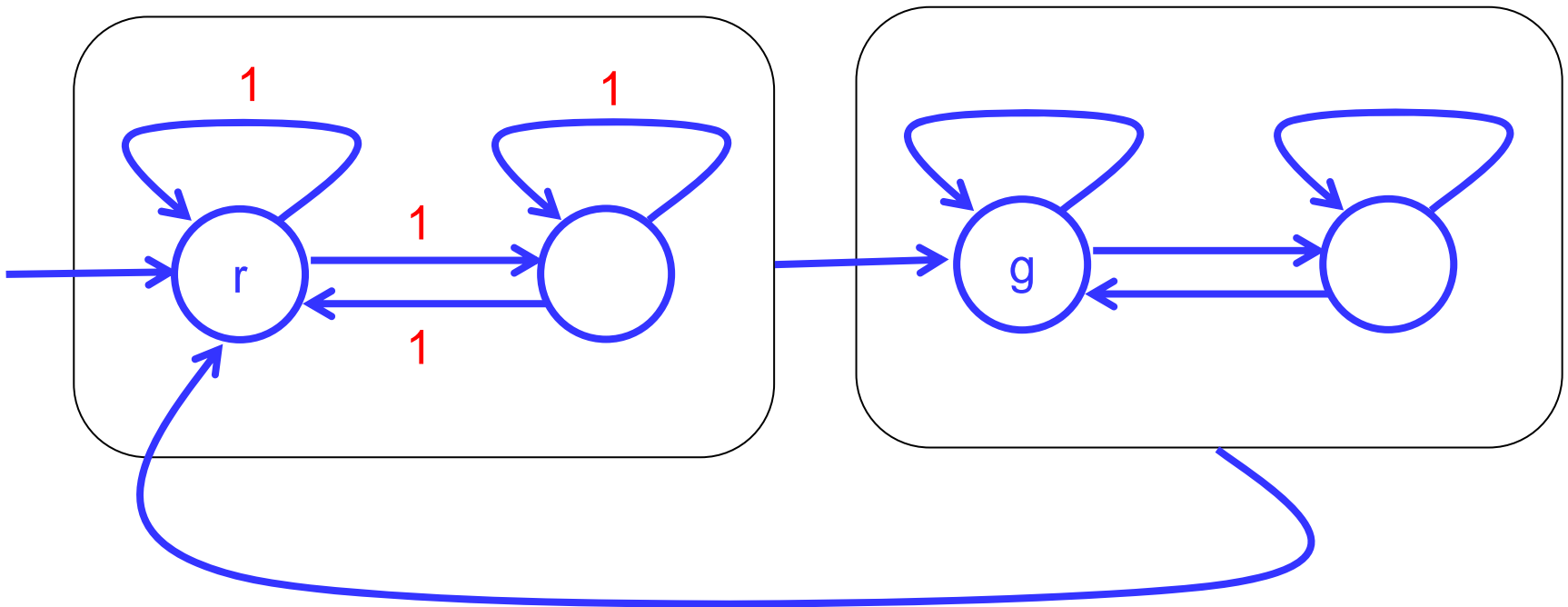
1 Constrained Resources

2 Preference between Different Implementations

- boolean spec, but certain implementations preferred
- formalized using **lexicographic objectives**
[Jobstmann et al.]

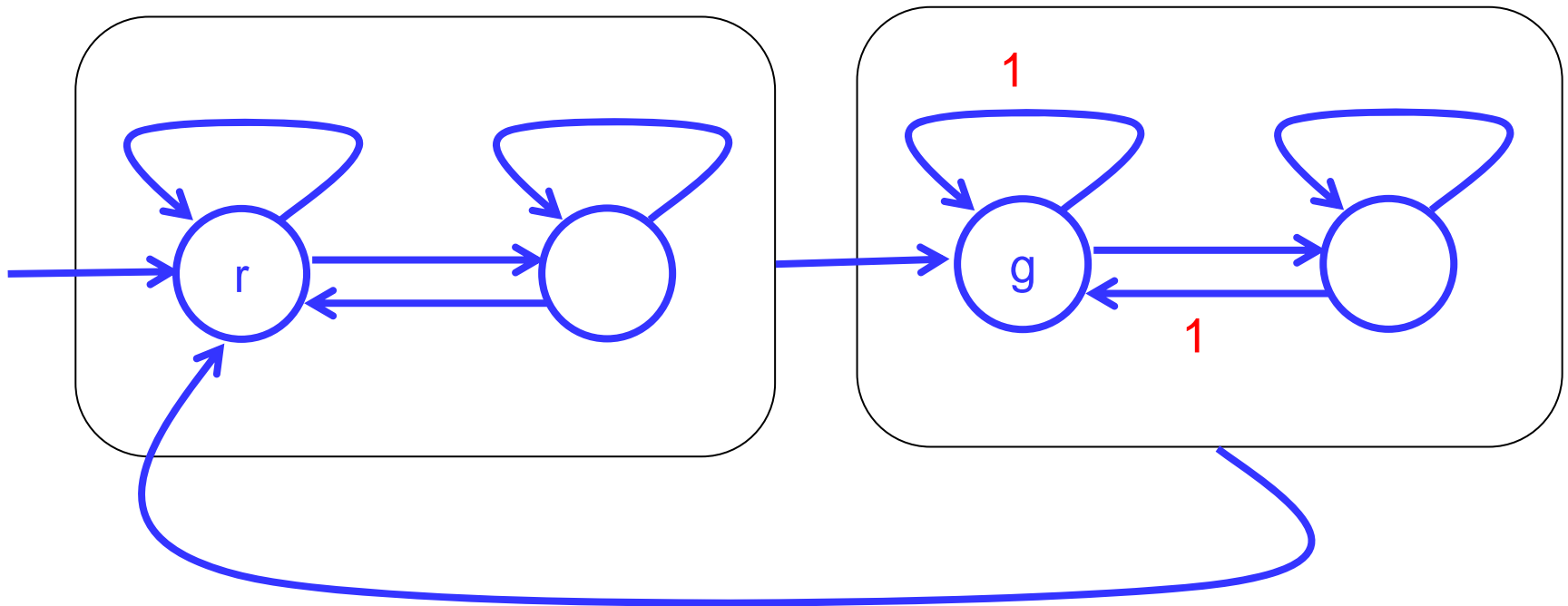


Request-Grant Limavg Automaton 1



Following a request, all steps until the next grant are penalized.

Request-Grant Limavg Automaton 2



Following a request, all repeated grants are penalized.

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Robust Systems

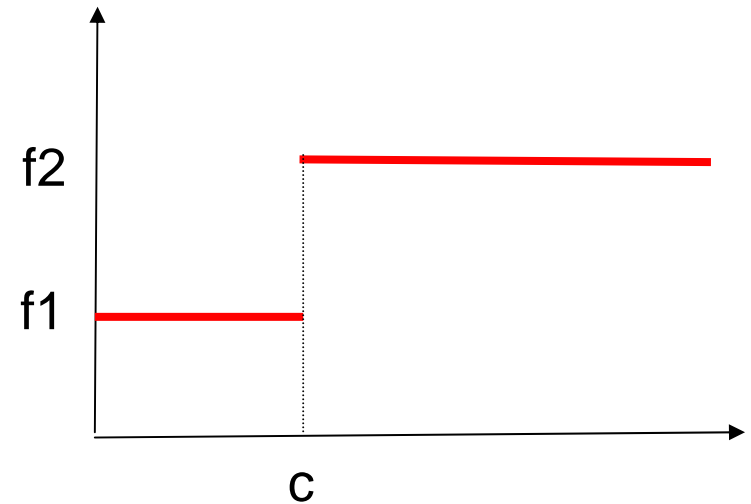
1 Robustness as Mathematical Continuity:

- small input changes should cause small output changes
- only possible in a quantitative framework

$$\forall \varepsilon > 0. \exists \delta > 0. \text{input-change} \leq \delta \Rightarrow \text{output-change} \leq \varepsilon$$

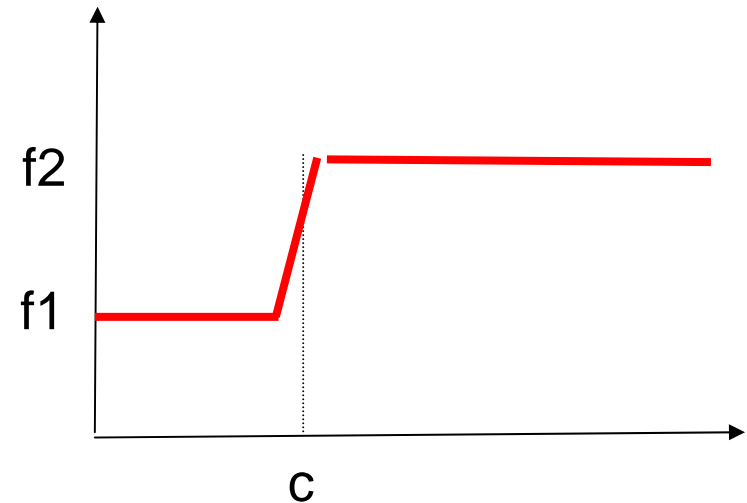
In general programs are not continuous.
But they can be less continuous:

```
read sensor value x;  
if  $x \leq c$  then  $y = f1(x)$   
else  $y = f2(x)$ ;
```



In general programs are not continuous.
But they can be less continuous:

```
read sensor value x;  
if  $x \leq c$  then  $y = f_1(x)$   
  else  $y = f_2(x)$ ;
```



Or more continuous:

```
if  $x \leq c - \epsilon$  then  $y = f_1(x)$ ;  
if  $x \geq c + \epsilon$  then  $y = f_2(x)$   
  else  $y = (f_2(c+\epsilon) - f_1(c-\epsilon))(x - c + \epsilon) / 2\epsilon + f_1(c - \epsilon)$ ;
```

[Majumdar et al., Gulwani et al.]

Robust Systems

1 Robustness as Mathematical Continuity:

- small input changes should cause small output changes
- only possible in a quantitative framework

$$\forall \varepsilon > 0. \exists \delta > 0. \text{input-change} \leq \delta \Rightarrow \text{output-change} \leq \varepsilon$$

Example of a Robustness Theorem [AHM]:

If $\text{discountedBisimilarity}(A, B) > 1 - \varepsilon$,
then $\forall w : |A(w) - B(w)| < f(\varepsilon)$.

Robust Systems

1 Robustness as Mathematical Continuity:

- small input changes should cause small output changes
- only possible in a quantitative framework

2 Robustness w.r.t. Faulty Assumptions:

- environment may violate assumptions
- few environment mistakes should cause few system mistakes
- ratio of system to environment mistakes as quantitative quality measure

[Greimel et al.]

Conclusions

- “Quantitative” is more than “timed” and “probabilistic.”
- Weighted automata offer a natural quantitative specification language.
- We need to move from boolean correctness criteria to quantitative system preference metrics.
- We have interesting point solutions, but no convincing overall framework.