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# Resource Contracts for deploying multiple applications on MPSoC systems

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# Why do we need resource contracts?

- Unbounded set of multiple application = unexplorable dynamism
- Different types of application
  - Data dominated, control, hard, soft.
- Different mapping methodologies
  - Design space exploration: memory aware, scenario aware
  - pure design/run-time.
- Resource contracts



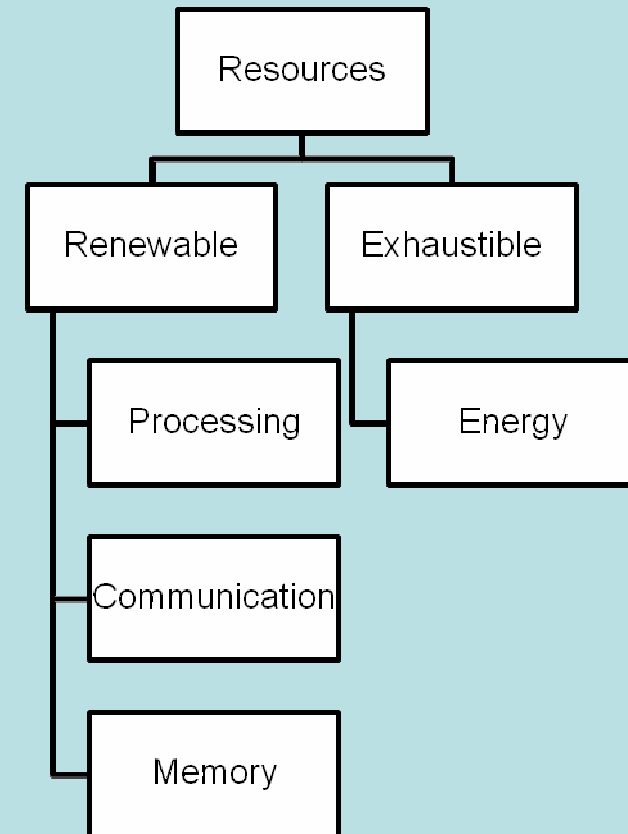
# Context: MP-SoC

## Objective:

Minimize resource usage for exhaustible resources

## Constraints:

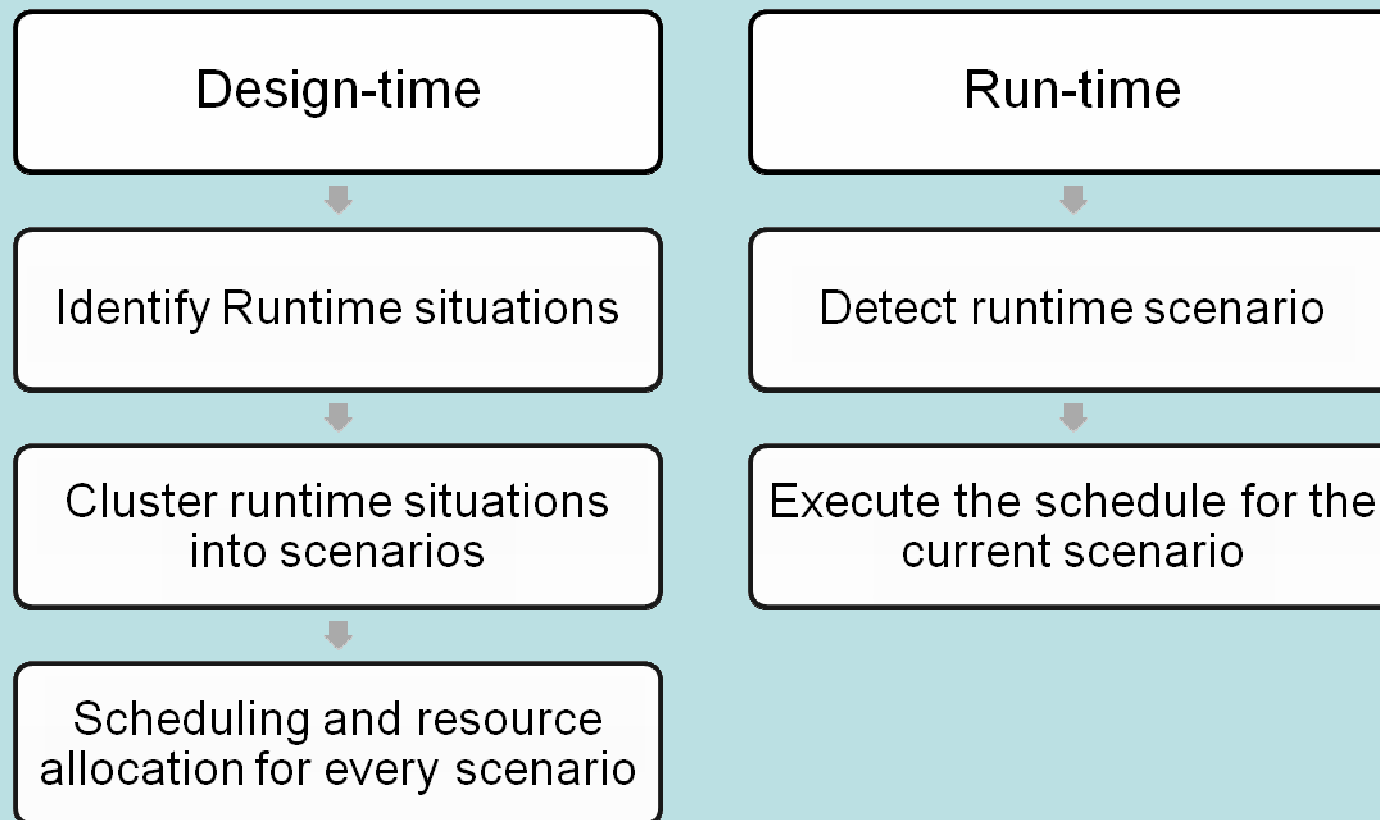
1. Renewable resources
2. QoS requirements





# System-scenario-based design

## Explorable Dynamism





# Application 1

Execution time / us	Energy / uJ
345431	129562
297921	137909
232187	153552
177263	270560

**Table: 1 mapping tradeoffs for 3D application in a frame with 22 objects being rendered**

Execution time / us	Energy / uJ
274528	73905
149104	115509
56714	304492
15420	377924

**Table: 2 mapping tradeoffs for 3D application in a frame with 13 objects being rendered**



# Application 2

Execution time/ us	Energy / uJ
17954	4307
9295	5812
7260	13604
1921	47778

Table 3: Mapping tradeoffs for static application



# QML for resource contracts

```
type Energy = contract {  
  energy: decreasing numeric uJ;  
};  
3D_Application_Contract = Energy contract ( Max_Energy: function; Scenario: int;  
  Available_Processor_Time: int; )  
{  
  Maximum = Max_Energy(Scenario, Available_Processor_Time);  
};
```

The function of `Max_Energy` is derived from Table 1 and Table 2.

```
Static_app_Contract = Energy contract ( Max_Energy: function;  
  Available_Processor_Time: int; )  
{  
  Maximum = Max_Energy(Available_Processor_Time);  
};
```

Where the `Max_Energy` function comes from table 3.



# Conclusion

- Mapping techniques should have a way to communicate with each other or standardized contracts
- This can't be done unless there is interest from the community
- Requirements analysis