

# 1<sup>st</sup> International workshop on Model Based Engineering for Robotics RoSyM.

Oslo, Norway, 5 October 2010

<http://www.artist-embedded.org/artist/RoSym-2010>

## Important Dates

**Submission deadline:** 26 July, 2010  
Notification acceptance: 25 August, 2010  
Final version papers: 15 September, 2010  
RoSyM Workshop: 4-5 October, 2010

## Organisers Committee

Laurent Rioux *THALES, France*  
Davide Brugali *Univ of Bergamo, Italy*  
Sebastien Gérard *CEA-LIST, France*

## Program Committee

Xavier Blanc *LIP6, France*  
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J.F Broenink *Univ of Twente, Netherland.*  
Paul Valckenaers *Univ of Leuven, Belgium*  
Toby McClean *ZeligSoft, Canada*

## Submission Guidelines

Authors have to apply by sending a paper/abstract (4-10 pages) in PDF or PS. The paper must conform to the Springer LNCS formatting guidelines: <http://www.springer.com/computer/lncs> (the same format of the Conference, see conference website for more information).

Authors of accepted papers shall prepare and submit a final version of their paper. The deadline for these final versions is 15 Sept 2010. Each accepted paper will be electronically published in the Workshop website and

## Goals

The aim of the workshop is to bring together researchers, industrials and tool developers to discuss on the usage of model-based engineering to robotics application in different domains as well as major issues to use this technology. A significant portion of time will be reserved for discussions.

## Topics

The concrete topics of the workshop are:

- Model-based design of robotics and autonomous systems, including dedicated modelling language for robotics (which may be extensions of existing languages as well)
- Safety, dependability and certification of robotics systems,
- Test, validation and simulation of the autonomous behaviour of the robot,
- Model-based quantitative analysis techniques, including performance optimisation techniques for robotics
- Model-based processes and methods for robotics, including the investigation and classification of activities adjusted to robotics
- Exploration and assessment of how existing MBE solutions have been used or experimented in robotics
- Evaluation techniques and metrics for assessing effectiveness of MBE robotics system prototype.
- Examples of "early adopters" of MDE for robotics
- Unique challenges in robotics that MDE might help overcome
- MDE concepts and techniques that are